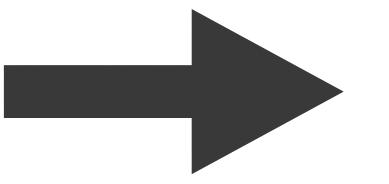


# Paparazzi: Surface Editing by way of Multi-View Image Processing

Hsueh-Ti Derek Liu, Michael Tao, Alec Jacobson  
University of Toronto

# Image Filters



# Image Filters



# Image Style Transfer [Gatys et al. 2016]

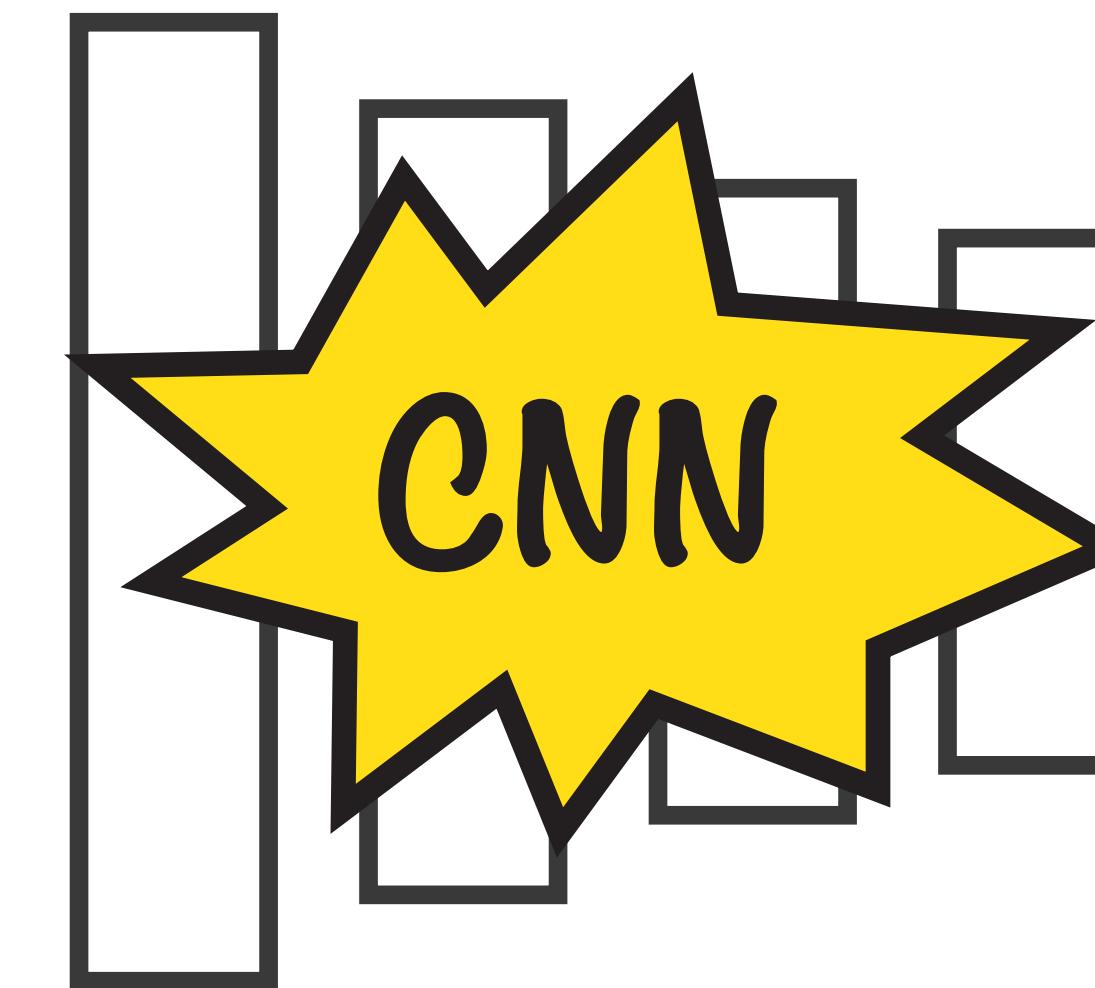


input

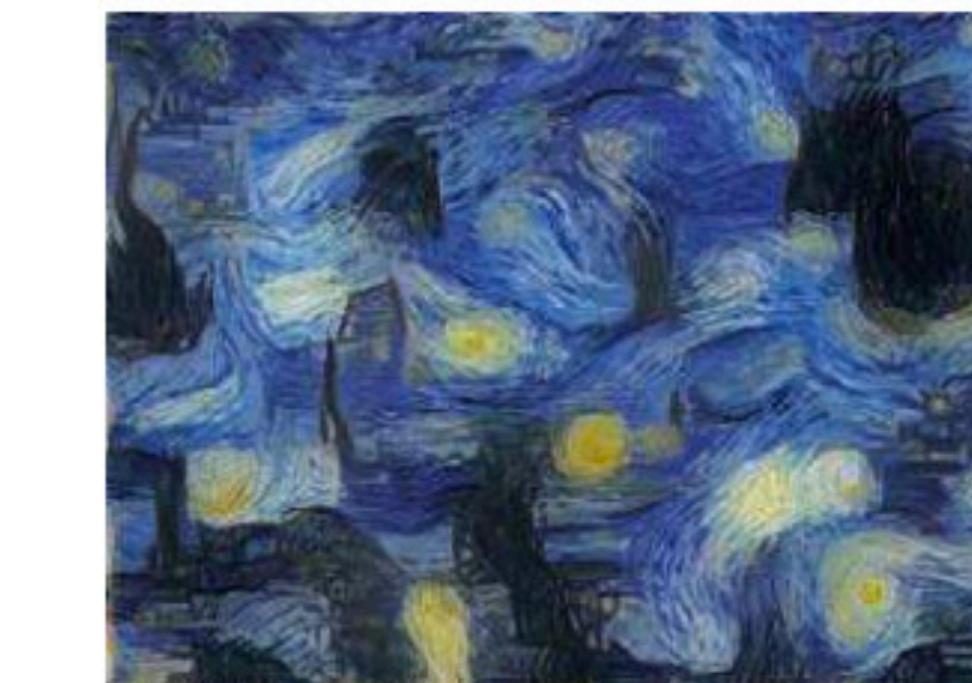
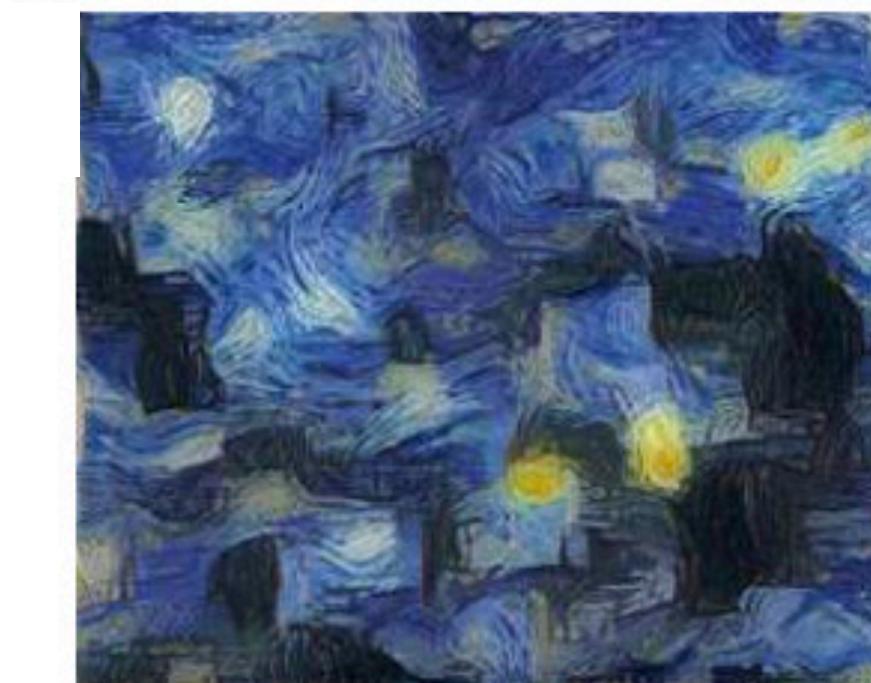
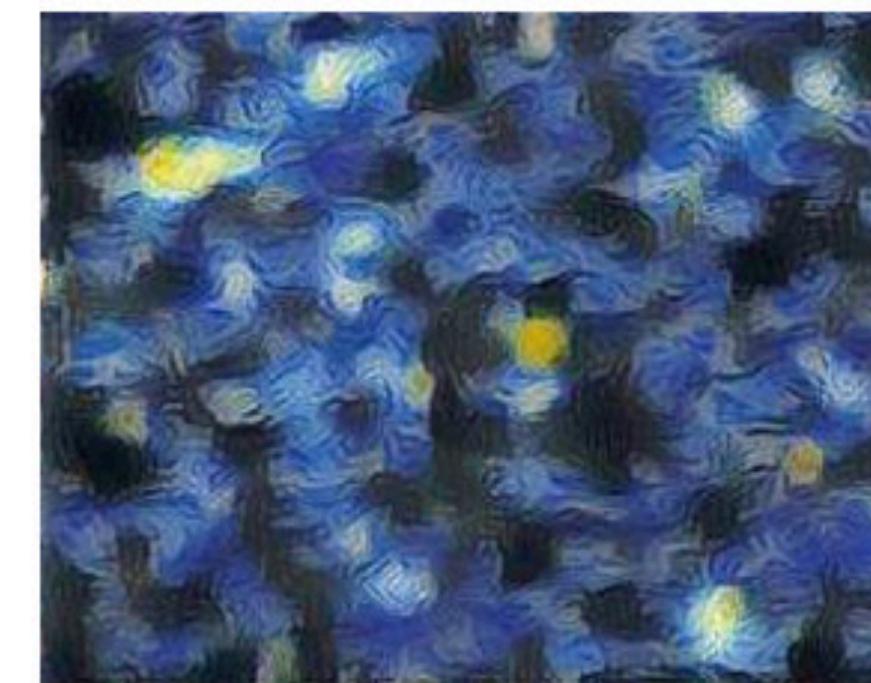
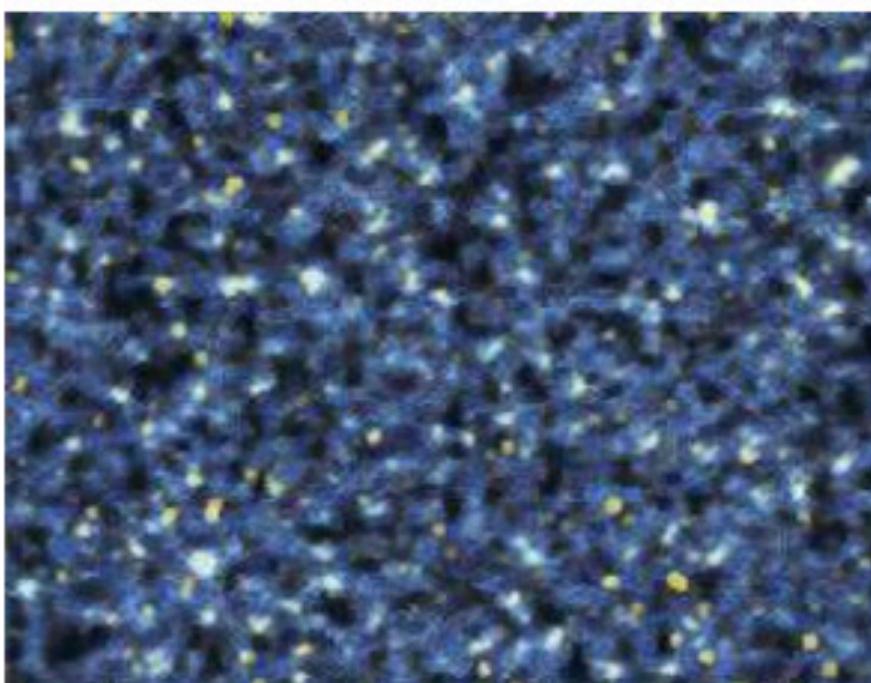
+



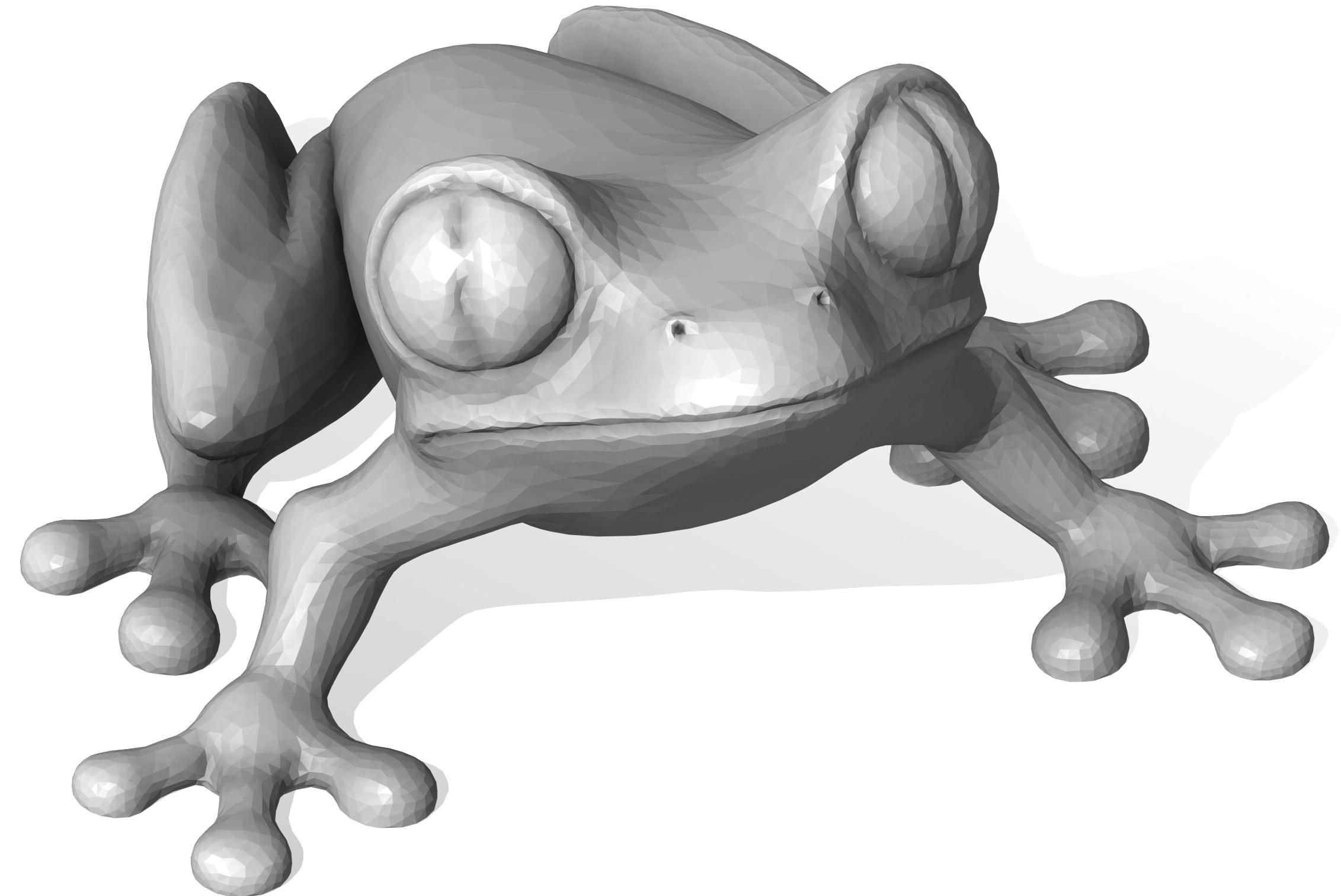
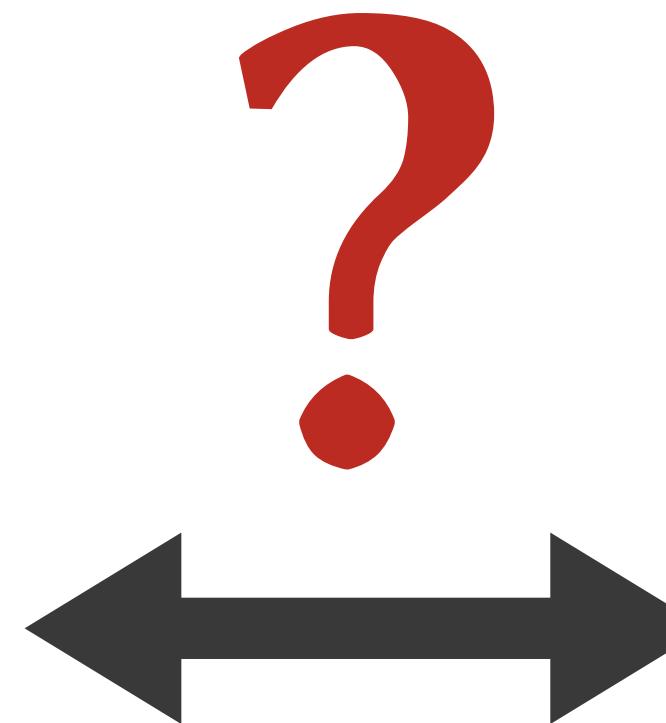
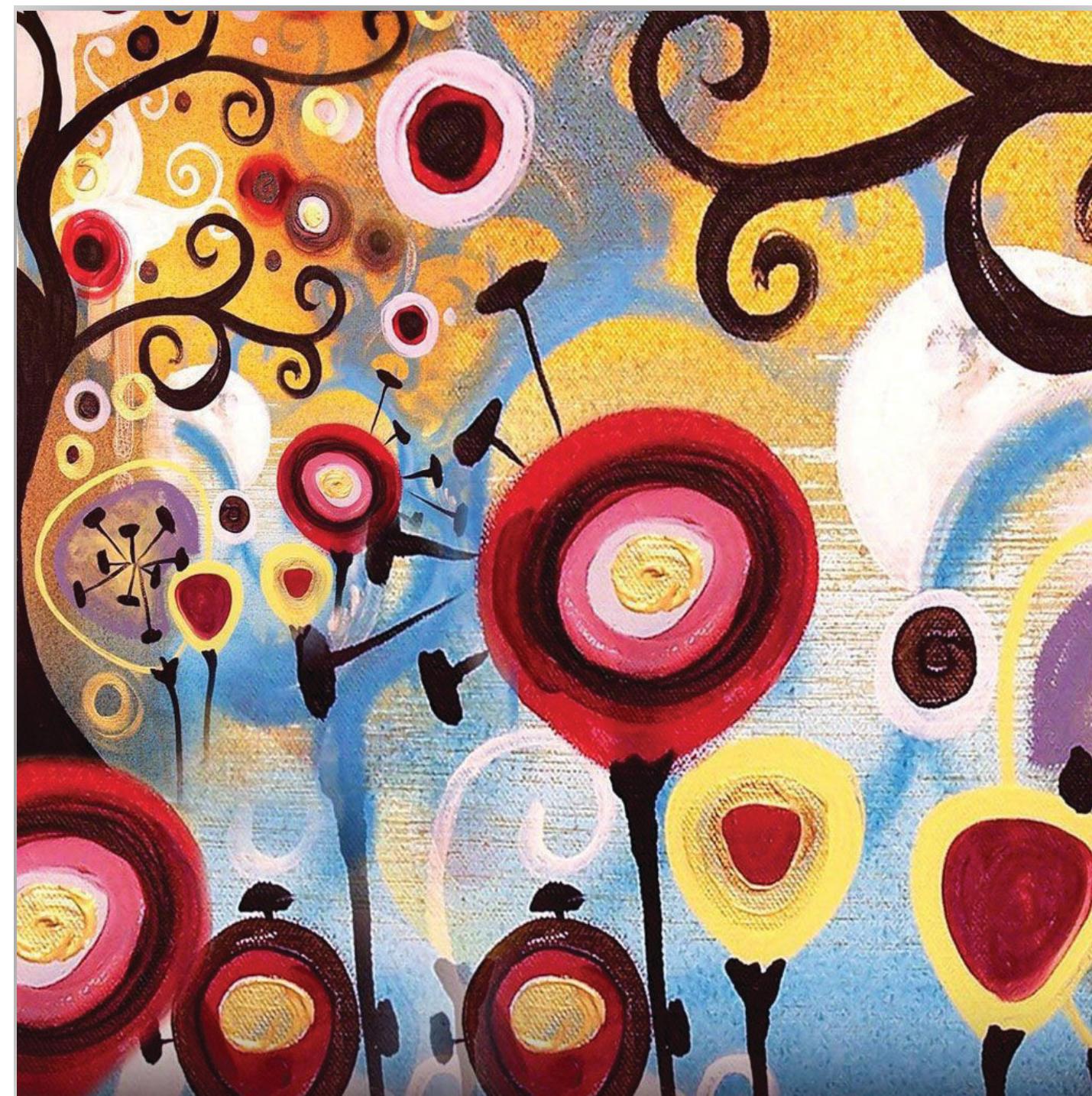
style

