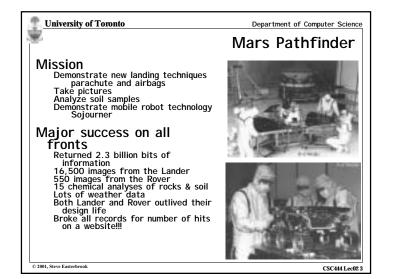
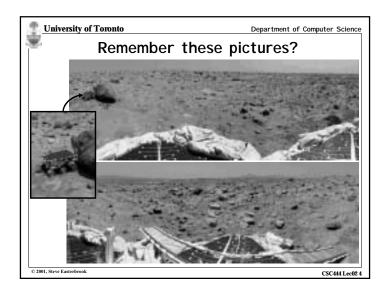
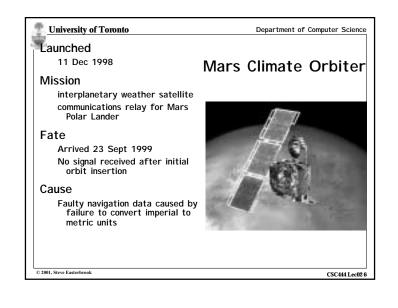
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Lecture 2:			
Examples of Poor Engineering			
"Software Forensics" Case	e Studies		
Mars Pathfinder			
Mars Climate Observer			
Mars Polar Lander			
Deep Space 2			
Some conclusions			
Reliable software has very little to	do with writing good programs		
Humans make mistakes, but good en	gineering practice catches them!		
	· ·		
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University of Toronto Department of Computer Sc NASA JPL's Mars Program			
Mission	Launch Date	Arrival Date	Outcome
Viking I Viking II	20 Aug 1975 9 Sept 1975	Landed 20 Jul 1976 Landed 3 Sept 1976	Operated until 1982 Operated until 1980
Mars Observer	25 Sept 1992	Last contact: 22 Aug 1993	Contact lost just before orbit insertion
Pathfinder	4 Dec 1996	Landed 4 July 1997	Operated until 27 Sep 1997
Global Surveyor	7 Nov 1996	Orbit attained 12 Sept 1997	Still operational
Climate Orbiter	11 Dec 1998	Last contact: 23 Sept 1999	Contact lost just before orbit insertion
Polar Lander	3 Jan 1999	Last contact: 3 Dec 1999	Contact lost before descent
Deep Space 2	3 Jan 1999	Last contact: 3 Jan 1999	No data was ever retrieved
Mars Odyssey	7 Apr 2001	Arrived in orbit: Oct 23 2001	Still operating

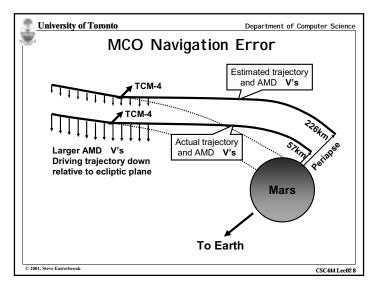


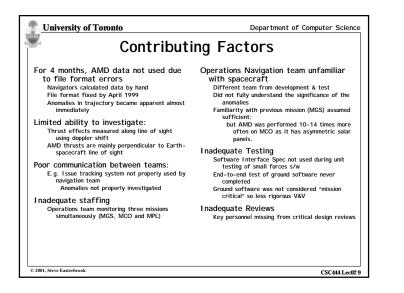


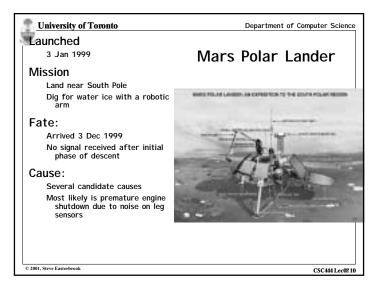
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Pathfinder had Sof	tware Errors
Symptoms: software did total systems resents a Symptoms noticed soon after Pathfinder started co	
Cause	
3 Process threads, with bus access via mutual exclu	usion locks (mutexs):
High priority: Information Bus Manager	
Medium priority: Communications Task	
Low priority: Meteorological Data Gathering	Task
Priority Inversion:	
Low priority task gets mutex to transfer data t	
High priority task blocked until mutex is release	
Medium priority task pre-empts low priority task	
Eventually a watchdog timer notices Bus Manage	r hasn't run for some time
Factors	
Very hard to diagnose and hard to reproduce	
Need full tracing switched on to analyze what h	
Was experienced a couple of times in pre-flight te	
Never reproduced or explained, hence testers a	ssumed it was a hardware glitch
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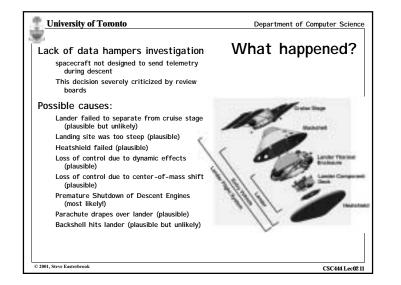


