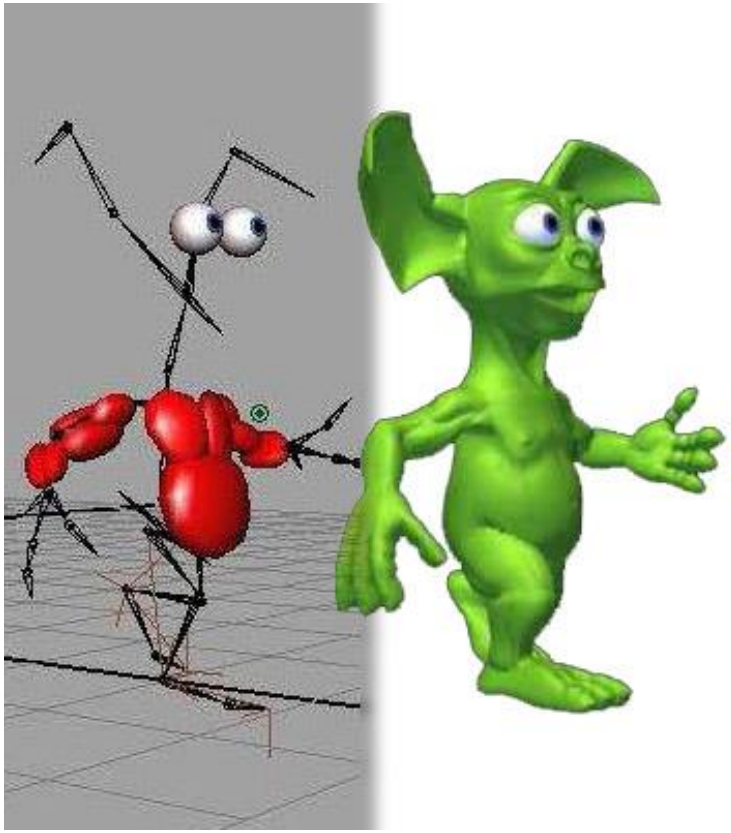
# 199: Anatomy and psychorealism



Karan Singh

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University of Toronto
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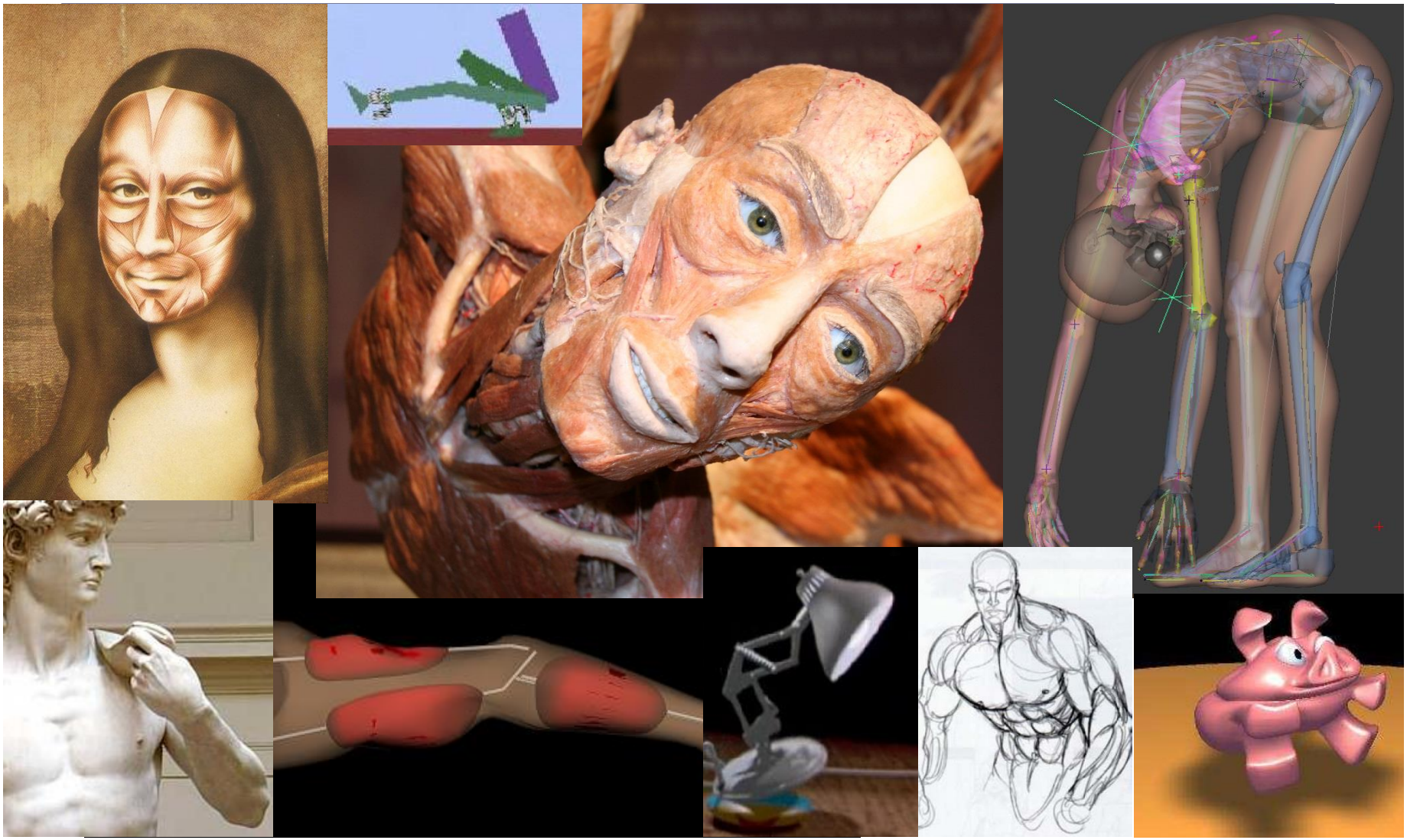
# Anatomy



# Overview

- Understanding anatomy.
- Hand modeling and simulation: a case study.
- Anatomic considerations in *Ryan*.

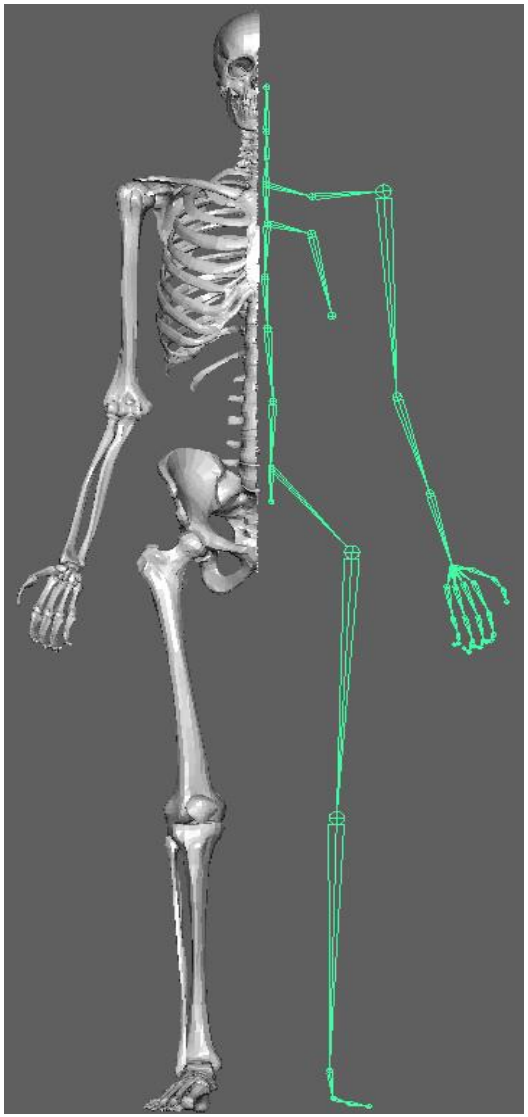
# Understanding Anatomy

Image Credit: Bodyworlds

# Layered Approach

- Skeletal.
- Muscle.
- Skin and underlying tissue.
- Hair, nails, blemishes.
- Clothes and accessories.