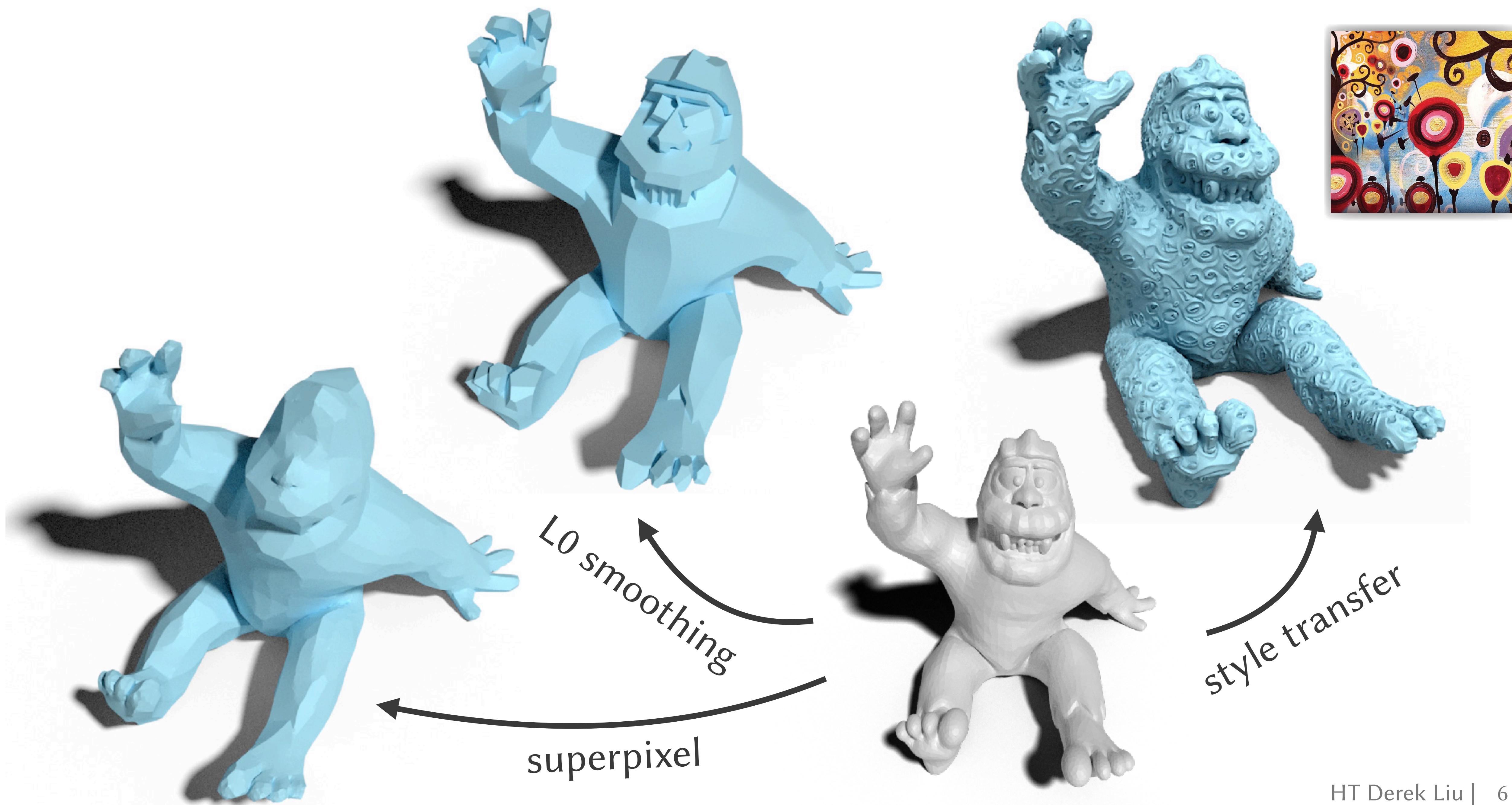


output



# Style Transfer for 3D Triangle Meshes





# Main Idea: Shape Optimization

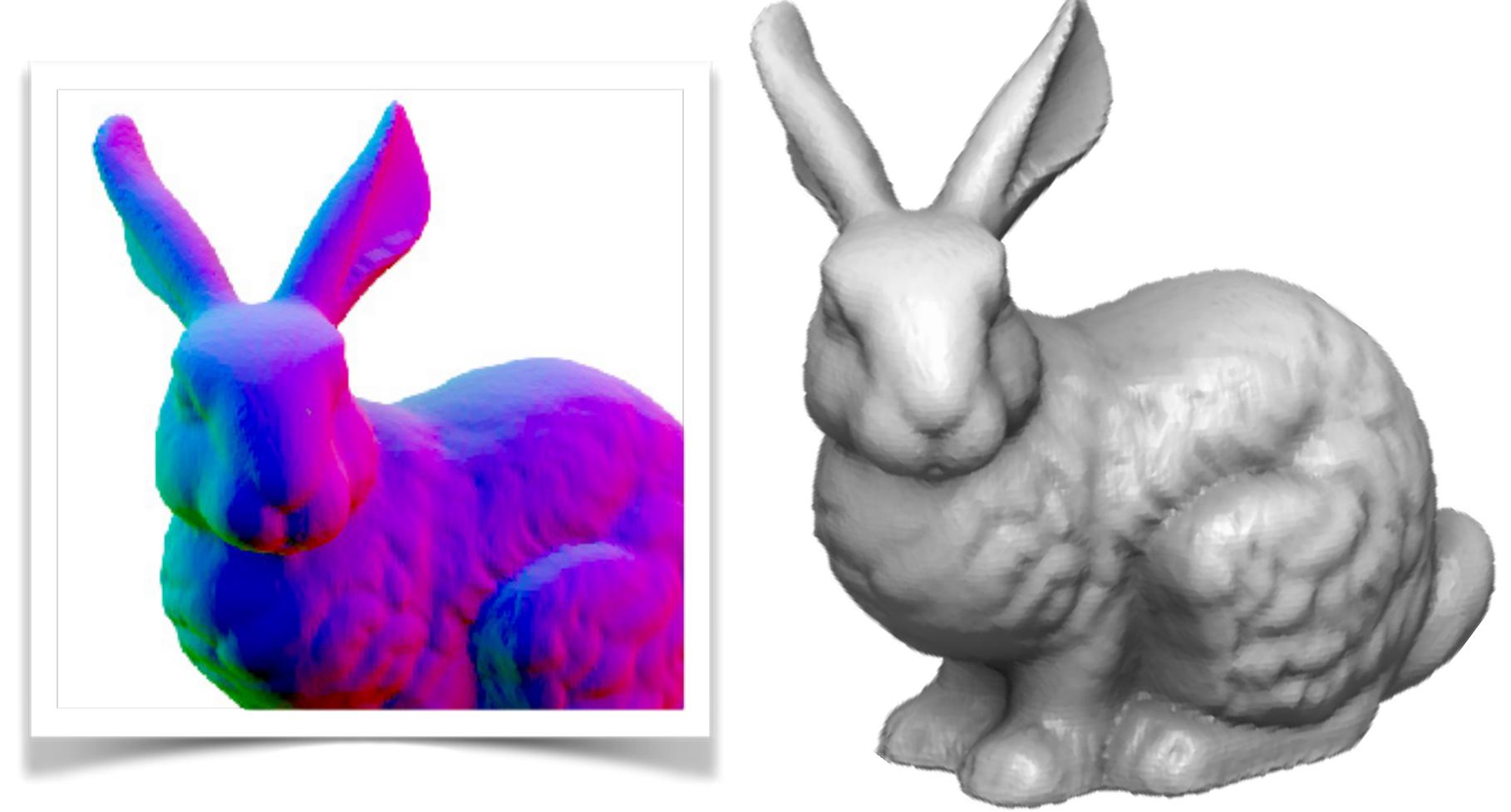
$$E_{3D} \left( \text{3D Model} \right) := \int E_{2D} \left( \text{2D Heatmap} \right)$$

# Key Steps

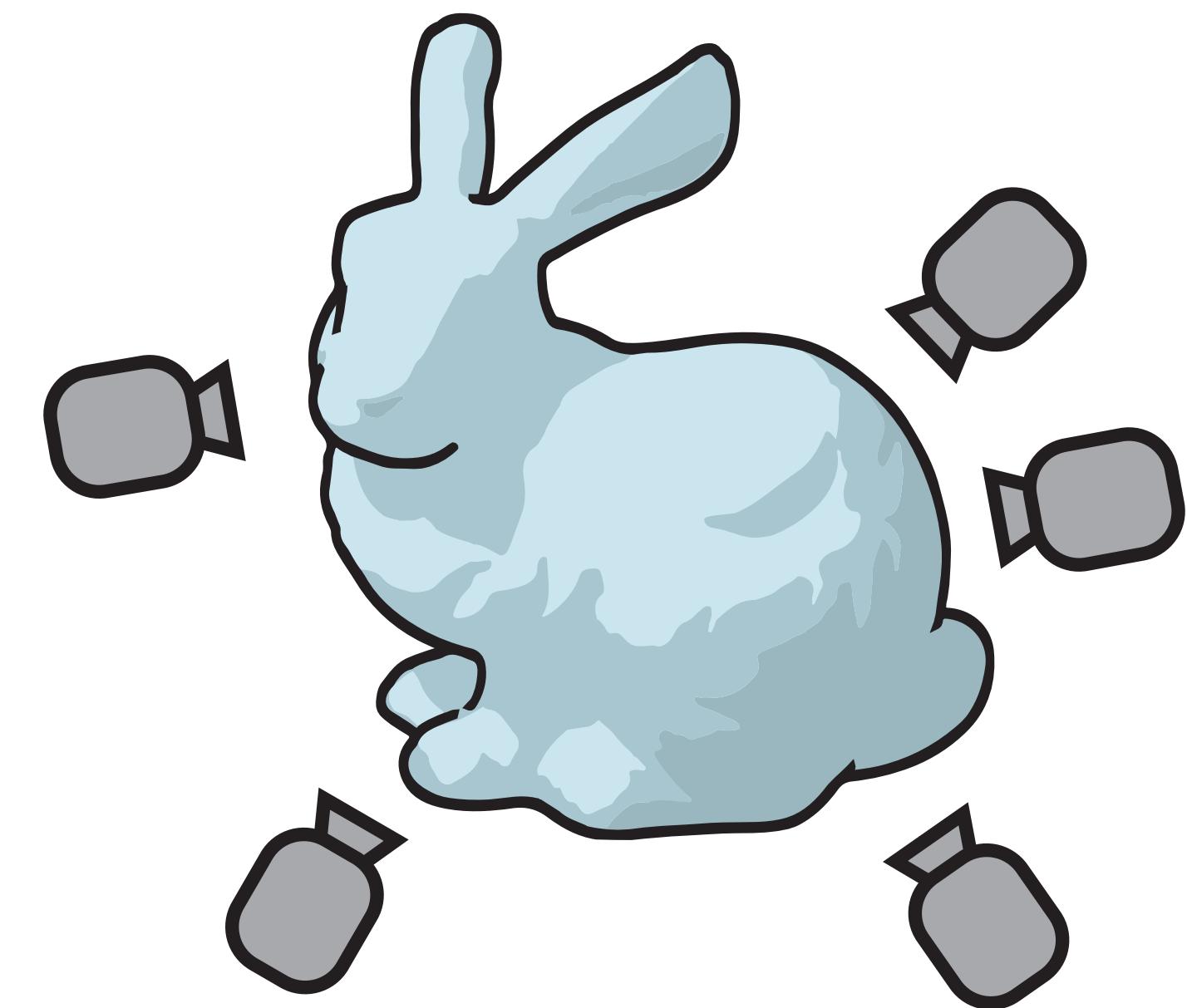
1. Process renderings



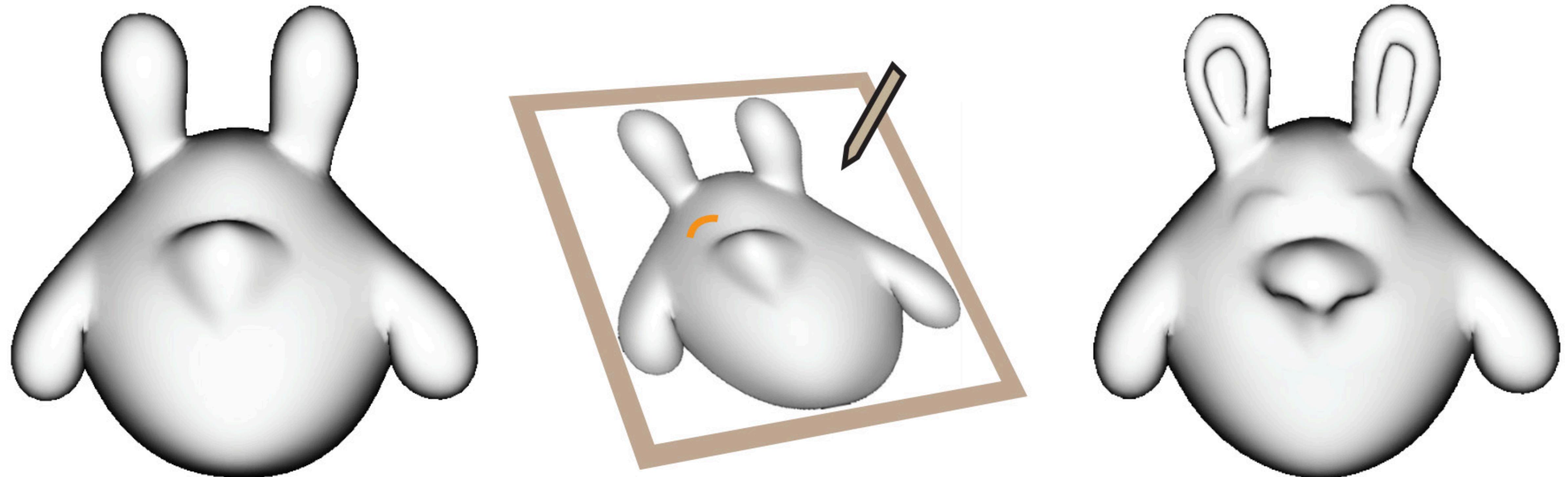
2. Differentiable renderer



3. Multiview optimization

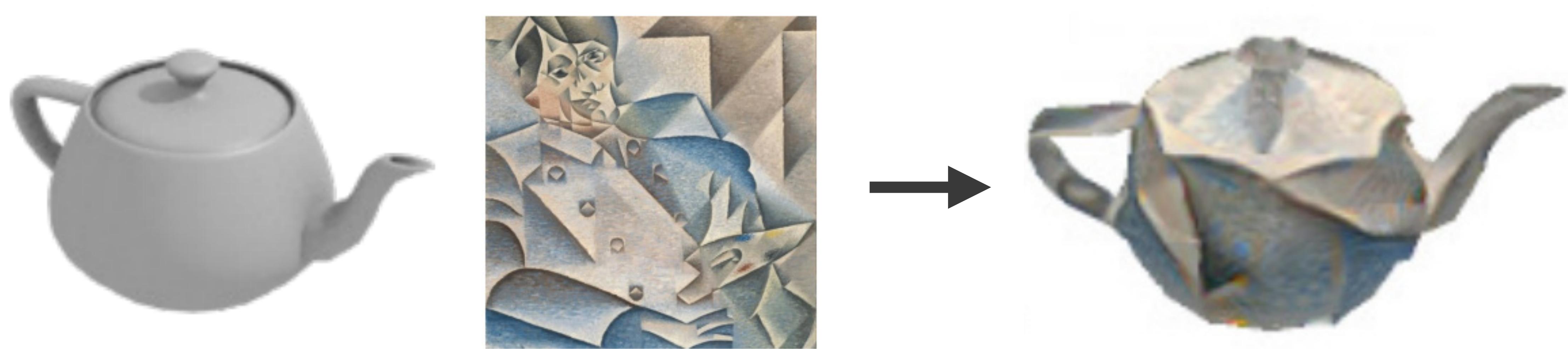


# Shading-Based Surface Editing



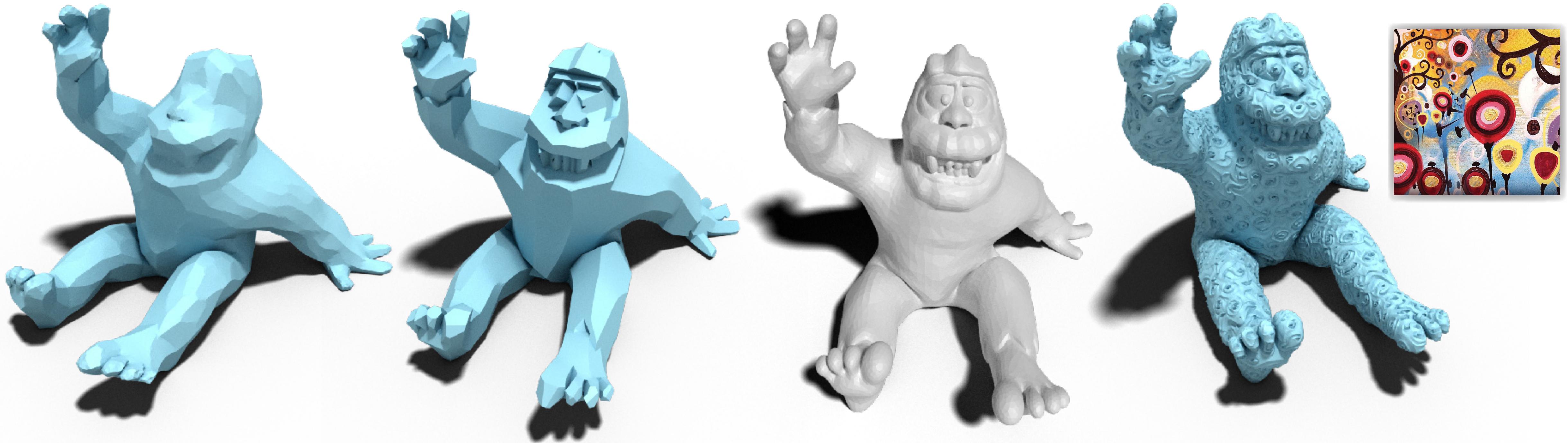
# Previous Differentiable Renderers

- Automatic differentiation [Loper Black 2014, Genova et al. 2018]
- Rendering networks [Eslami et al. 2016, Liu et al. 2017, Richardson et al. 2017, Wu et al. 2017]
- Neural 3D mesh renderer [Kato et al. 2018]

