

A note on the prior of GPDM latent variables

Jack M. Wang
Stanford University

The distribution over latent variables is obtained by marginalizing over the weights \mathbf{A} :

$$\begin{aligned} p(\mathbf{X} | \bar{\alpha}) &= p(\mathbf{x}_1) p(\mathbf{X}_{2:N} | \mathbf{x}_1, \bar{\alpha}) \\ &= p(\mathbf{x}_1) \int p(\mathbf{X}_{2:N} | \mathbf{x}_1, \mathbf{A}, \bar{\alpha}) p(\mathbf{A}) d\mathbf{A}, \end{aligned} \quad (1)$$

where $\bar{\alpha}$ is a vector of kernel hyperparameters. Incorporating assumptions of the Markov property and the independence of output dimensions gives

$$\begin{aligned} p(\mathbf{X}_{2:N} | \mathbf{x}_1, \bar{\alpha}) &= \int \prod_{t=2}^N p(\mathbf{x}_t | \mathbf{x}_{t-1}, \mathbf{A}, \bar{\alpha}) p(\mathbf{A} | \bar{\alpha}) d\mathbf{A} \\ &= \int \prod_{t=2}^N \prod_{i=1}^d p(x_{t,i} | \mathbf{x}_{t-1}, \mathbf{A}, \bar{\alpha}) d\mathbf{A}. \end{aligned} \quad (2)$$

Since $x_{:,i}$ only depends on $\mathbf{a}_{:,i}$, factoring $p(\mathbf{A})$ and rearranging the integration order gives

$$\begin{aligned} p(\mathbf{X}_{2:N} | \mathbf{x}_1, \bar{\alpha}) &= \int \prod_{t=2}^N \prod_{i=1}^d p(x_{t,i} | \mathbf{x}_{t-1}, \mathbf{a}_{:,i}, \bar{\alpha}) p(\mathbf{a}_{:,i}) d\mathbf{A} \\ &= \int_{\mathbf{a}_{:,1}} \dots \int_{\mathbf{a}_{:,d}} \prod_{i=1}^d \prod_{t=2}^N p(x_{t,i} | \mathbf{x}_{t-1}, \mathbf{a}_{:,i}, \bar{\alpha}) p(\mathbf{a}_{:,i}) d\mathbf{a}_{:,d} \dots d\mathbf{a}_{:,1} \\ &= \prod_{i=1}^d \int_{\mathbf{a}_{:,i}} \prod_{t=2}^N p(x_{t,i} | \mathbf{x}_{t-1}, \mathbf{a}_{:,i}, \bar{\alpha}) p(\mathbf{a}_{:,i}) d\mathbf{a}_{:,i}. \end{aligned} \quad (3)$$

The RHS of (3) is identical in form to the likelihood of a GPLVM with input $\mathbf{X}_{1:N-1}$ and output $\mathbf{X}_{2:N}$. Therefore we obtain

$$\begin{aligned} p(\mathbf{X} | \bar{\alpha}) &= \frac{p(\mathbf{x}_1)}{\sqrt{(2\pi)^{(N-1)d} |\mathbf{K}_X|^d}} \exp \left(-\frac{1}{2} \text{tr} (\mathbf{K}_X^{-1} \mathbf{X}_{2:N} \mathbf{X}_{2:N}^T) \right), \end{aligned} \quad (4)$$

where $\mathbf{X}_{2:N} = [\mathbf{x}_2, \dots, \mathbf{x}_N]^T$, and \mathbf{K}_X is the $(N-1) \times (N-1)$ kernel matrix constructed from $\mathbf{X}_{1:N-1} = [\mathbf{x}_1, \dots, \mathbf{x}_{N-1}]^T$.