# Human Skeleton



- Human bones =206, CG approx. 40.
- Human bones flexible, 6 DOF joints.
- CG bones rigid, 3DOF Kinematics.
- Human bones have connective tissue called ligaments.
- Muscle attached to bone by tendons.

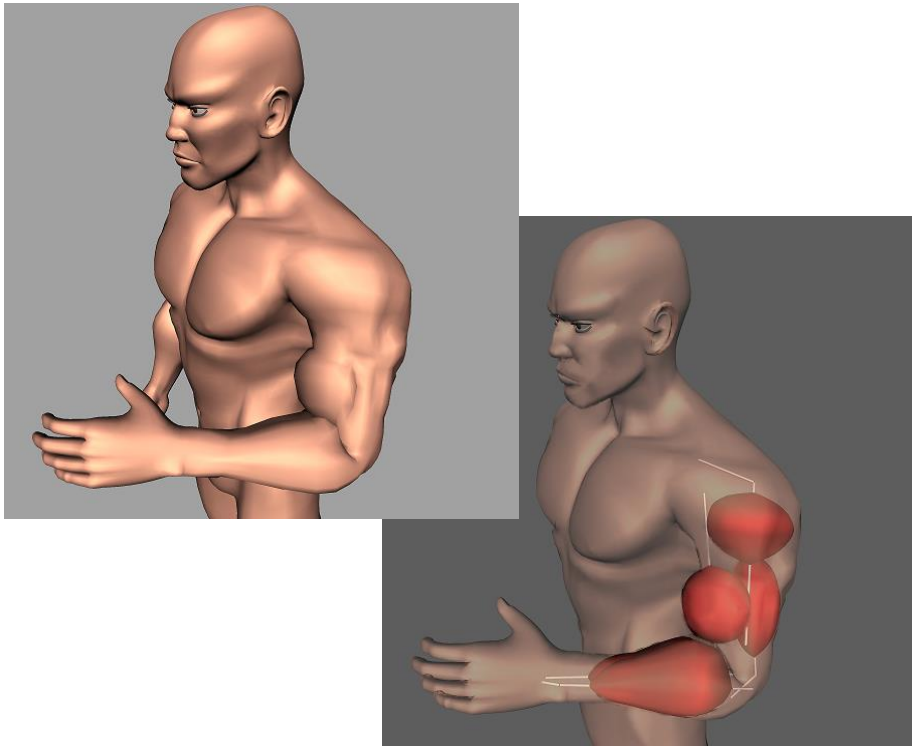
# Skeletal control interfaces

- More DOF = more control (both GOOD & BAD).
- Interfaces that capture the domain of specialized motion makes working with experts easier.
- Complex motion with environmental interaction is best left to physics and motion capture.
- Even simple abstractions of the human form are rooted in understanding the underlying anatomy.
- An anatomic model could establish a ground truth for realistic character animation.

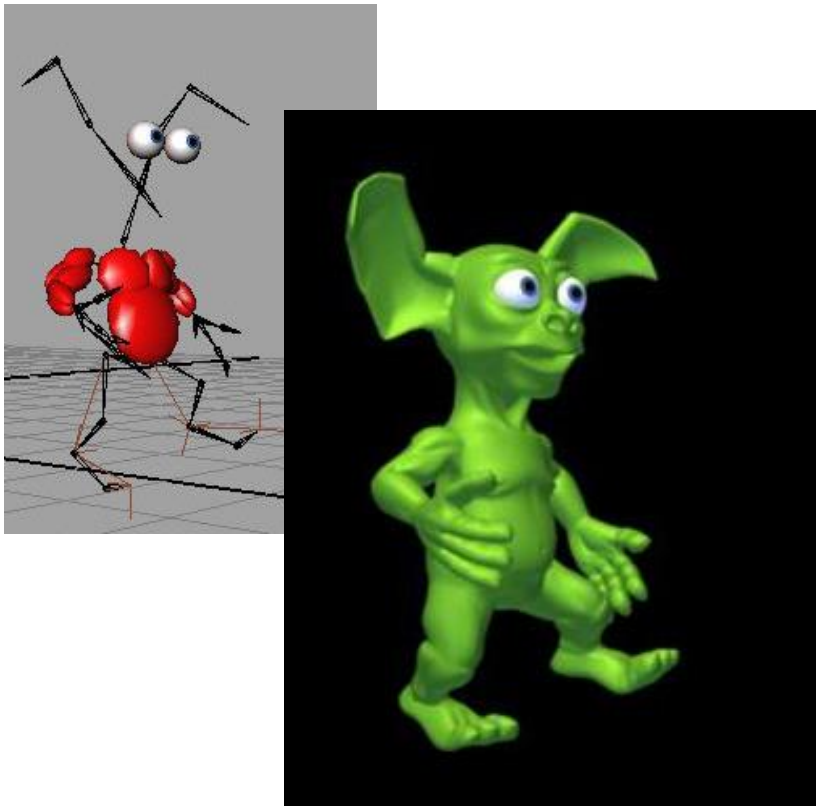
# Skeletal models

- Robot-like
  - **Human bones = 206, CG approx. 40**
  - **Human bones flexible, 6 DOF joints. CG bones rigid, 3DOF**
- Skeletal control
  - **Kinematic**
  - **Dynamic**
  - **Procedural**
  - **Motion Capture**