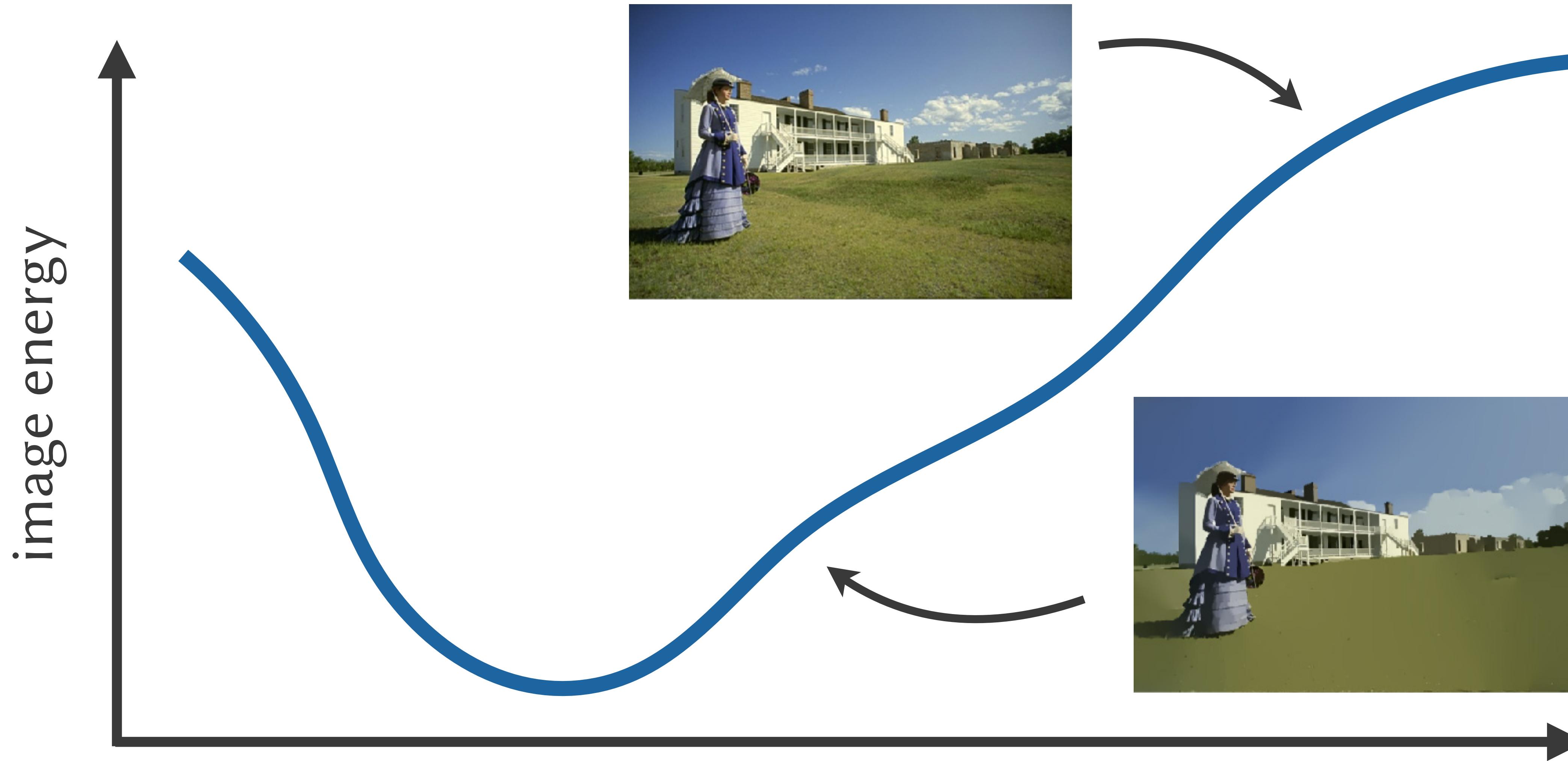


# Paparazzi

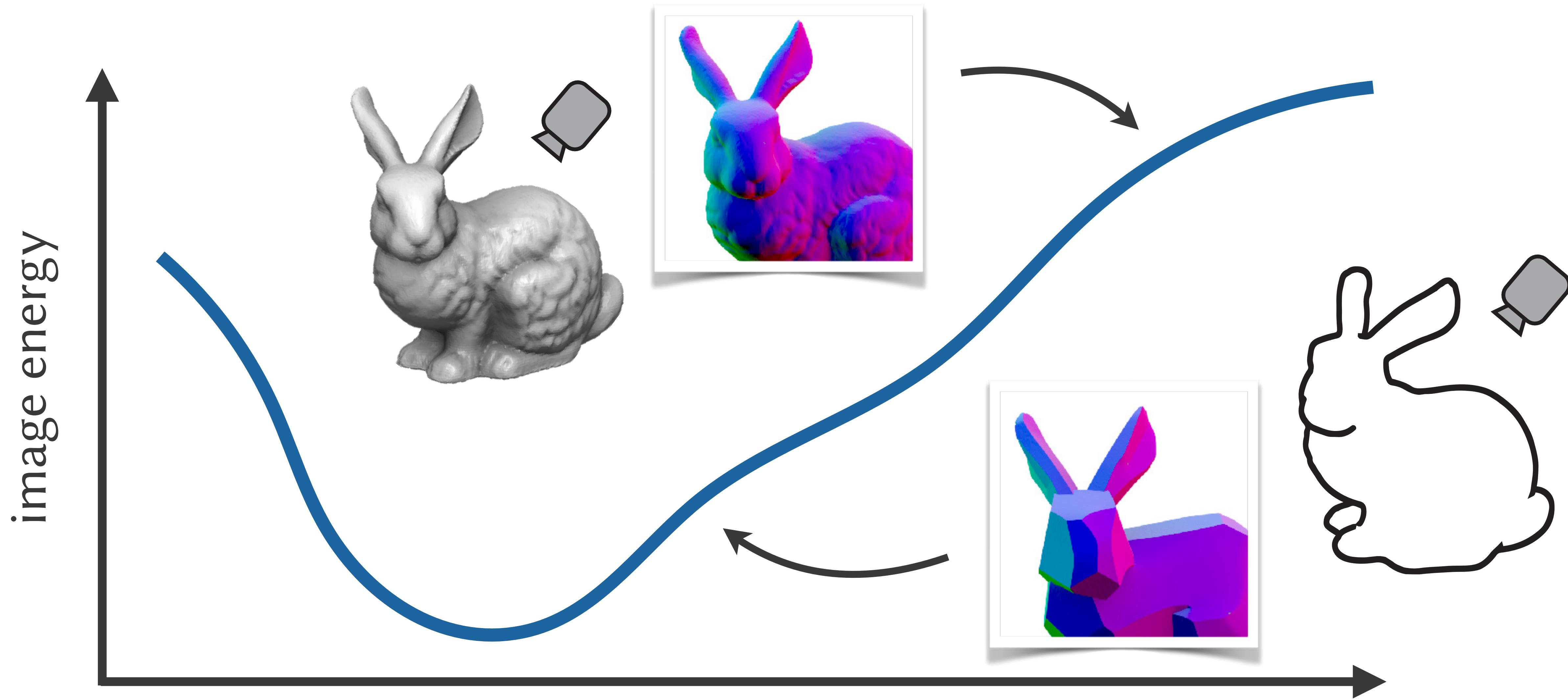
- More general than shading-based editing
- Tailor-made novel differentiable renderer for 3D shapes
- **Analytical** derivative (faster, less memory)



# Image Optimization



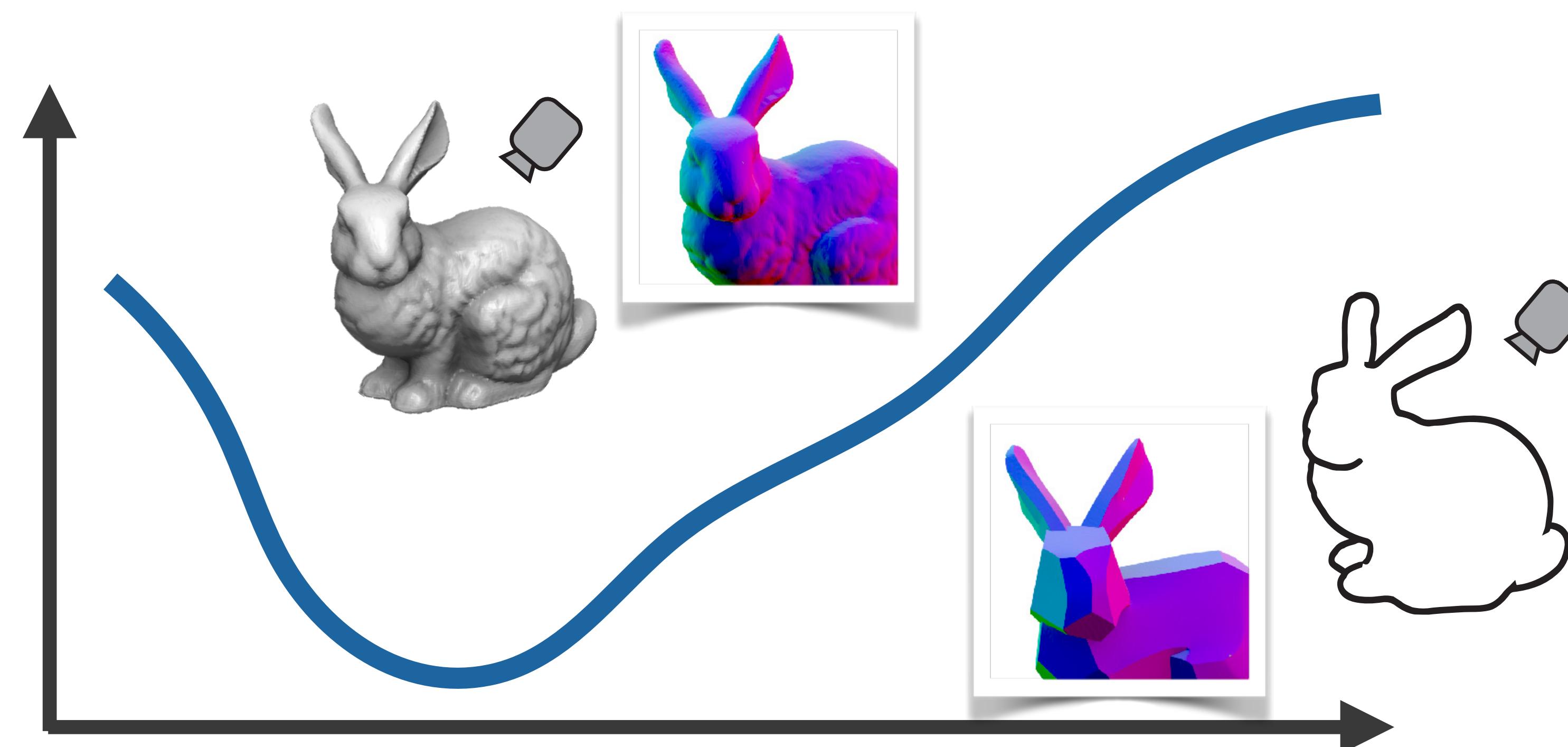
# Paparazzi Shape Optimization



# Paparazzi Shape Optimization

$$V^* \leftarrow \arg \min_V E(R(V))$$

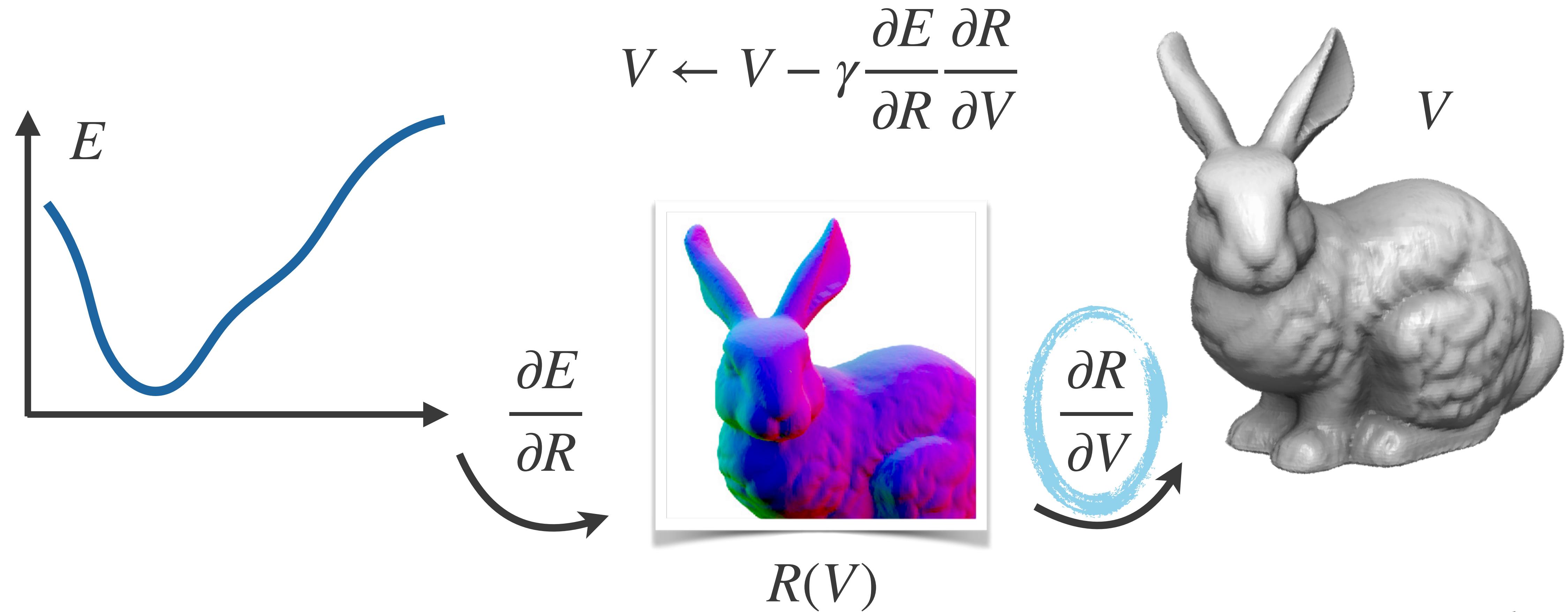
optimized shape      image energy      rendering