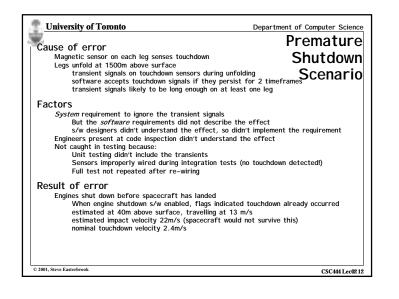
Locus of error	Small Forces
Ground software file called "Small For	ces" gives thruster performance data
This data used to process telemetry f	rom the spacecraft
	Momentum Desaturation (AMD) maneuver
Small Forces data used to compu	
Software underestimated effect	by factor of 4.45
Cause of error	
Small Forces Data given in Pounds-sec	onds (lbf-s)
The specification called for Newton-se	econds (N-s)
Result of error	
As spacecraft approaches orbit insert	on, trajectory is corrected
Aimed for periapse of 226km on	first orbit
Estimates were adjusted as the space	
1 week prior: first periapse estir	
1 hour prior: this was down to 1 Minimum periapse considered surv	
MCO entered Mars occultation 49 sec	
	the predicted 21 minute occultation
Subsequent analysis estimates fir	
. ,	

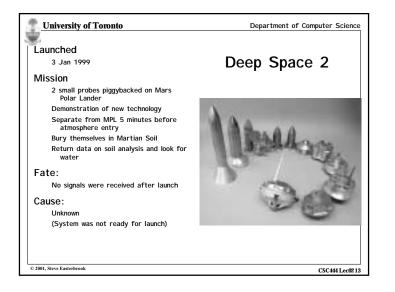


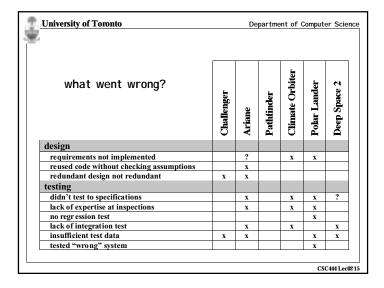


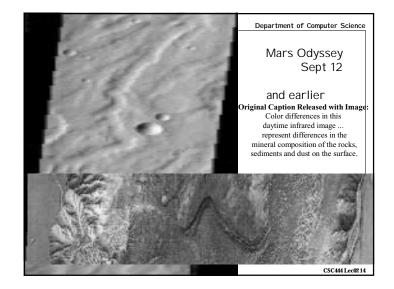












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2.	Challenger	Ariane	Pathfinder	Climate Orbiter	Polar Lander	Deep Space 2
problem tracking						
didn't investigate anomalies	x		x	x		
didn't use problem reporting system	x		x	x	x	?
didn't track problems properly	x	x	x	x	x	?
operation						
software used before ready				?	?	x
system changed after testing					x	?
lack of diagnostic data during operation			x	x	x	x
different team maintains software				x	x	
management						
poor communication between teams	x	x	x	x	x	?
inexperienced managers	?			x	x	х
failure to adjust budget and schedule	x			X	x	x
insufficient staffing	x			x	x	x
commercial pressure took priorities	X	x		x	x	X
						csc

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Summary				
Failures can usually be traced to a single root cause But good engineering practice should prevent these causing system failure The real problems are failures of: testing and inspection process problem reporting and tracking lack of expertise inadequate resources, etc In most cases, it takes a failure of both engineering practice and of				
Reliable software depends not on flawless programs but on how good we are at: Communication (sharing information between teams) Management (of Resources and Risk) Verification and Validation Risk I dentification and tracking Questioning assumptions				
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