# Believable anatomy (muscles)

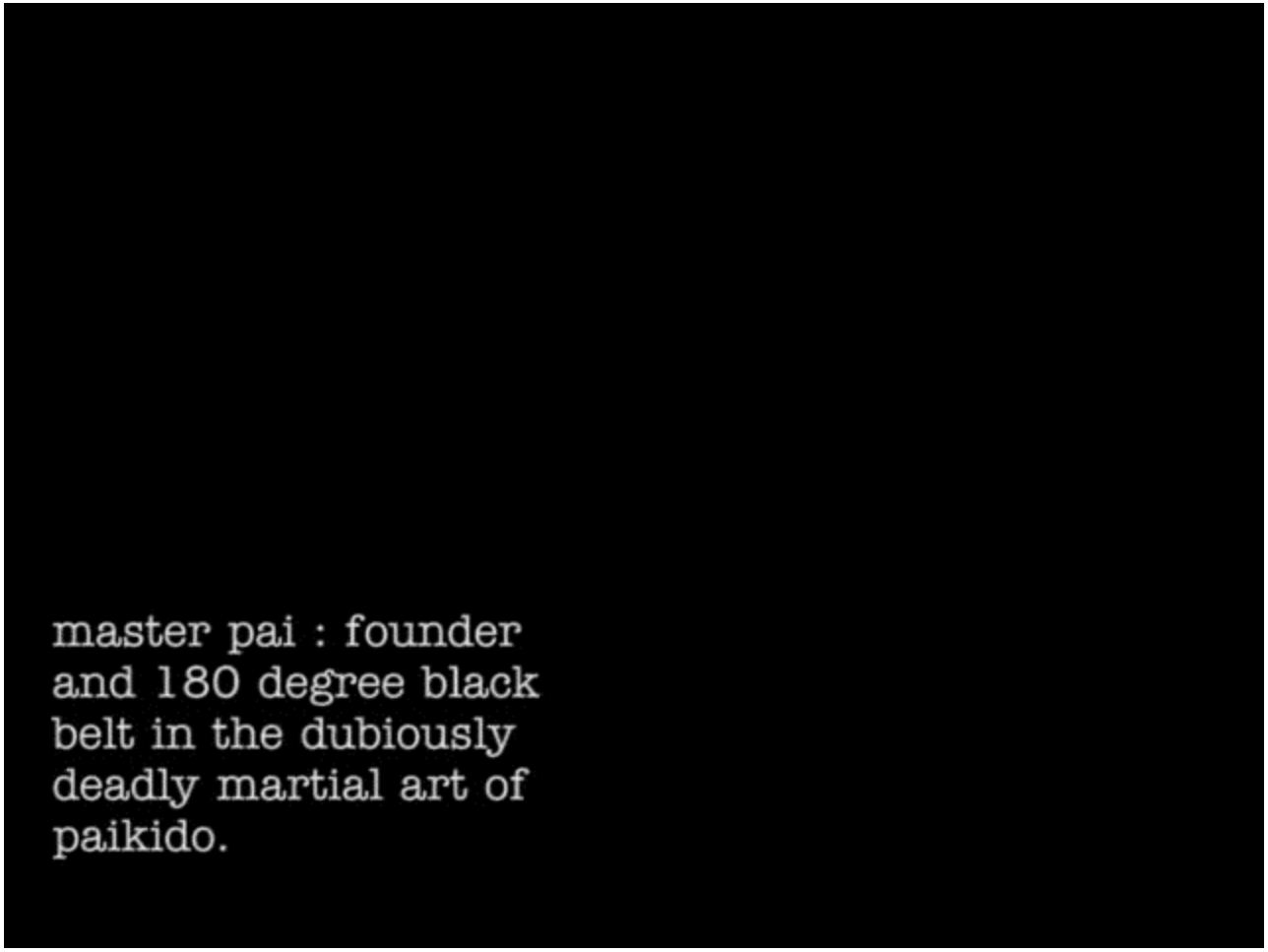


Fit muscles



Deform muscles and tissue

# Believable anatomy (muscles)



# Acquisition and exploration

# The Human Hand

Inside-out or Outside-in?

Helping hand

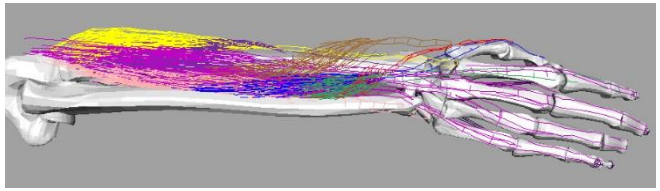
Handrix

ASL Project

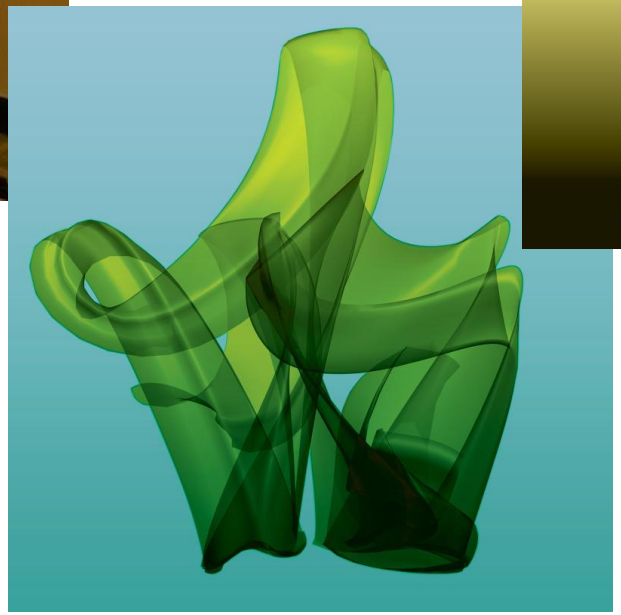
Musculoskeletal data acquisition

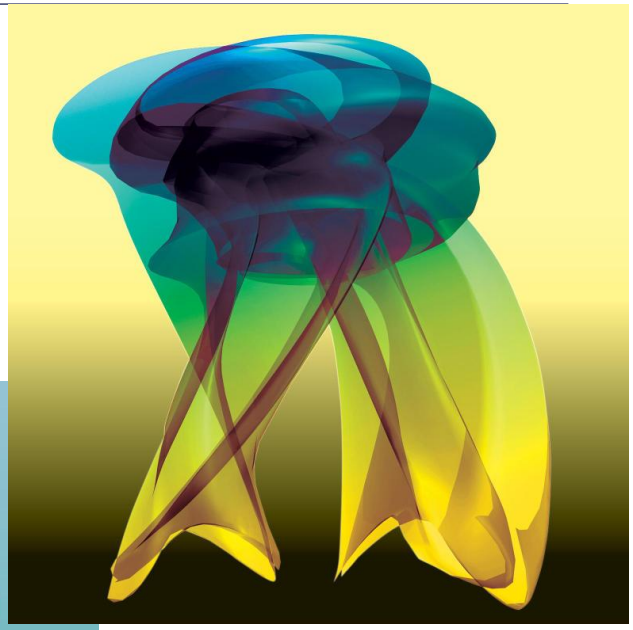
Exploration, Simulation, Synthesis, Visualization

External shape & Motion data acquisition



# The Deaf Cultural Center ASL Project





Unite

Diverse

# Handrix (Inspiration)


# Helping Hand

How do forearm and hand muscles produce hand motion?

**Problem**

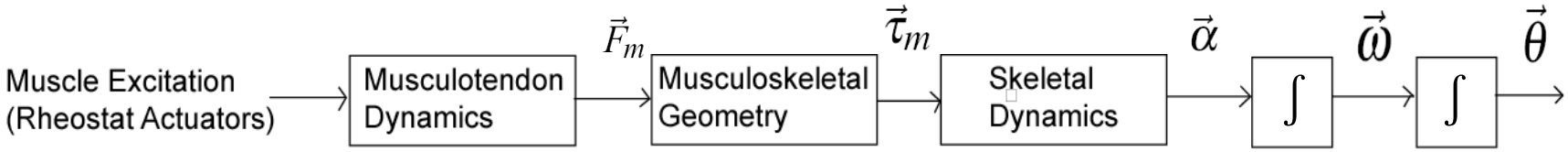
- Neurologic control maps 29 bones, 16 joints and 41 musculo-tendon units to 23 degrees of freedom.