# Paparazzi Shape Optimization

$$V^* \leftarrow \arg \min_V E(R(V))$$

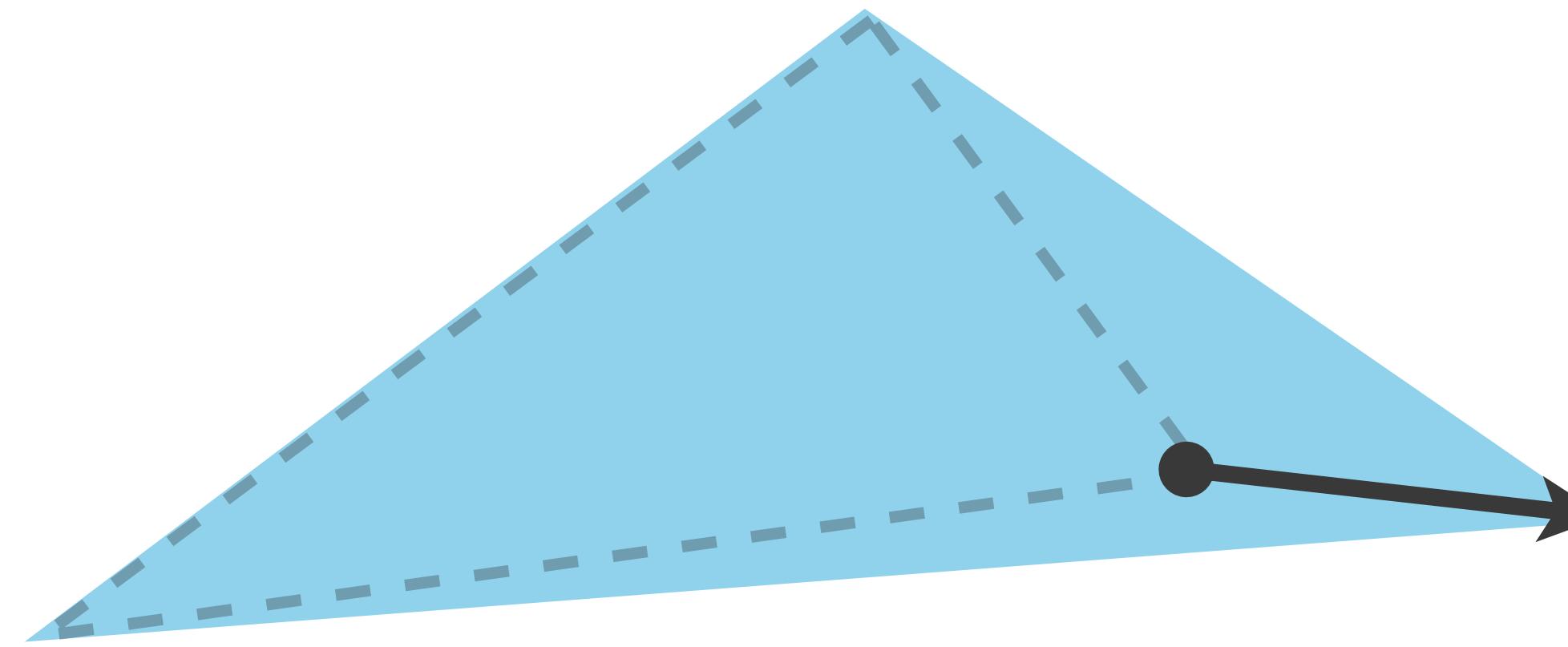
Gradient descent method



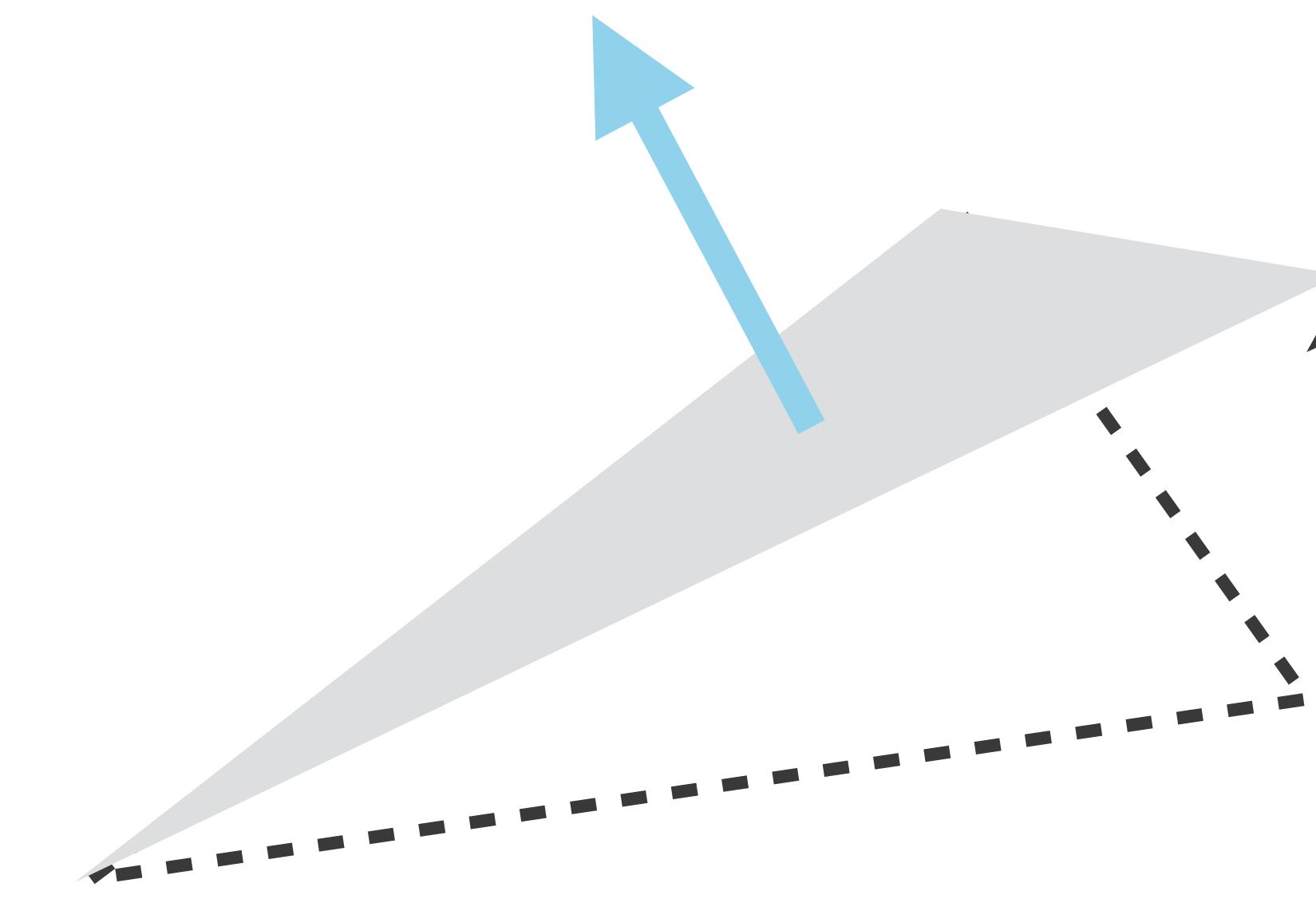
# RENDERING DIFFERENTIABLE?



# Rendering a Geometry

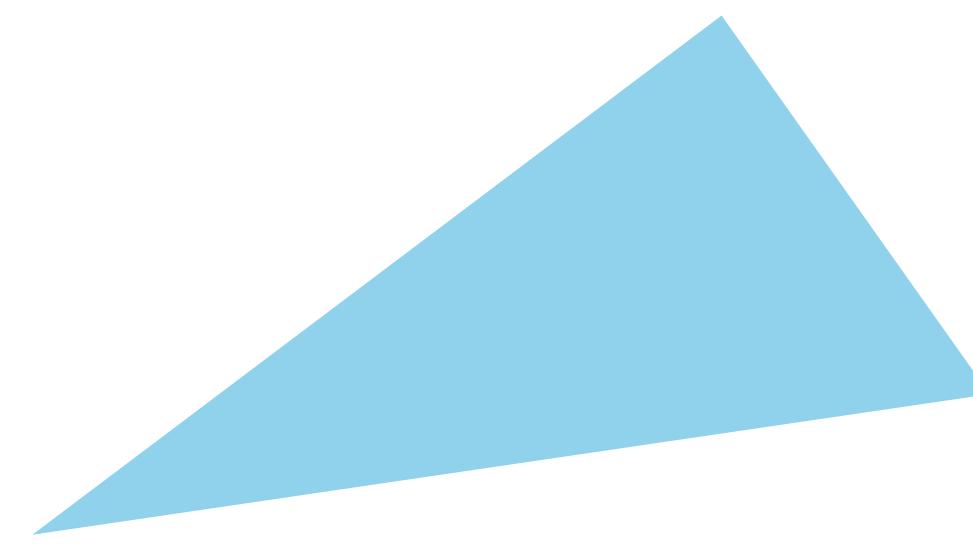
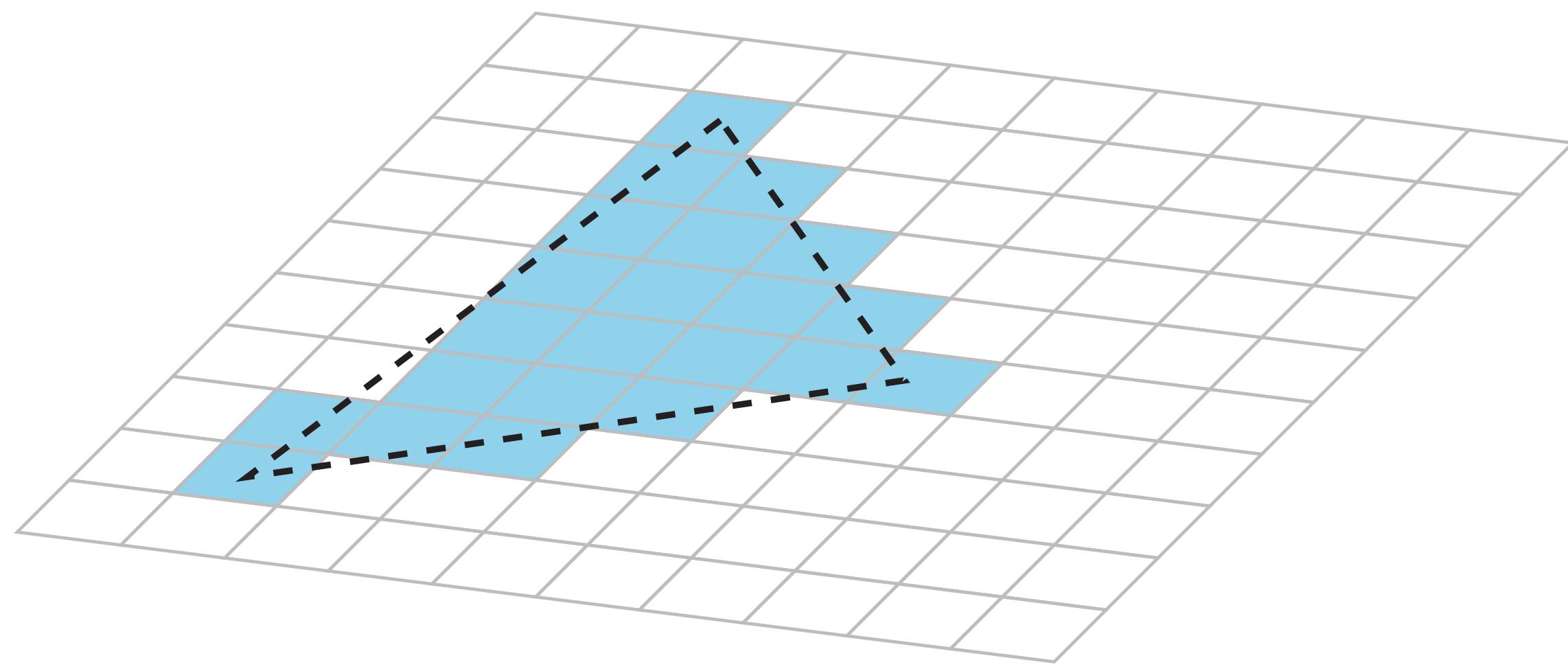


Visibility

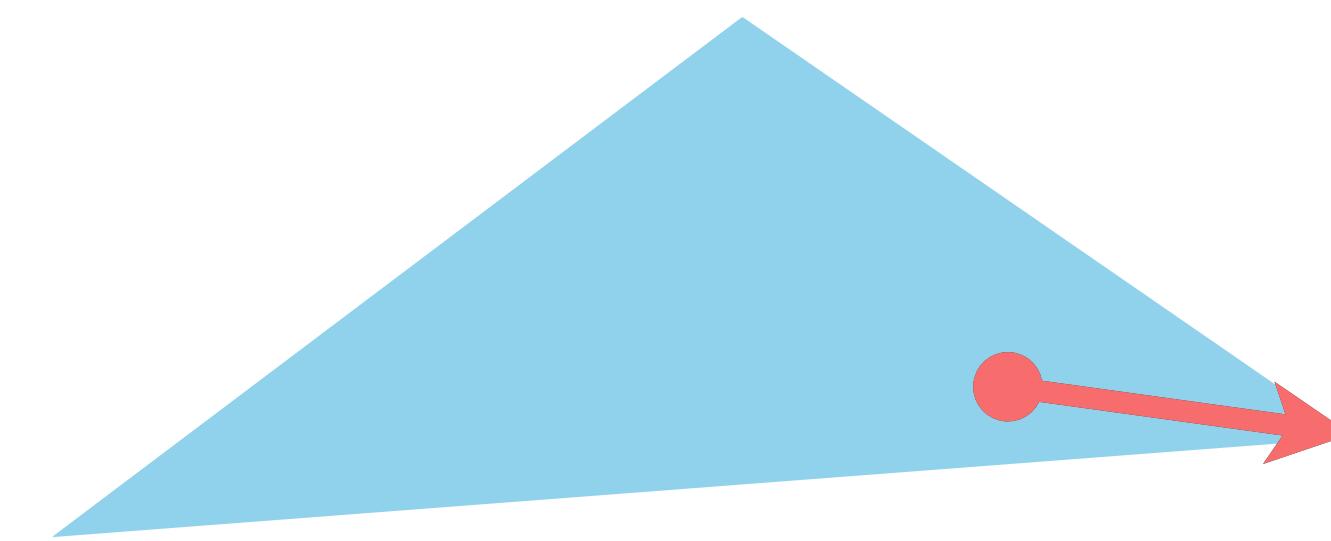
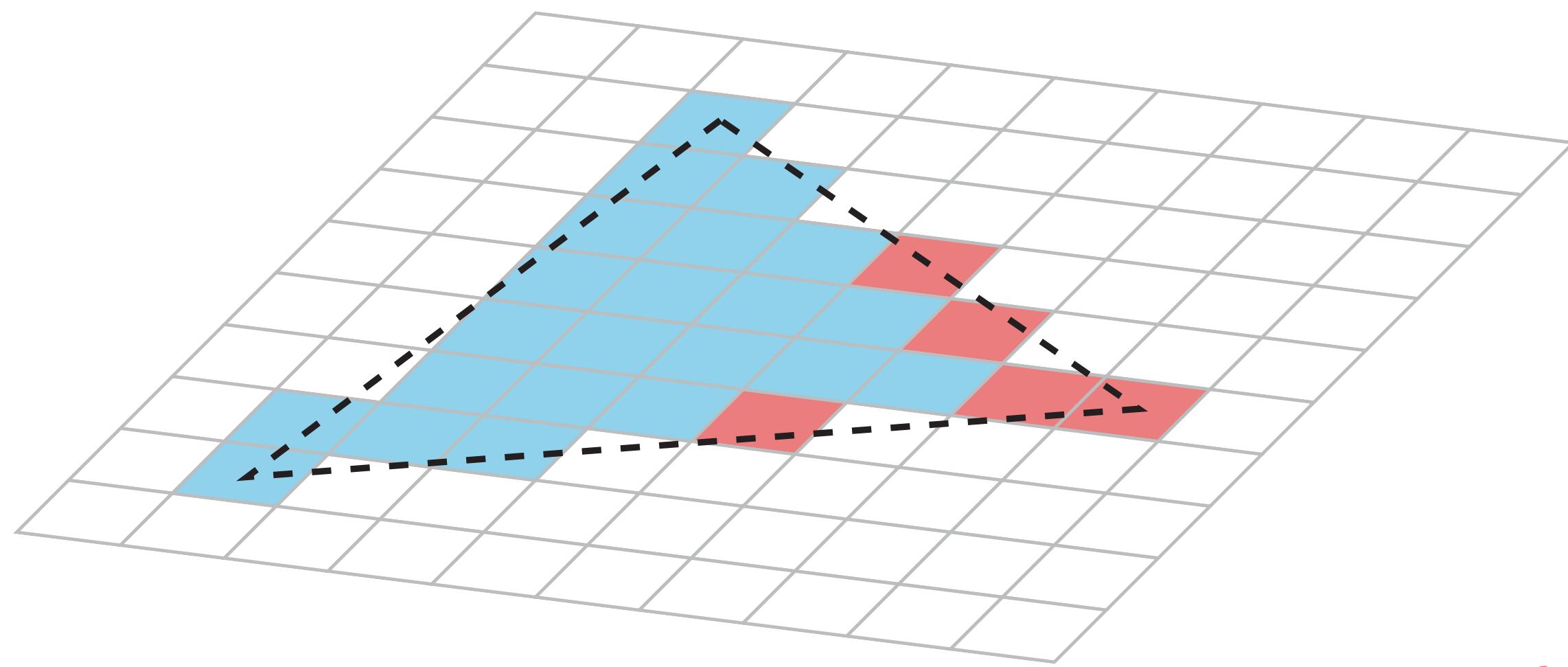


Orientation

# Visibility Component

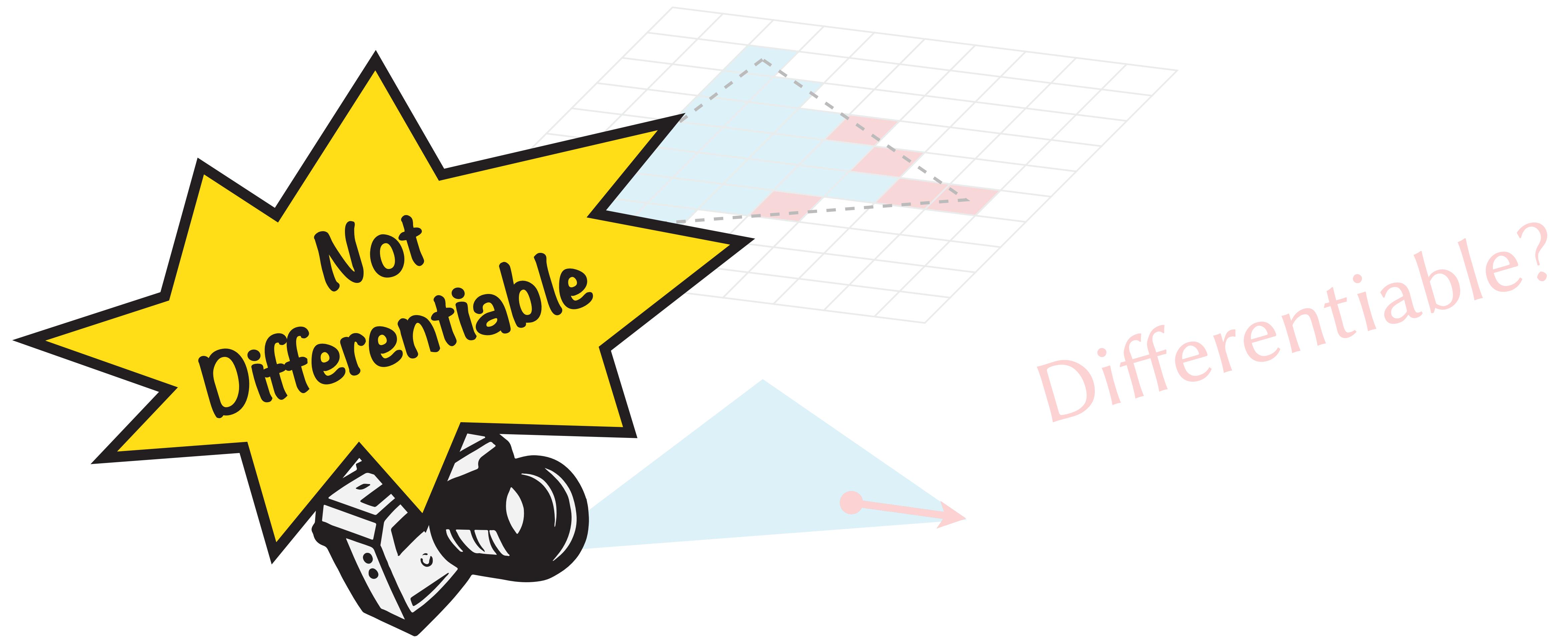


# Visibility Component

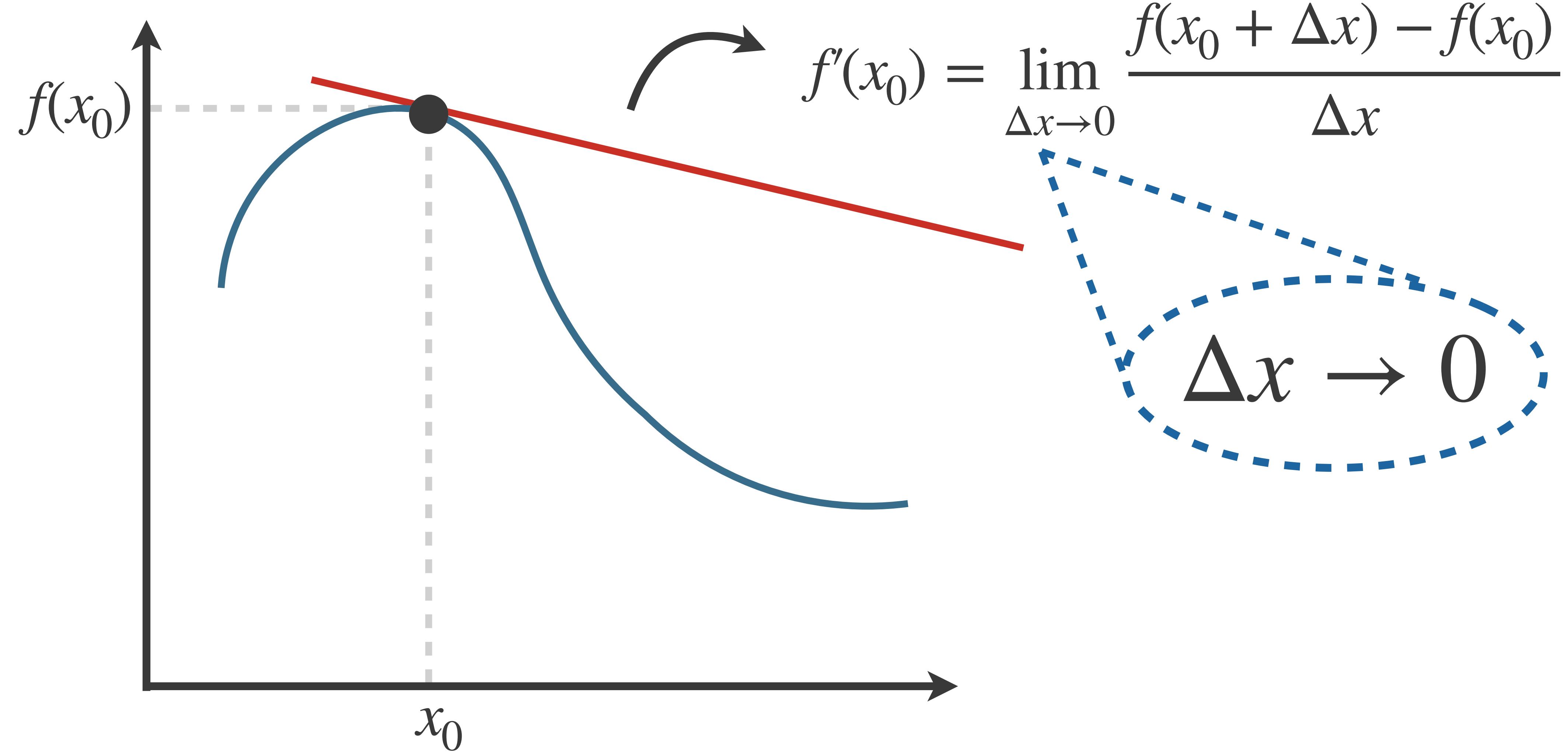


Differentiable?

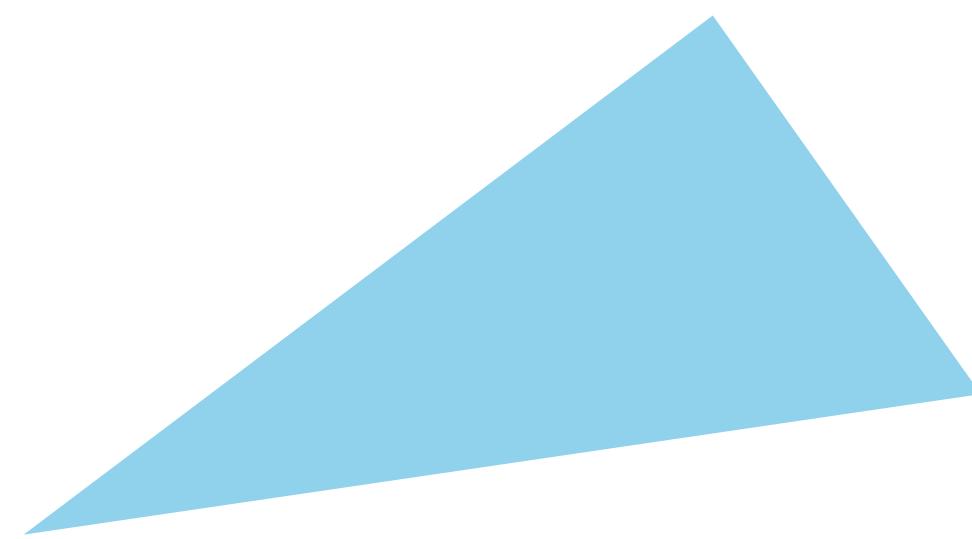
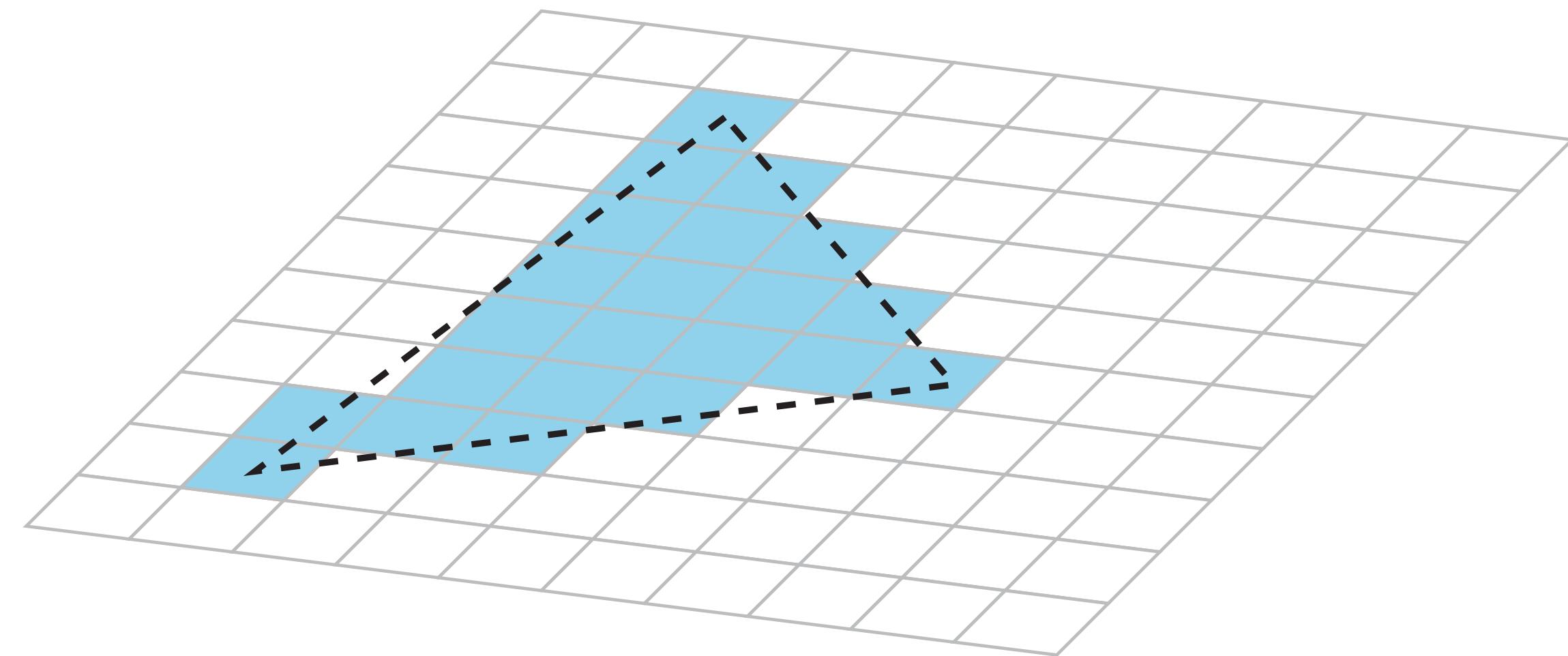
# Visibility Component



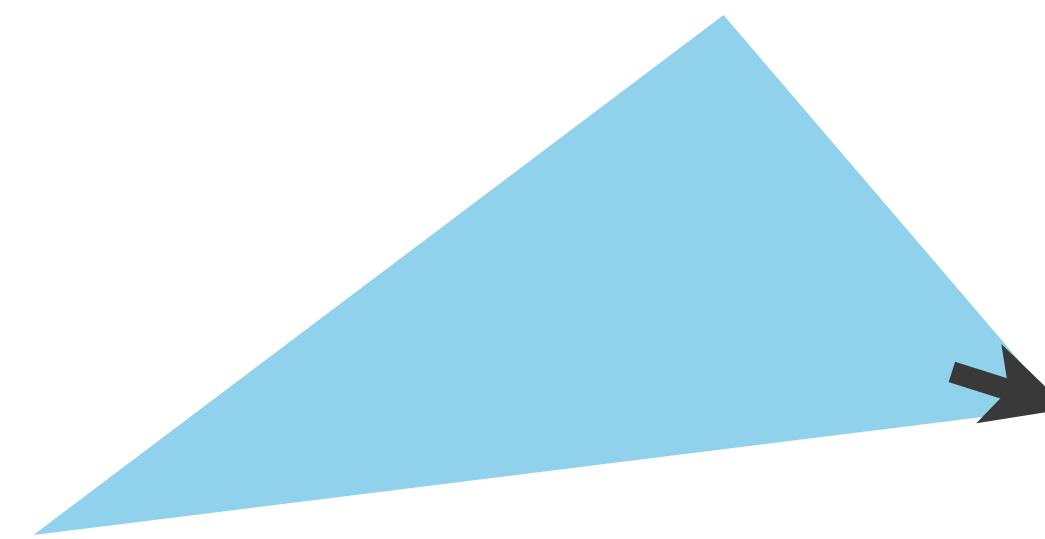
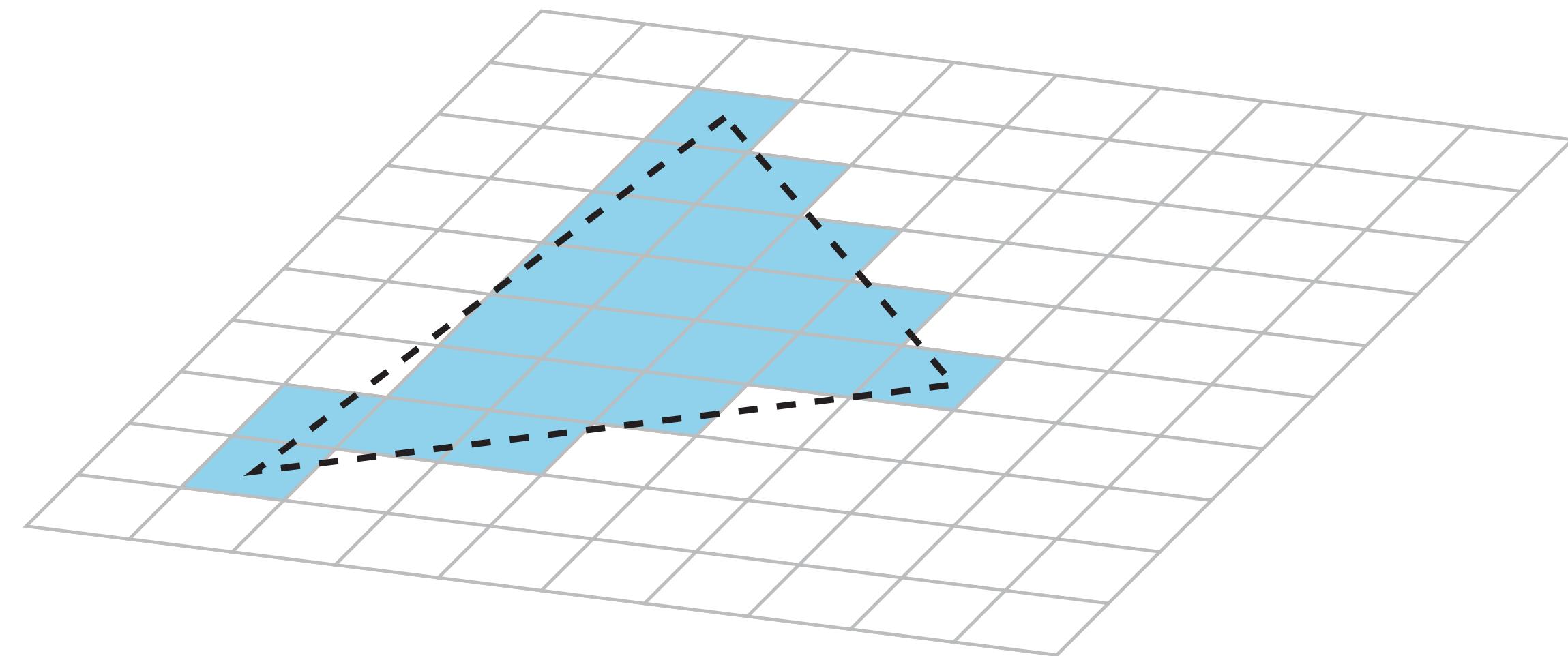
# Analytical Derivative



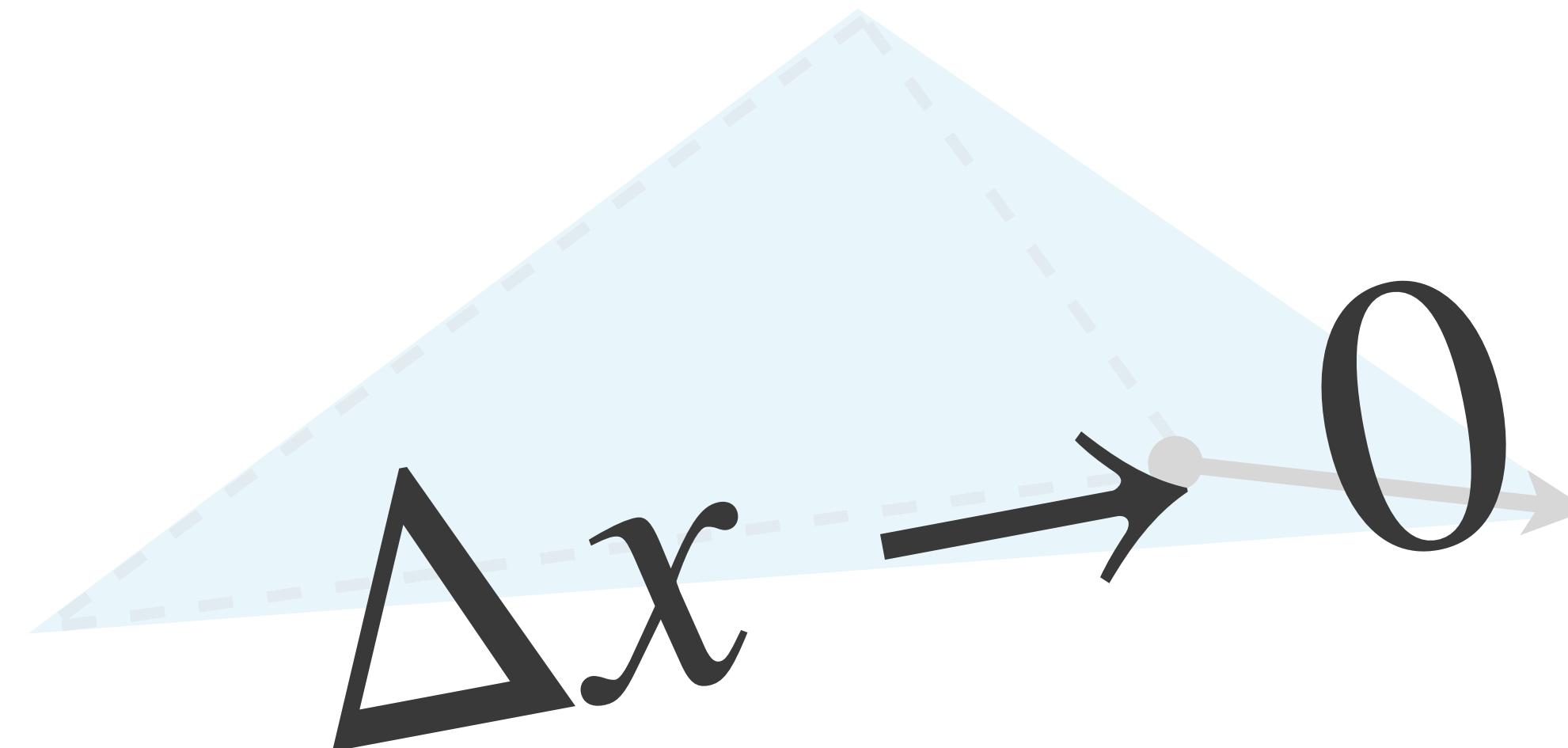
# Visibility Component $\Delta x \rightarrow 0$



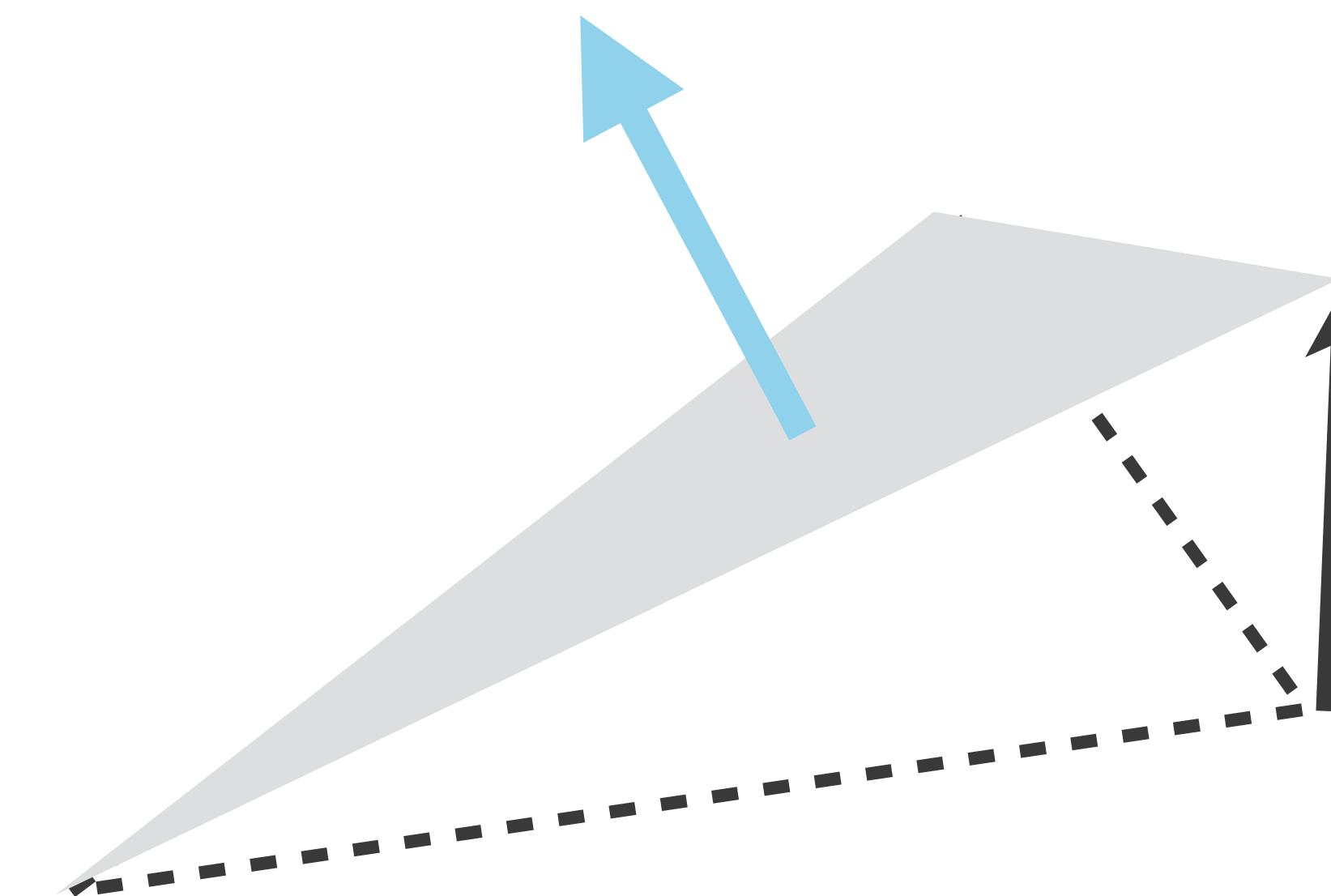
# Visibility Component $\Delta x \rightarrow 0$