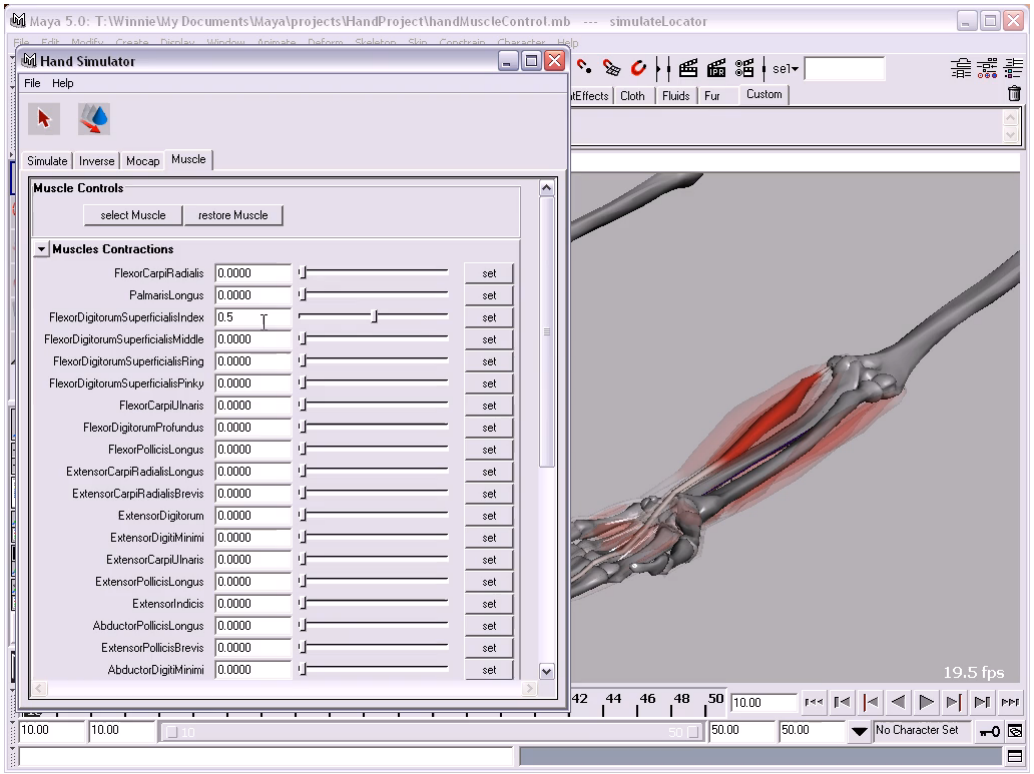
**Our Goal**

Construct a modular system for the exploration, simulation, synthesis and visualization and understanding of hand function.

# Forward Simulation

- Compute body motion given muscle *excitations.*




FDS index set with excitation of 0.5.

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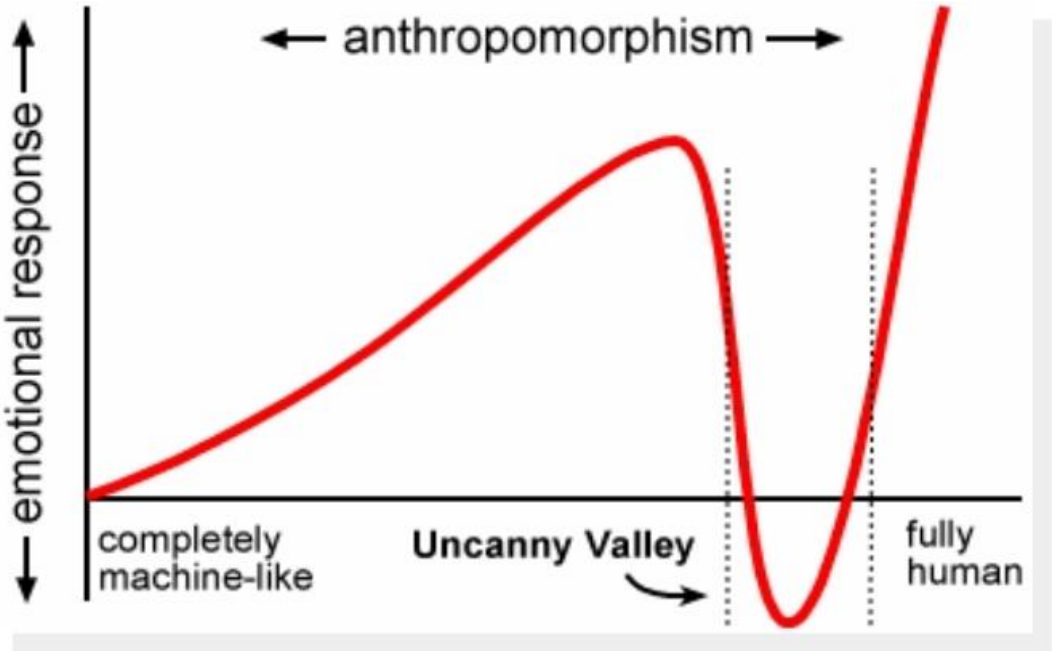
# Anatomic considerations in animation

- **Squash and Stretch.**
- Anticipation.
- **Follow Through and Overlapping Action.**
- **Slow in and Out.**
- Exaggeration.
- **Secondary Action.**
- Appeal.
- Timing and Motion.
- Staging.
- **Straight Ahead Action and Pose-to-Pose Action.**
- **Arcs.**