# Rendering a Geometry

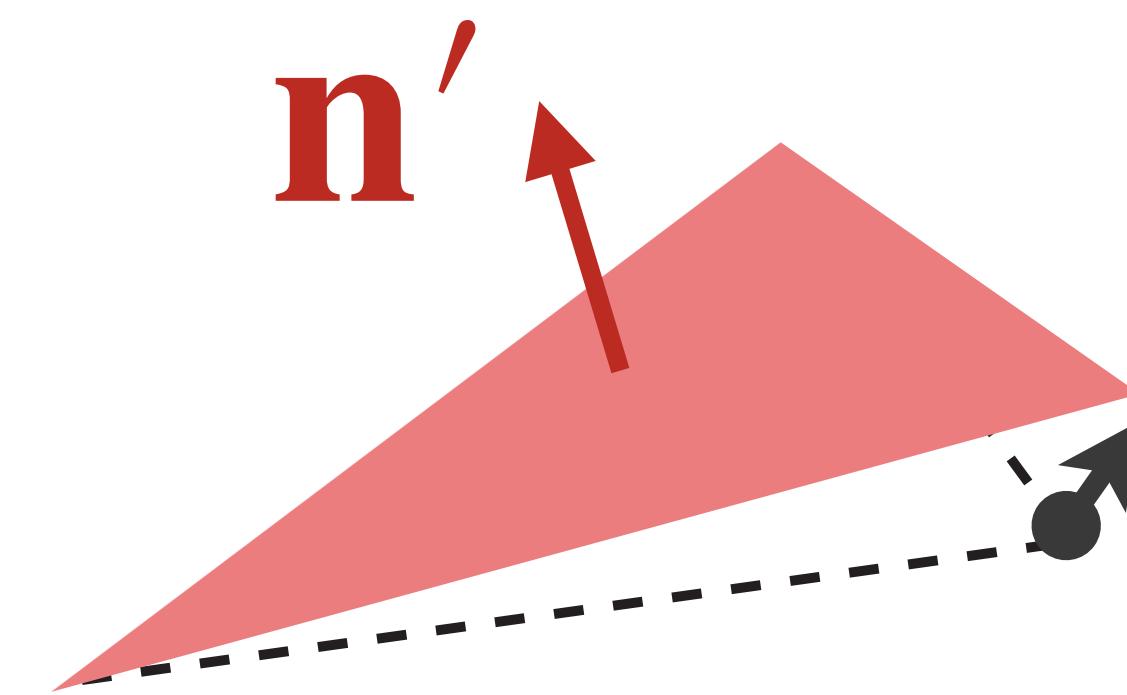
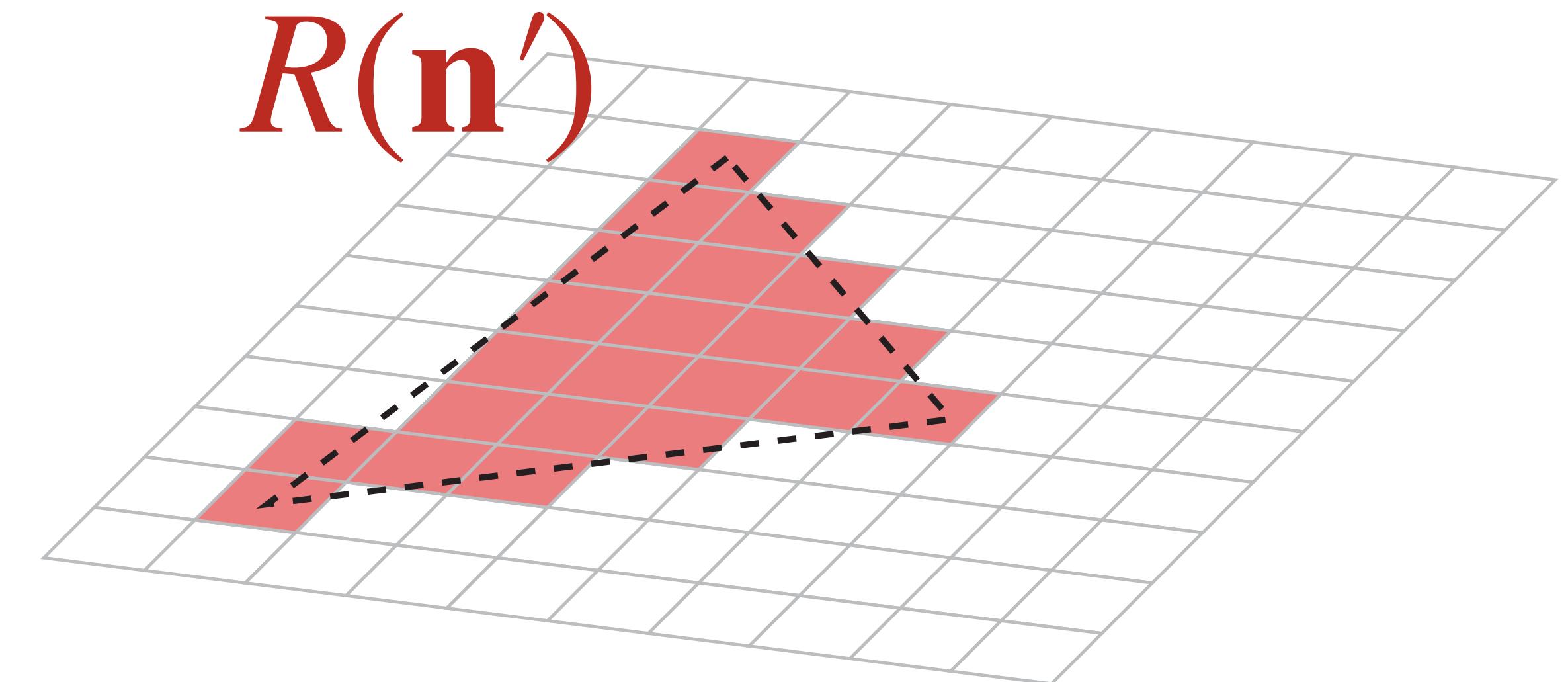
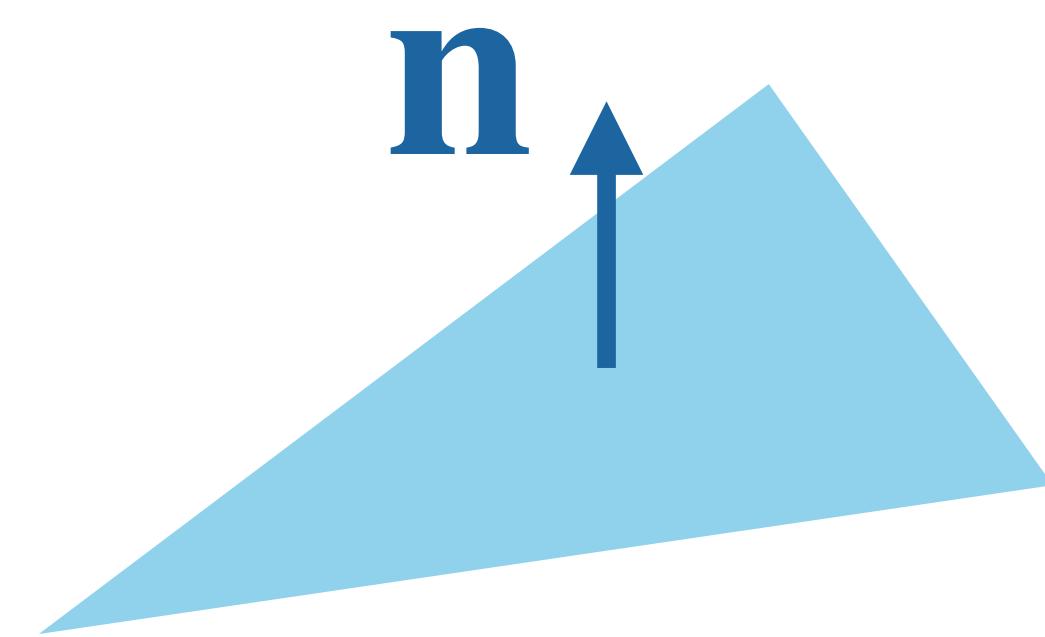
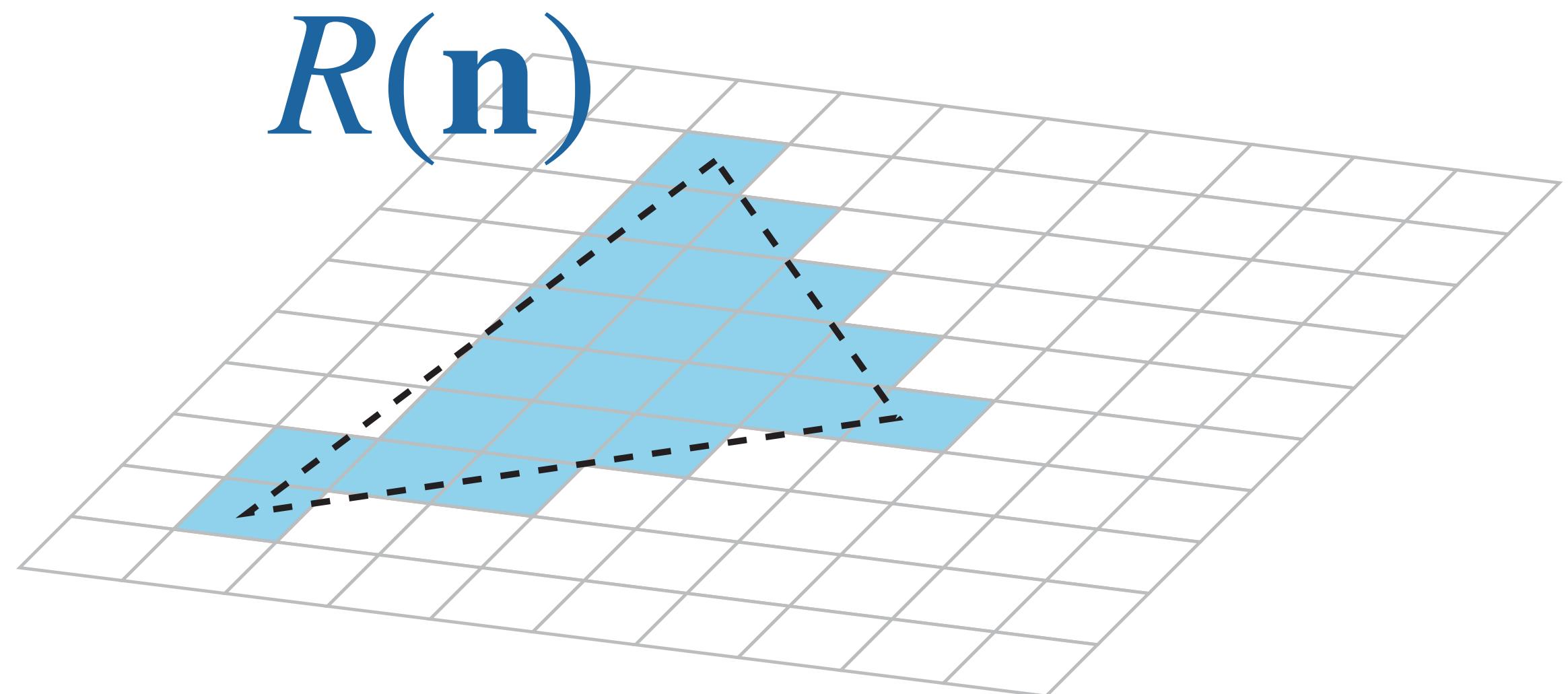


Visibility

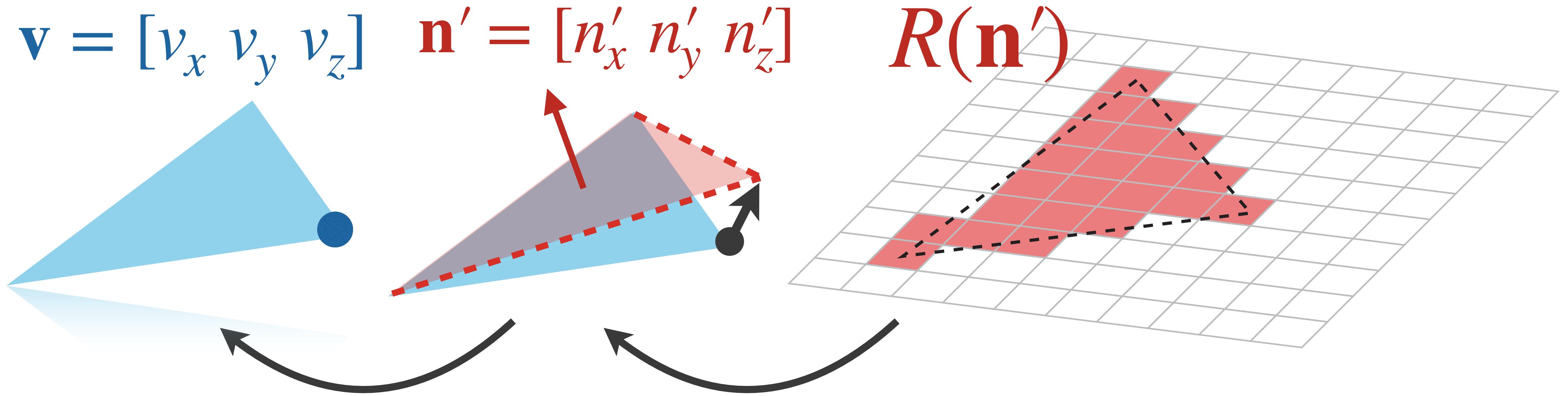


Orientation

# Orientation Component

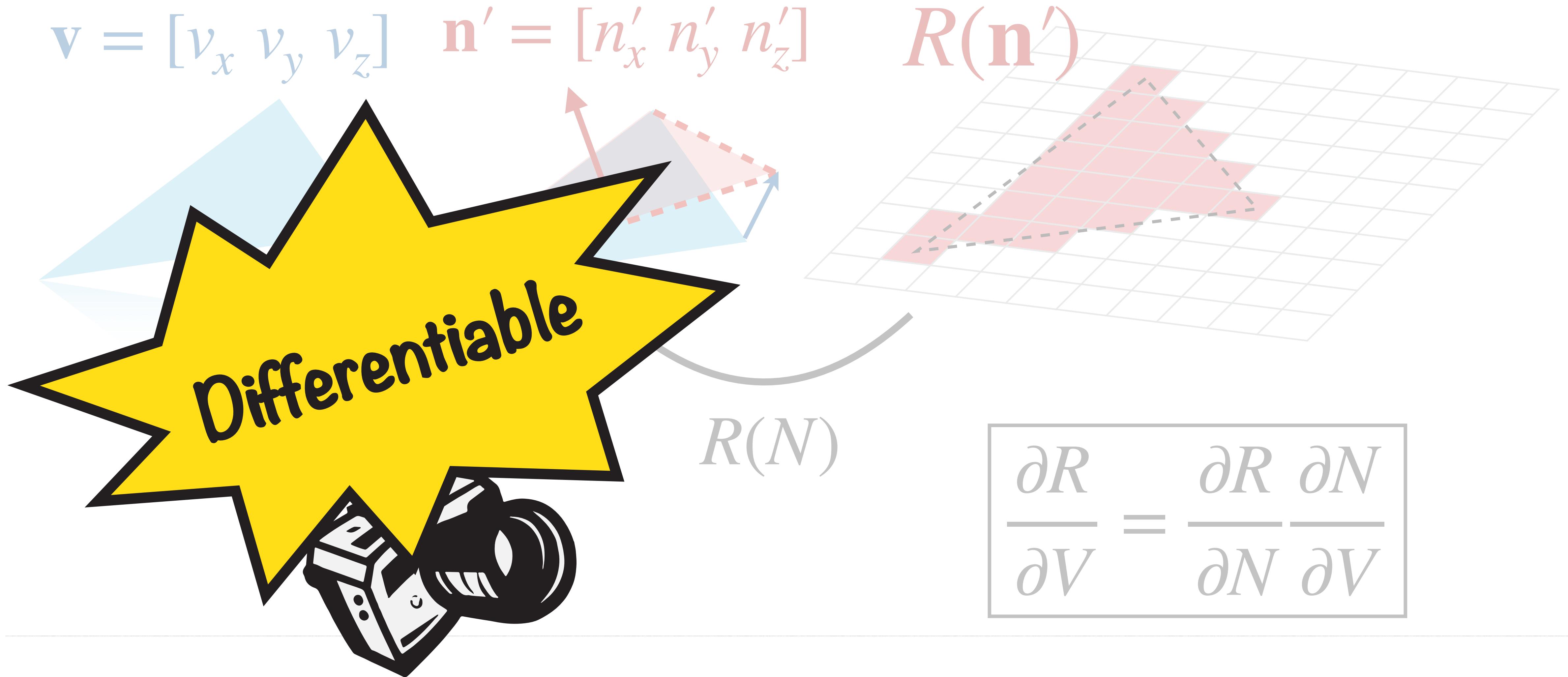


# Orientation Component

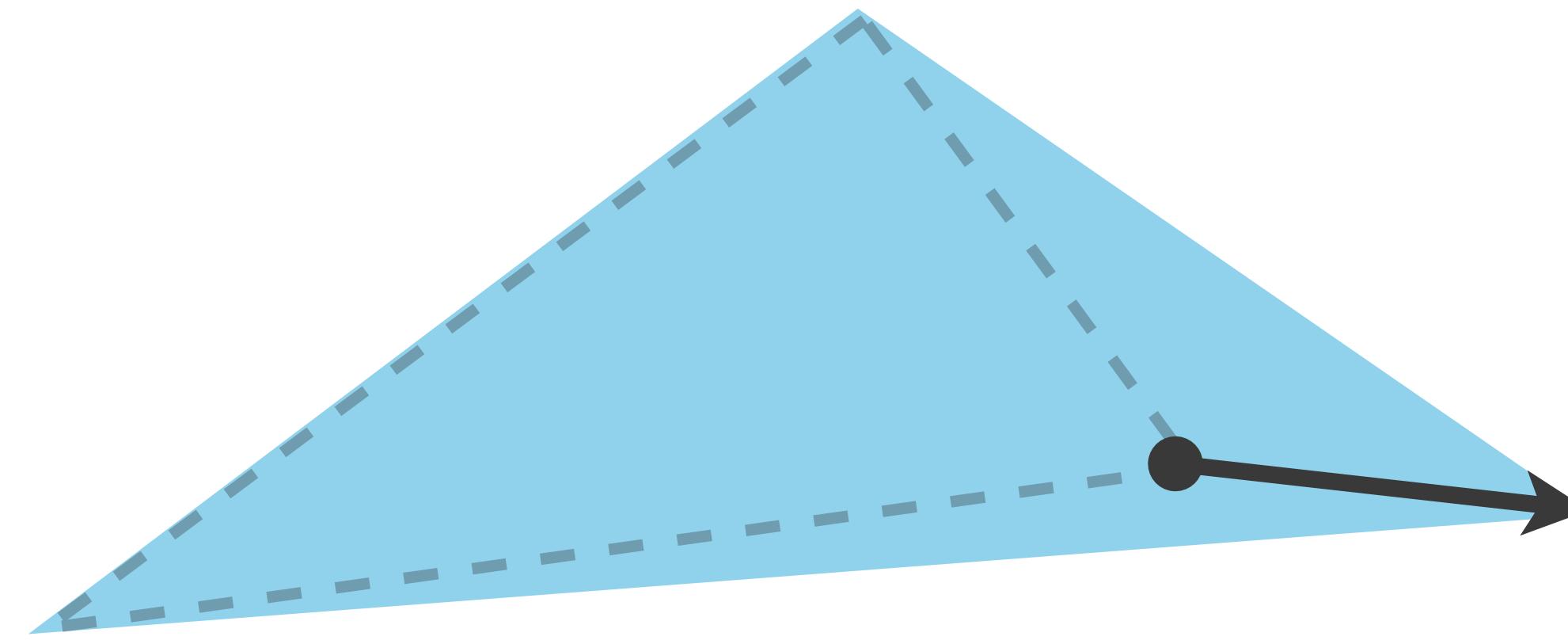


$$\frac{\partial R}{\partial V} = \frac{\partial R}{\partial N} \frac{\partial N}{\partial V}$$