# Anatomic considerations in *Ryan*

# Animating anatomy (Believability vs. Reality)

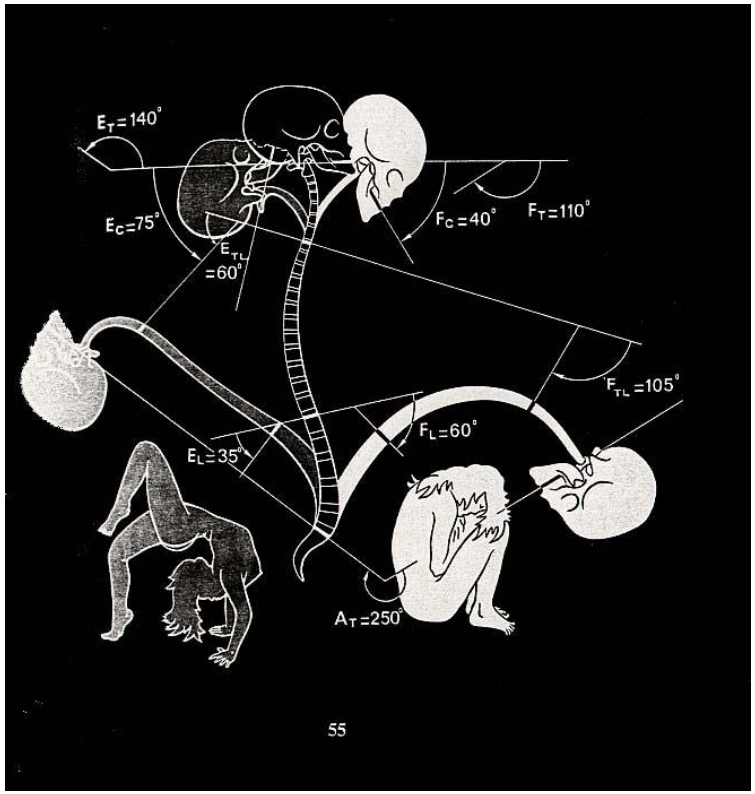


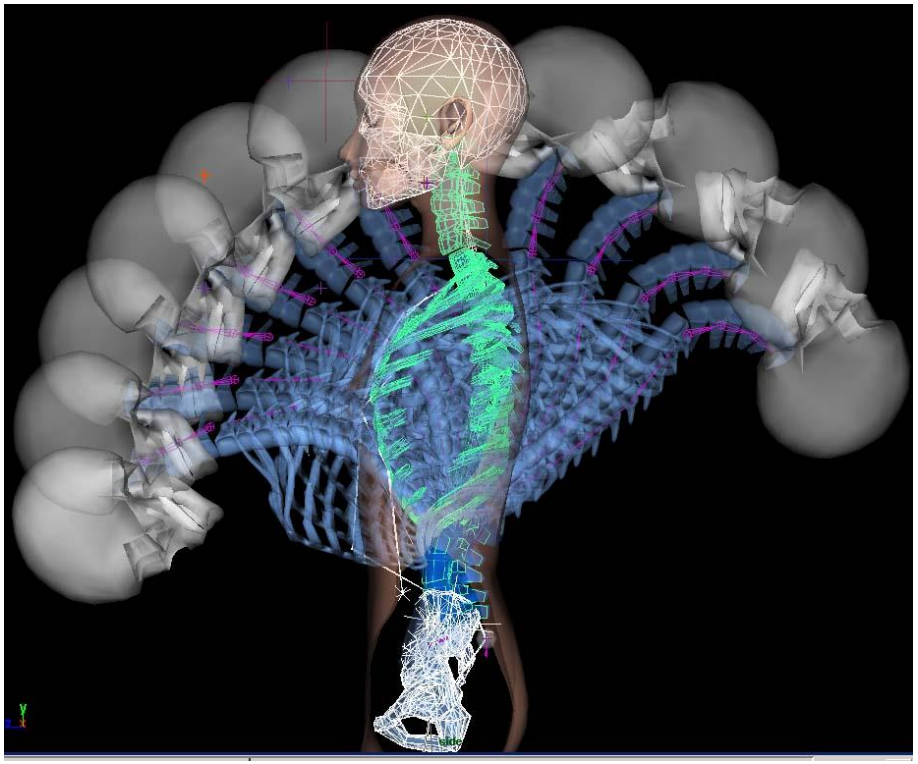

Masahiro Mori 1970

# Believable anatomy (skeletal control)


Image Credits: Michael Paulus

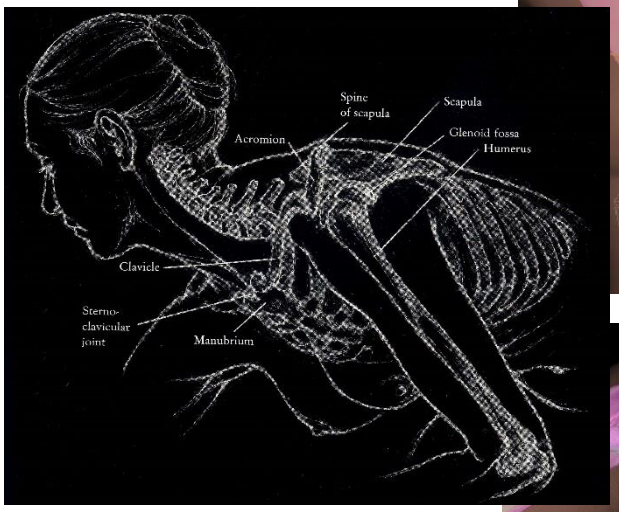
# Believable anatomy (spine and shoulder control)

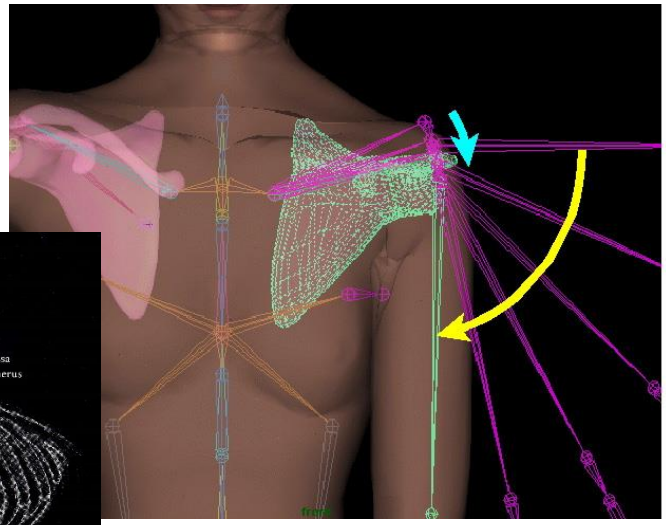


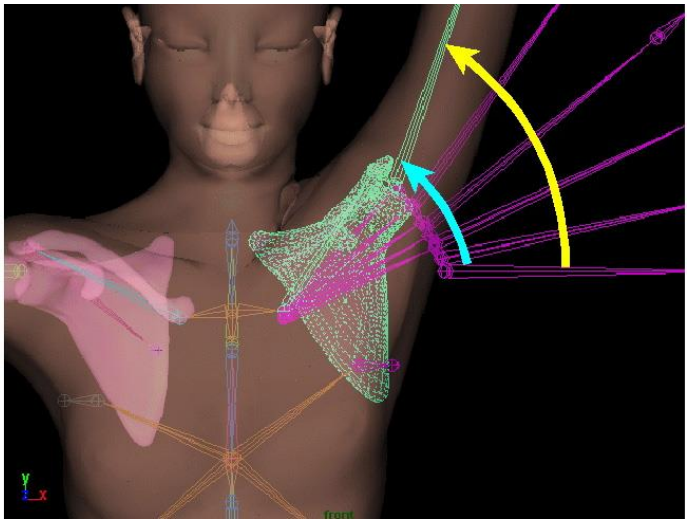



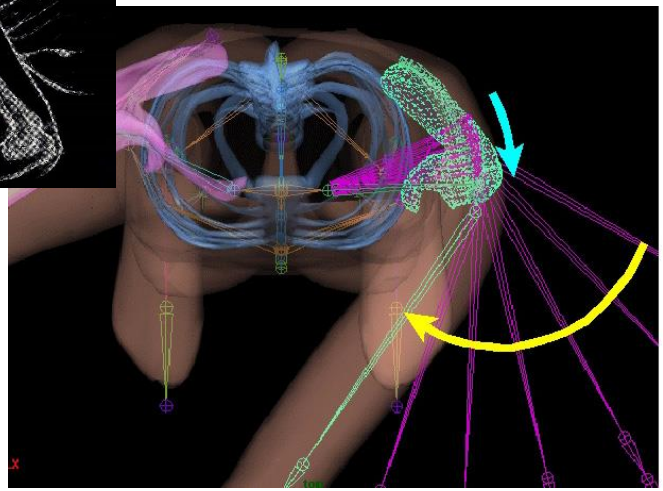
Flex

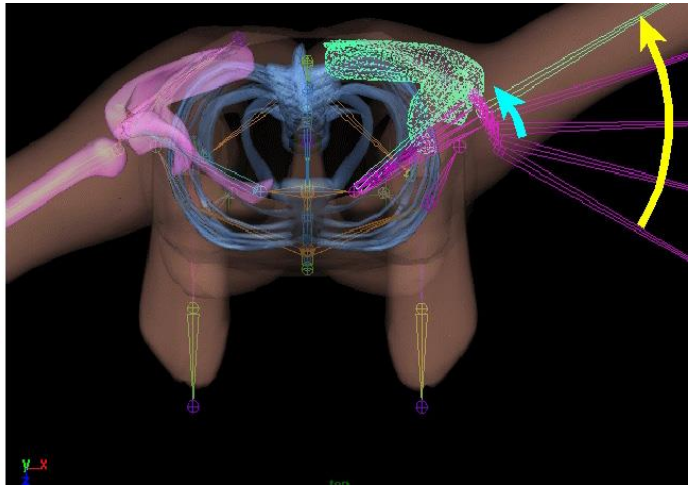
# Believable anatomy (spine and shoulder control)









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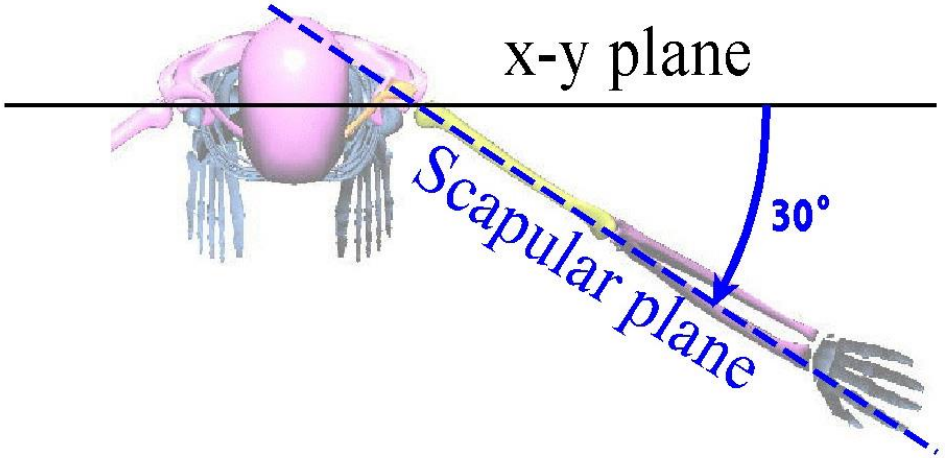
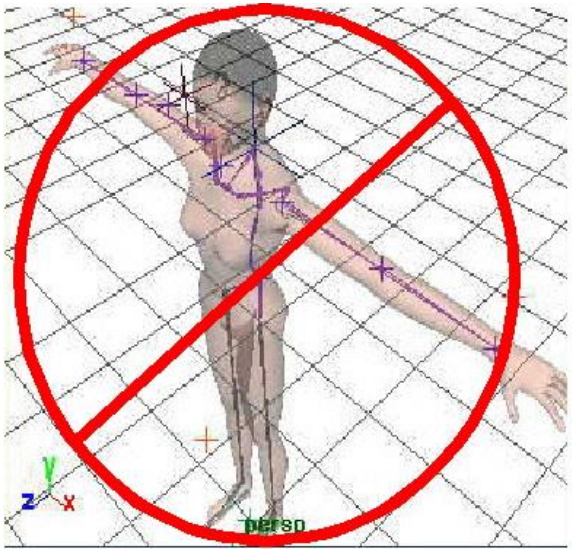
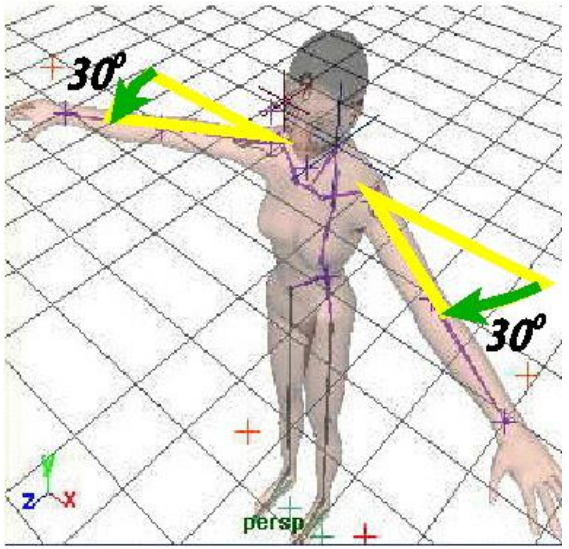
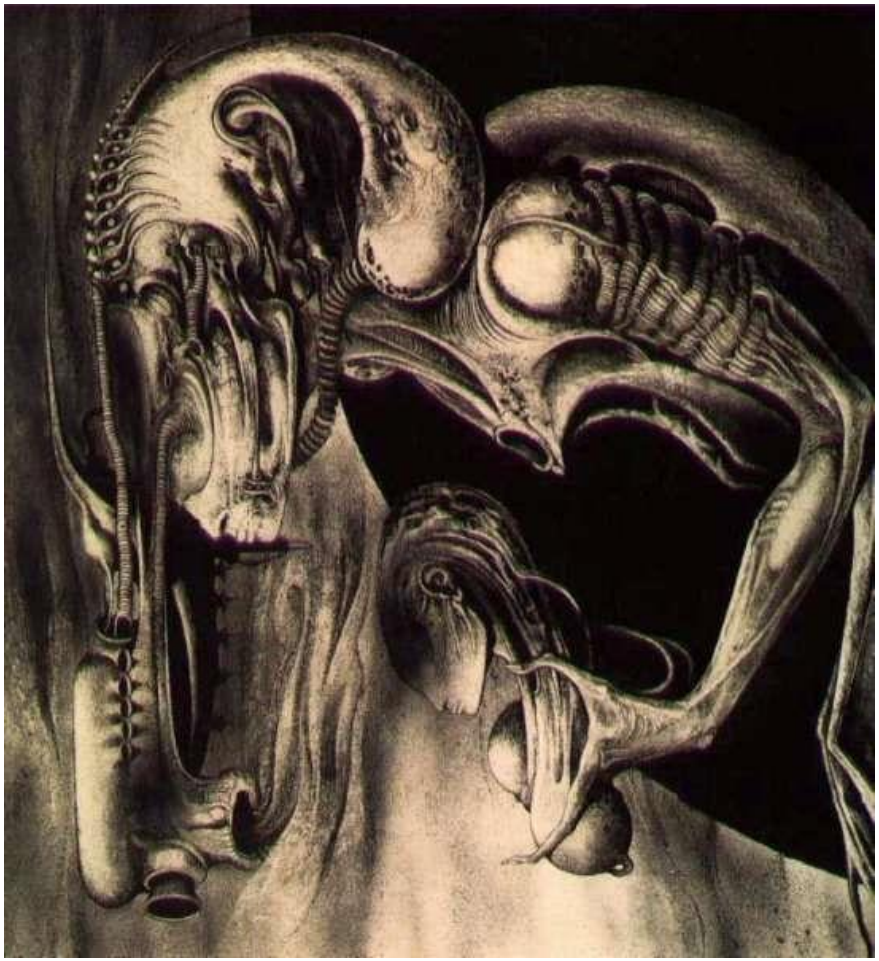