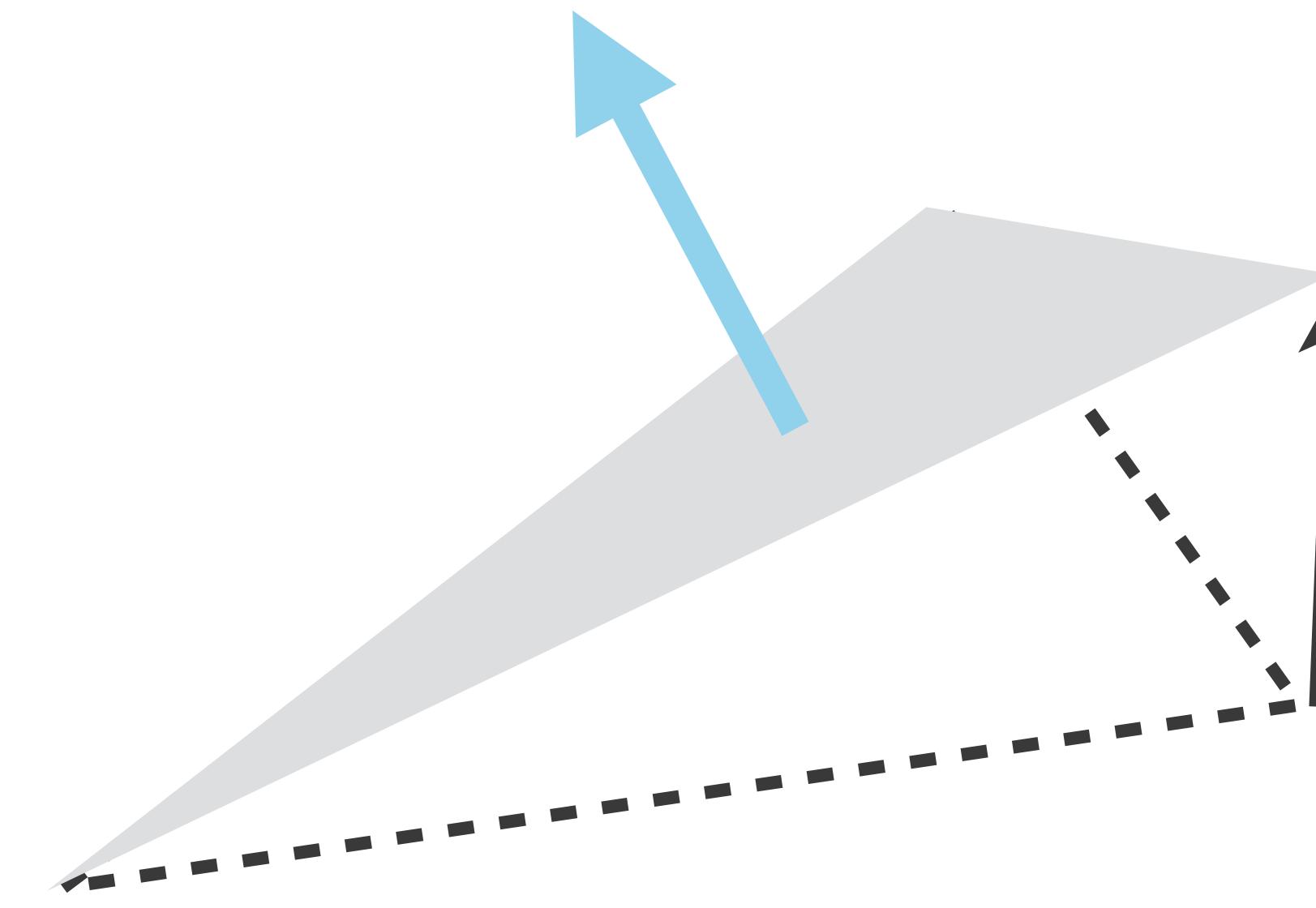
# Orientation Component



# Rendering a Geometry

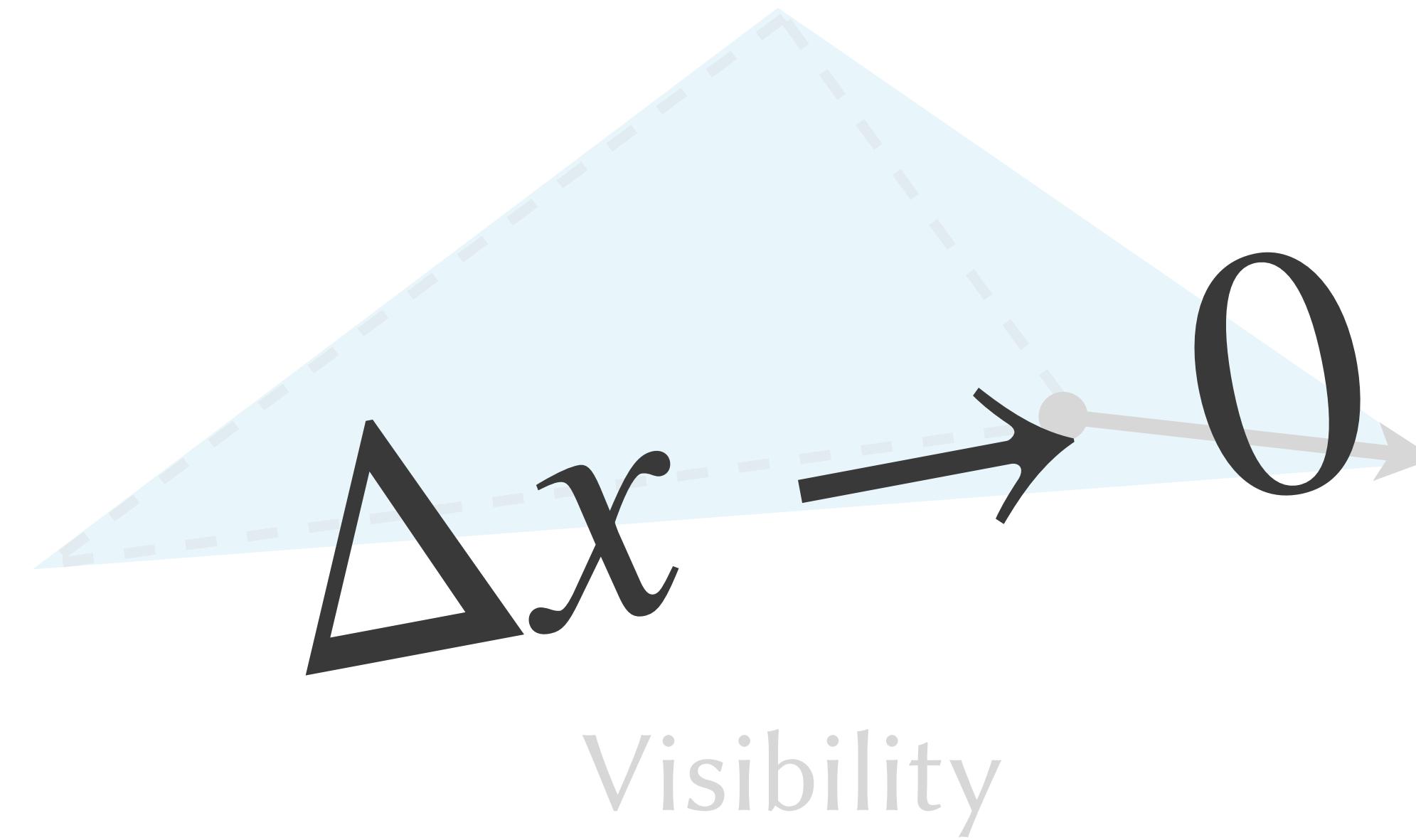


Visibility

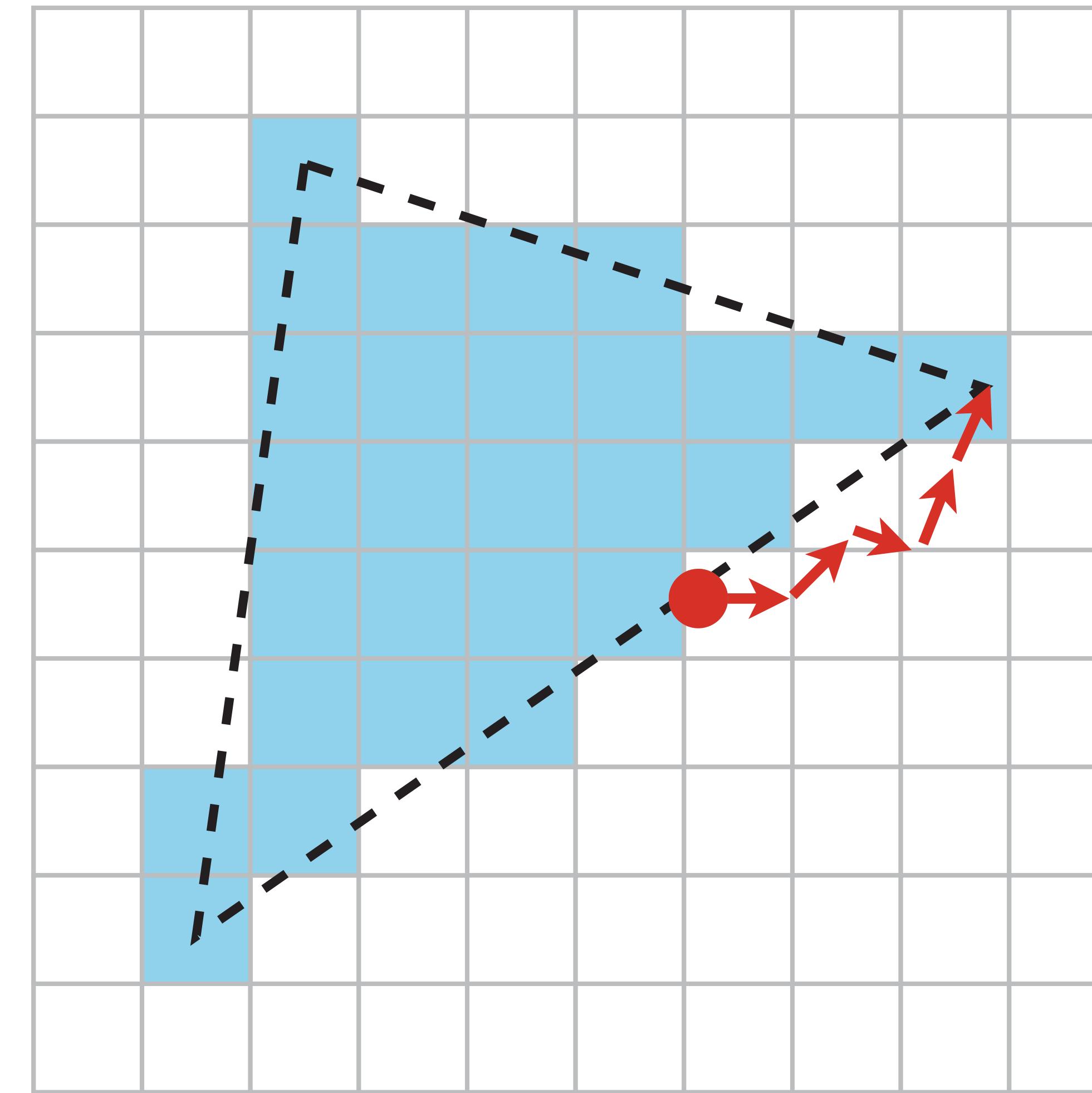


Orientation

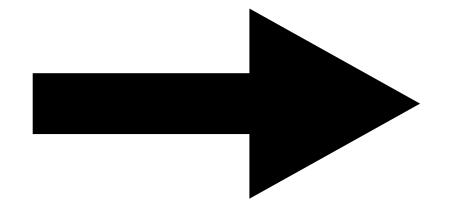
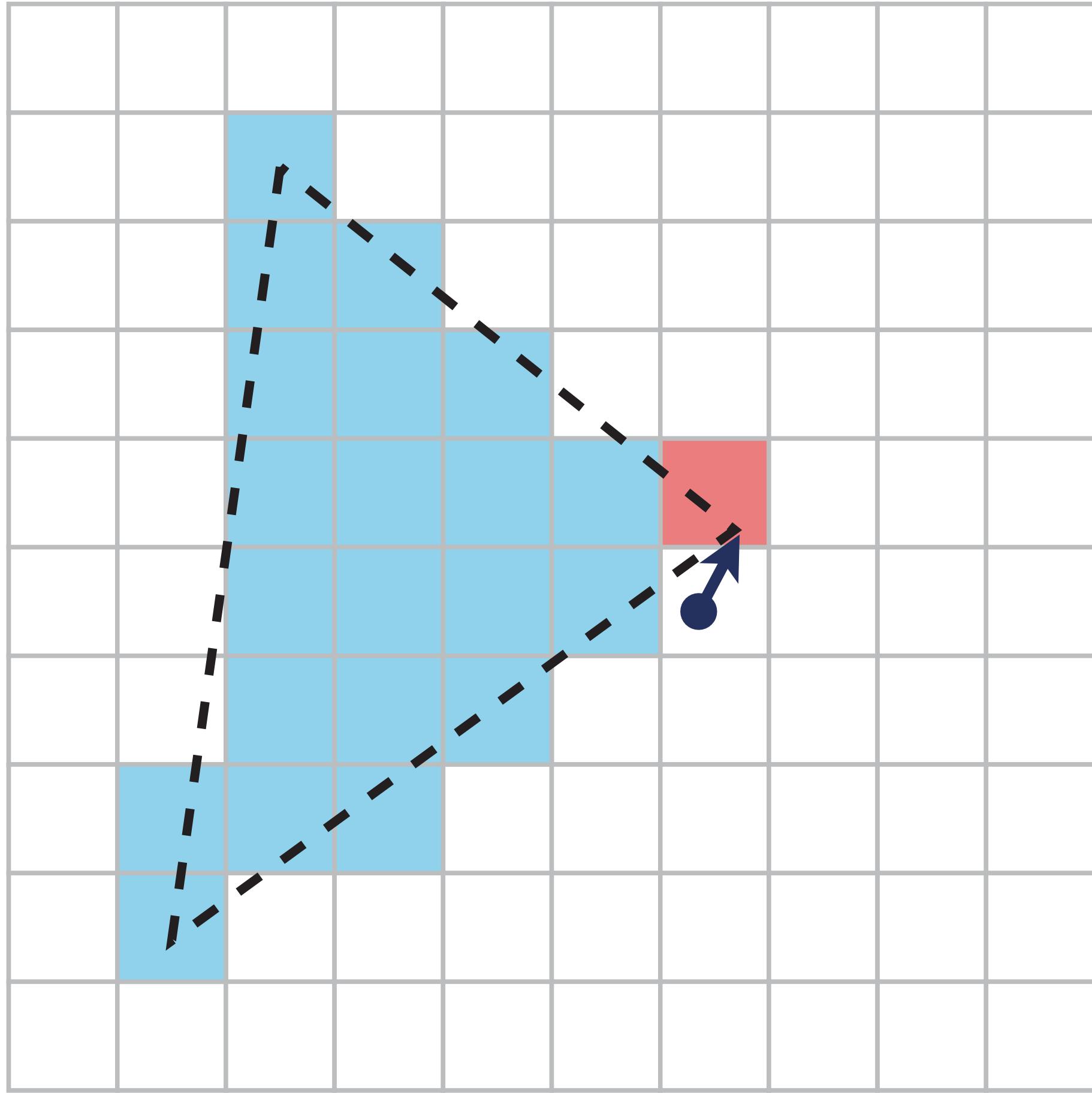
# Rendering a Geometry



# Visibility Change After Many Steps



# Update Visibility

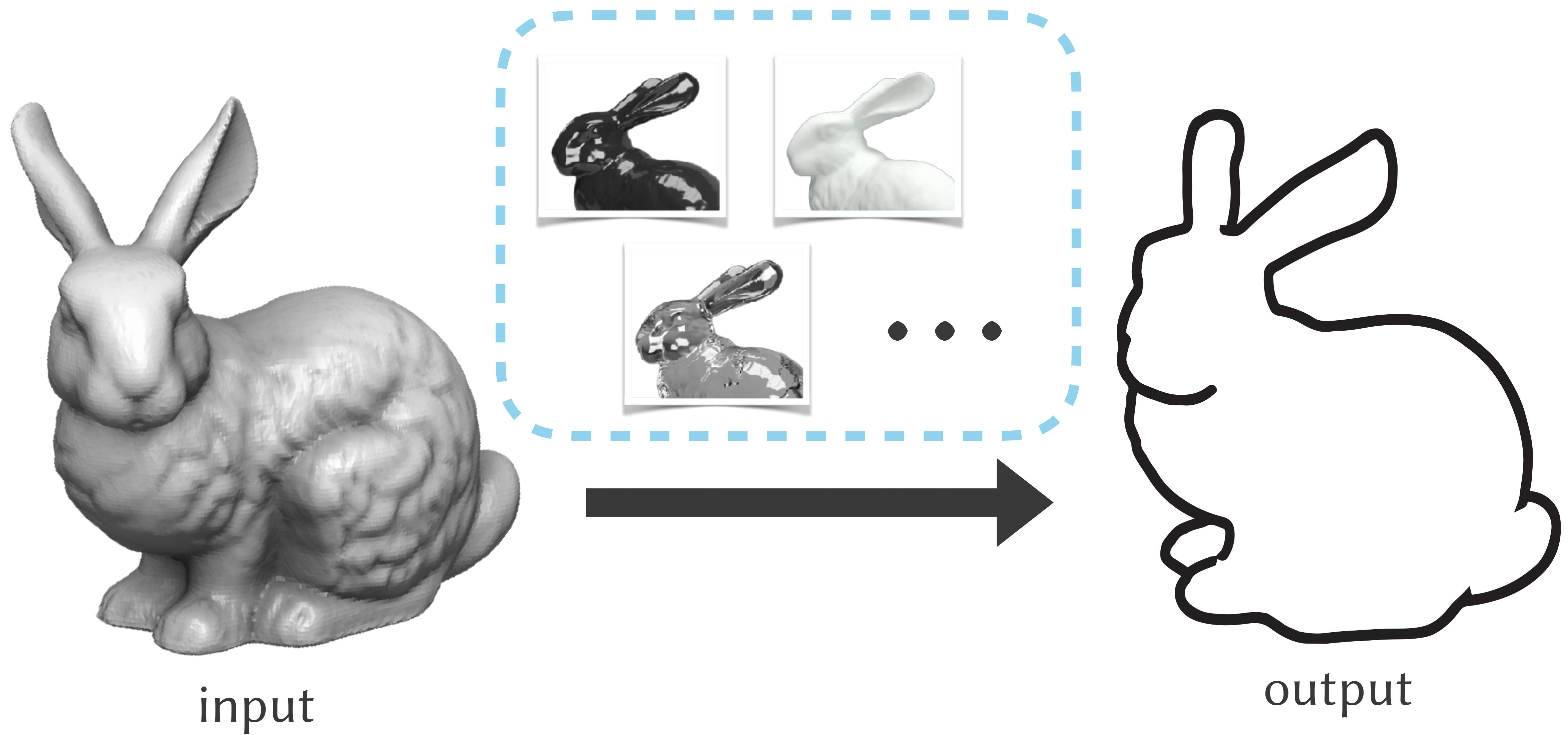


$$\frac{\partial R}{\partial V} = \frac{\partial R}{\partial N} \frac{\partial N}{\partial V}$$