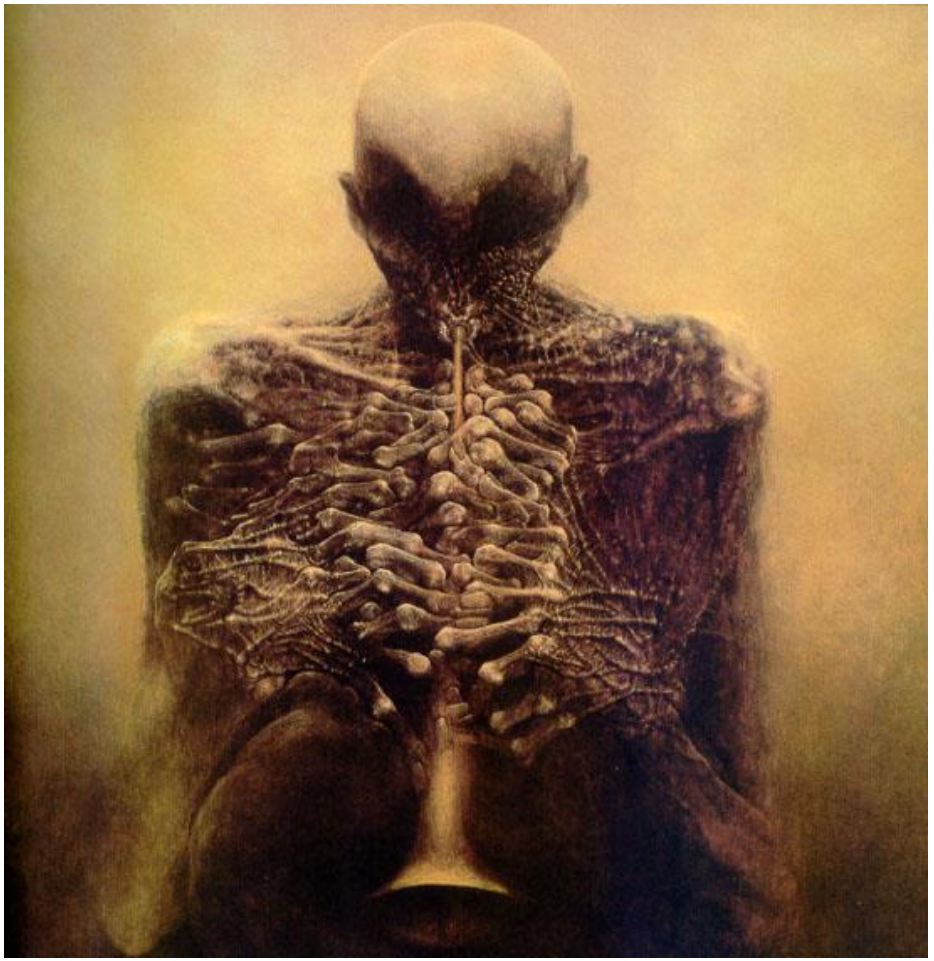



# Alternative anatomies

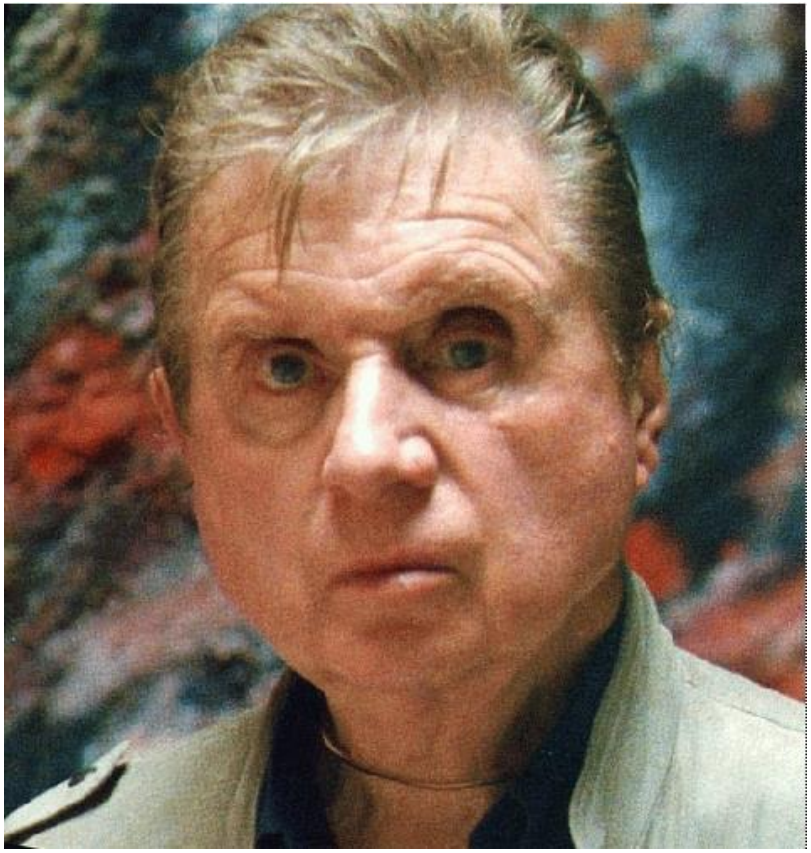


Giger



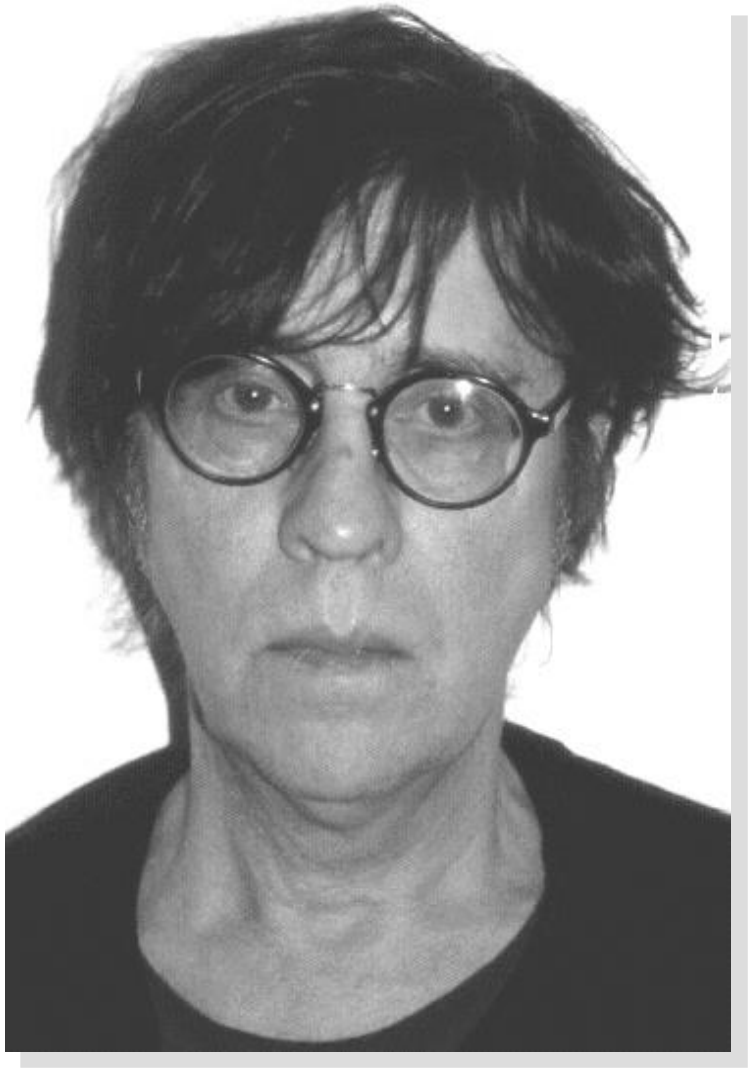
Beksinski

# Alternative anatomies



Bacon

# Alternative anatomies (Ryan)



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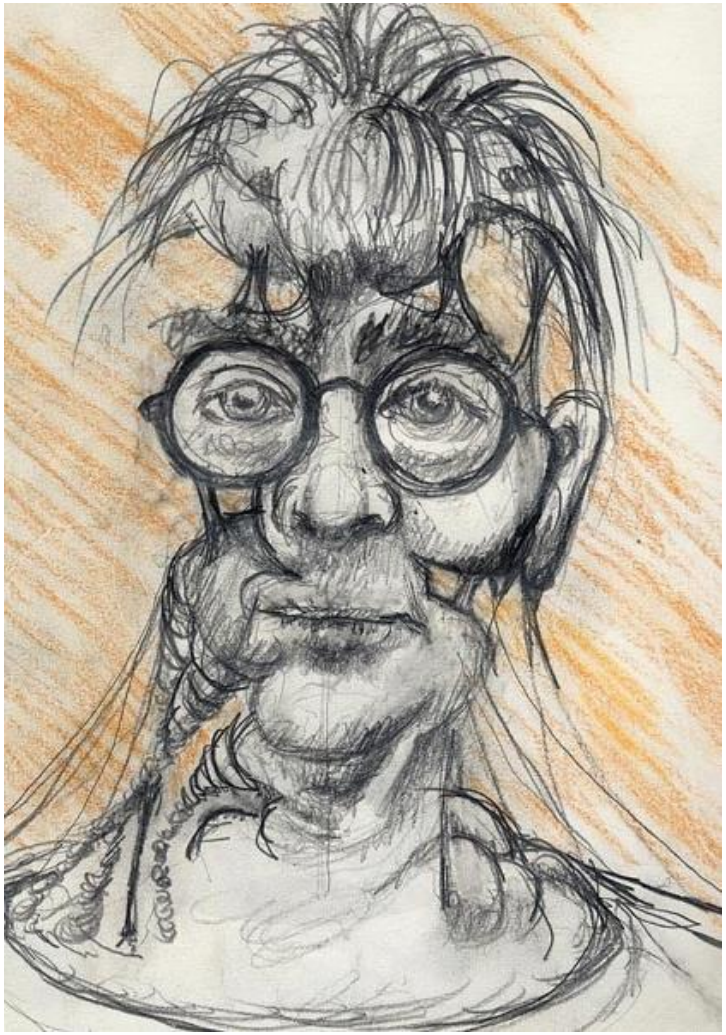

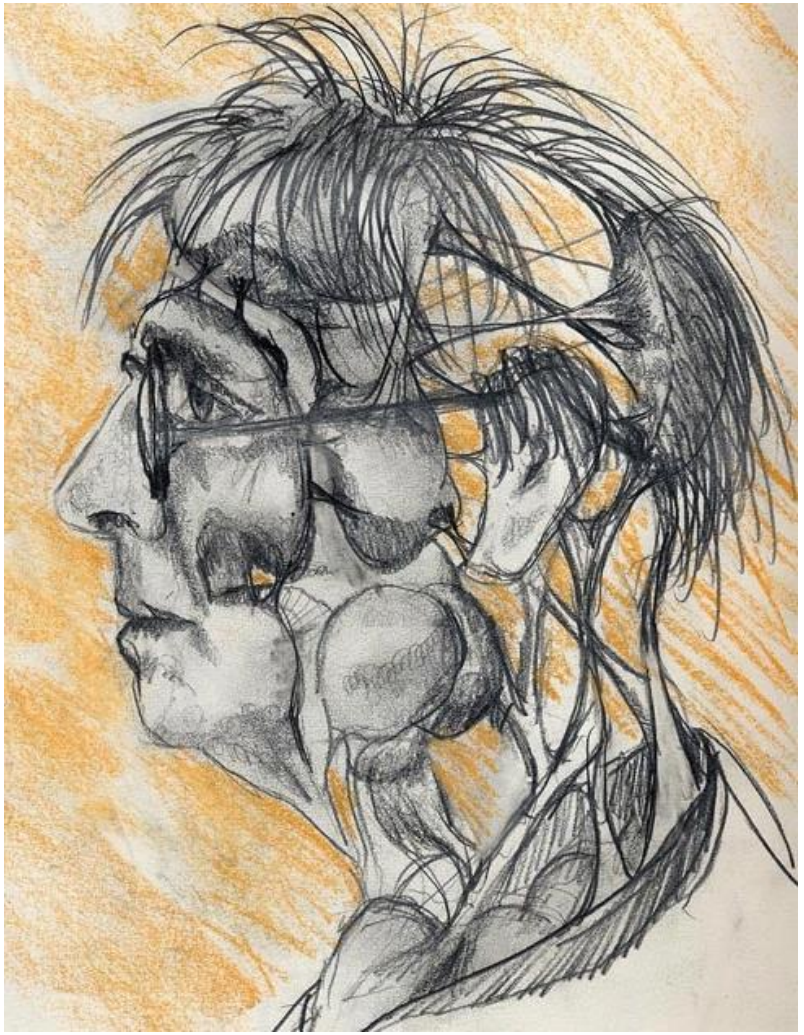

# Summary

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- Anatomic considerations in *Ryan*.

**MESSAGE:**

**ANATOMY IS IMPORTANT FOR ANIMATION**

# Acknowledgements

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