# PAPARAZZI DIFFERENTIABLE RENDERER

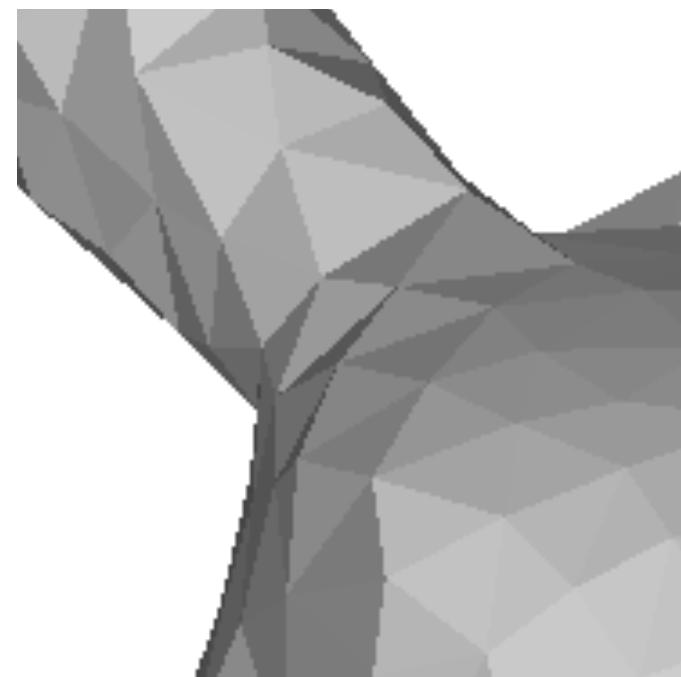


# Rendering Quality Means To An End

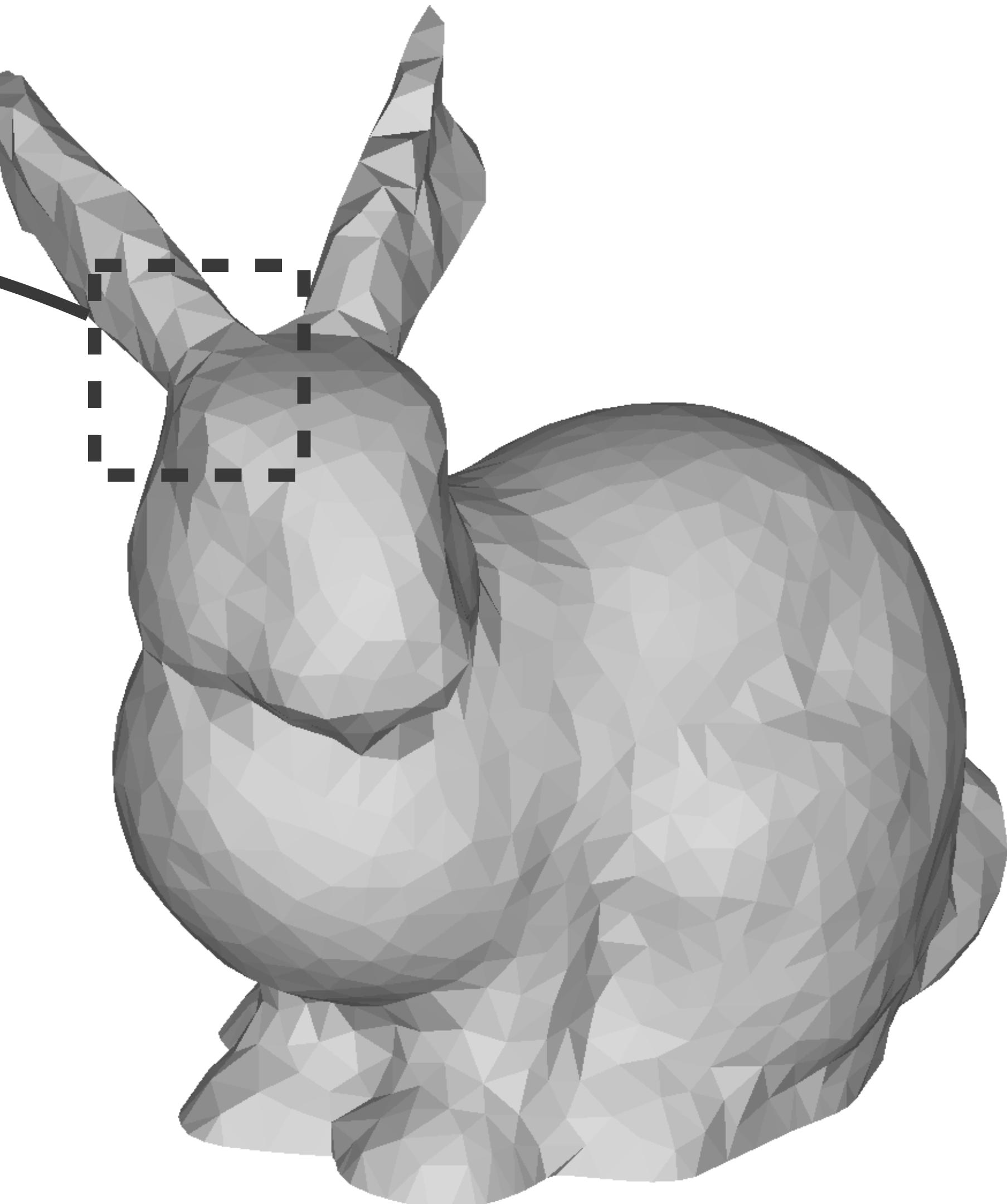
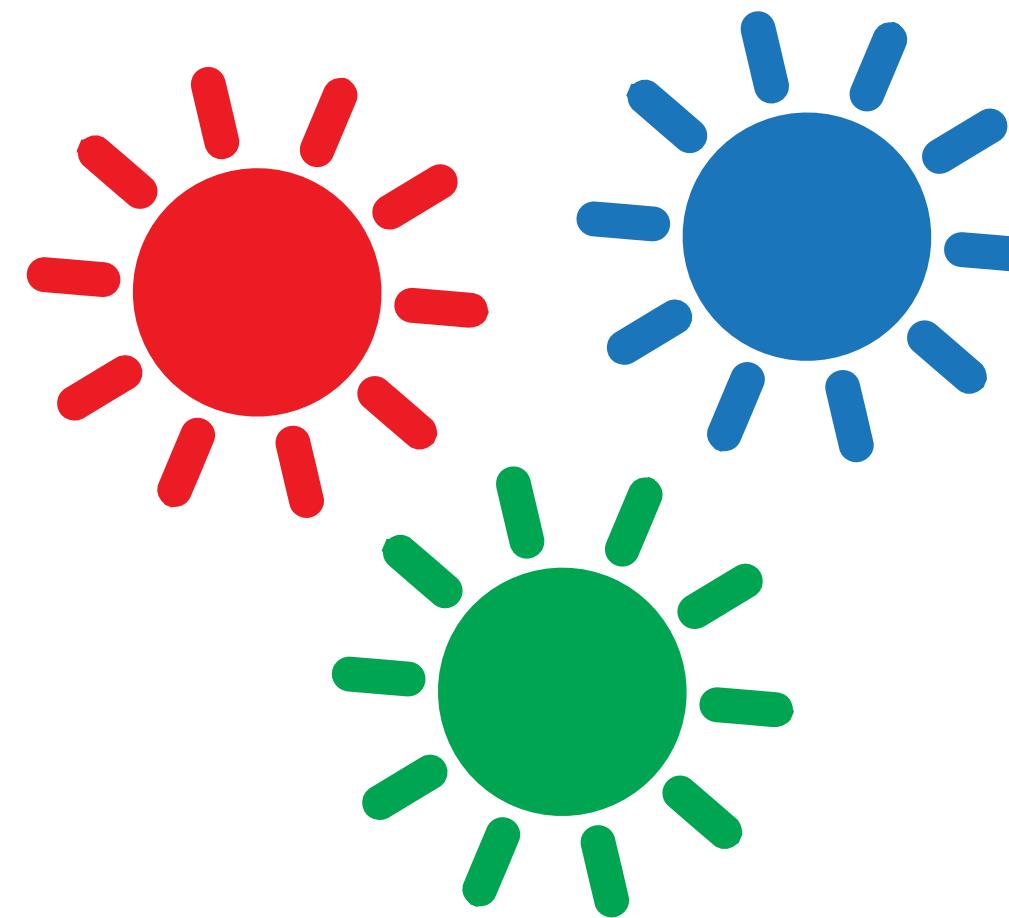


# Paparazzi Renderer

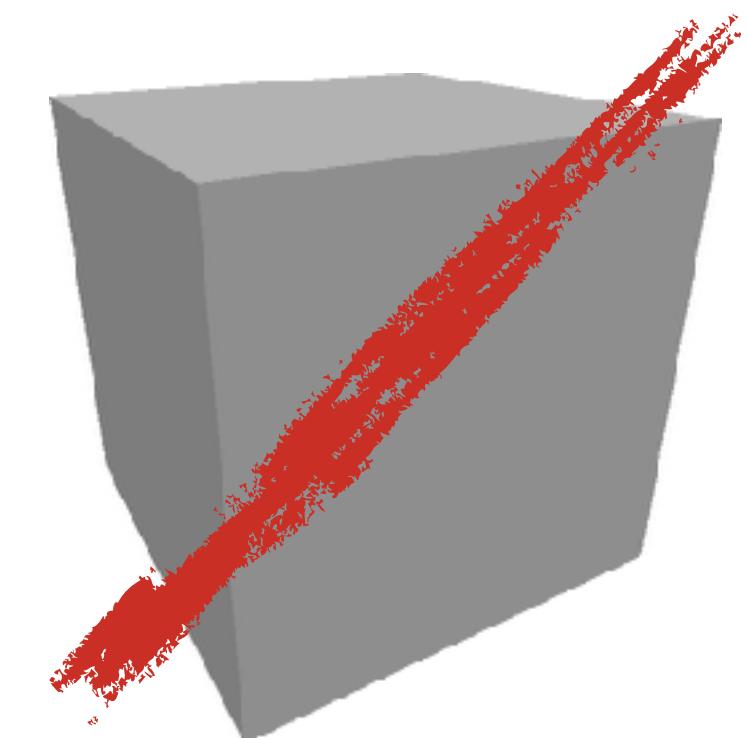
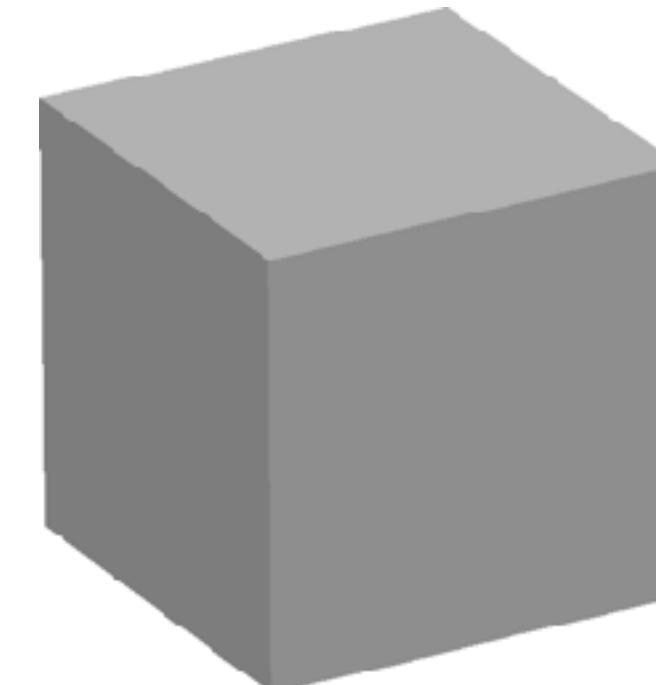
Flat shading



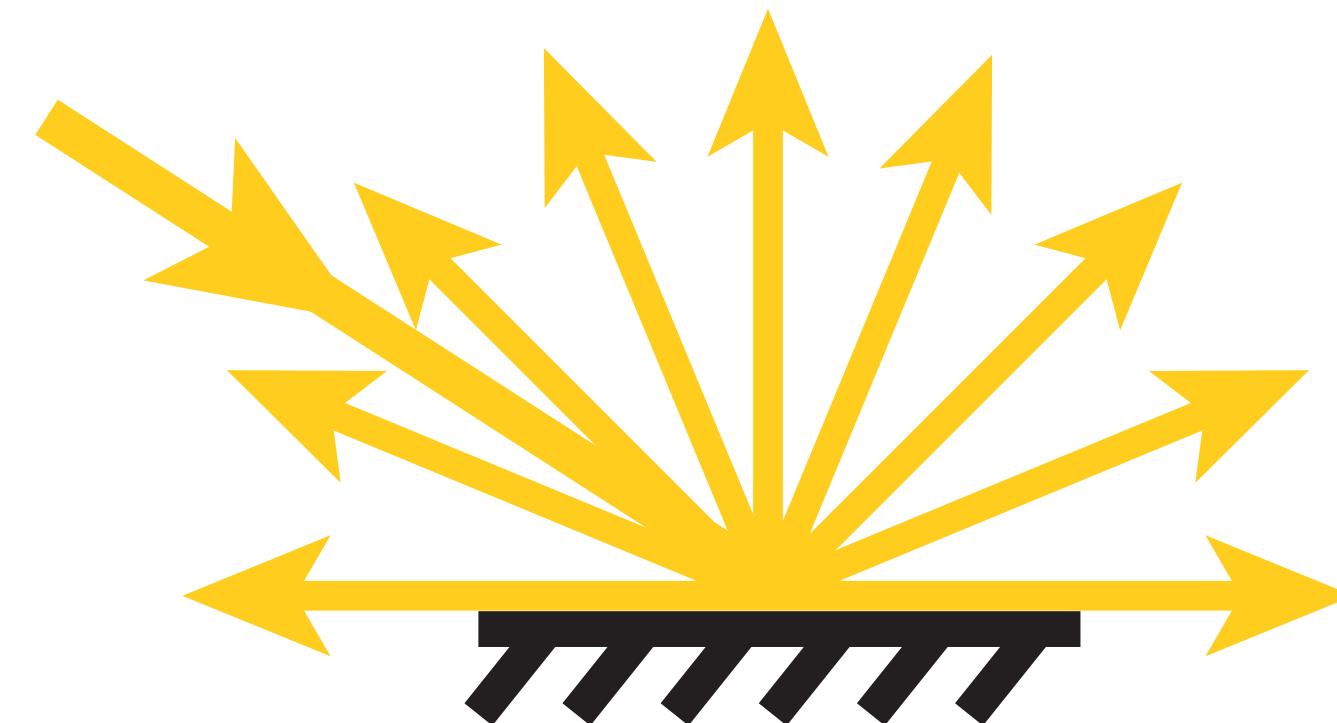
directional lights



orthographic projection

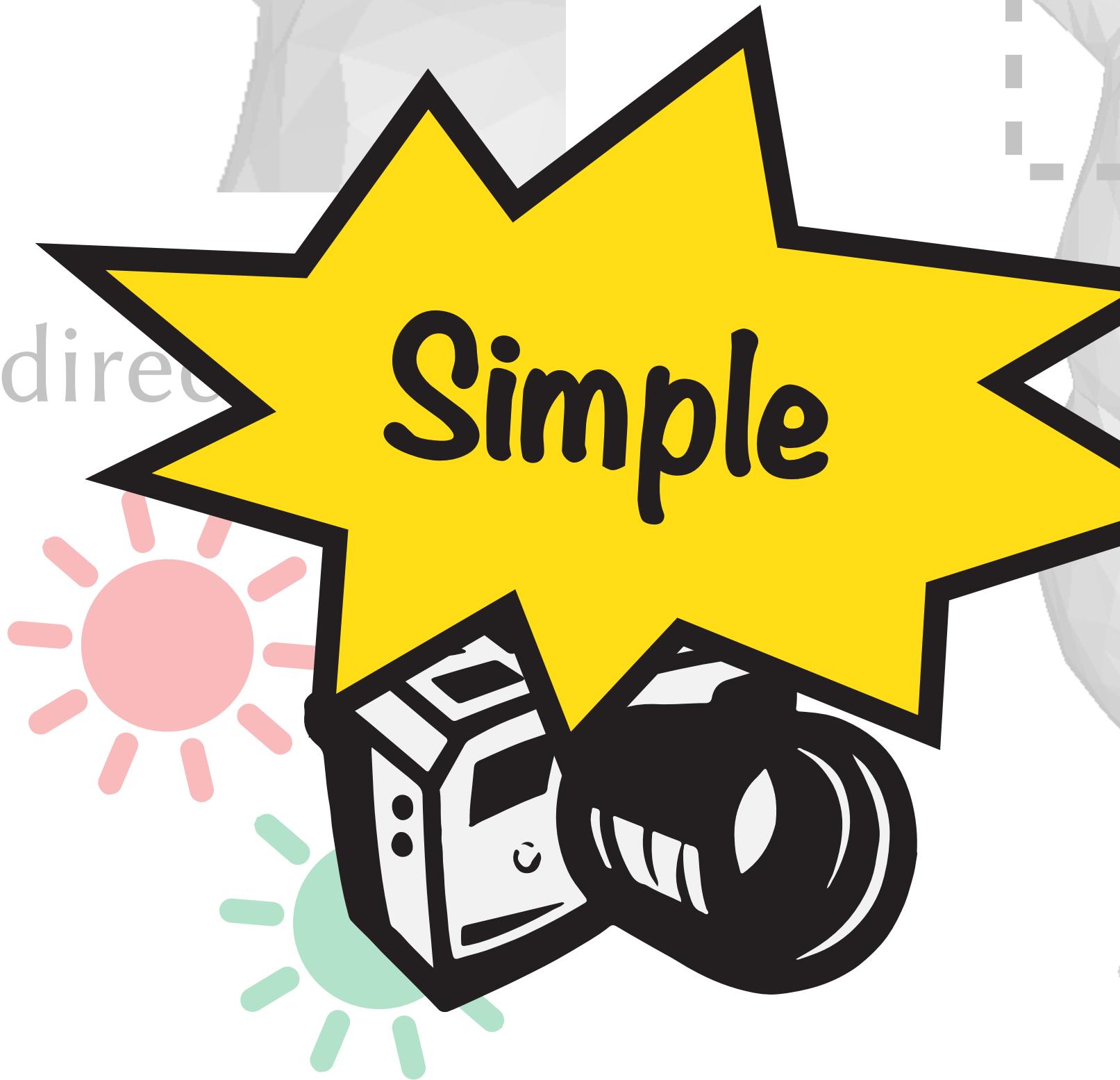


Lambertian material



# Paparazzi Renderer

Flat shading

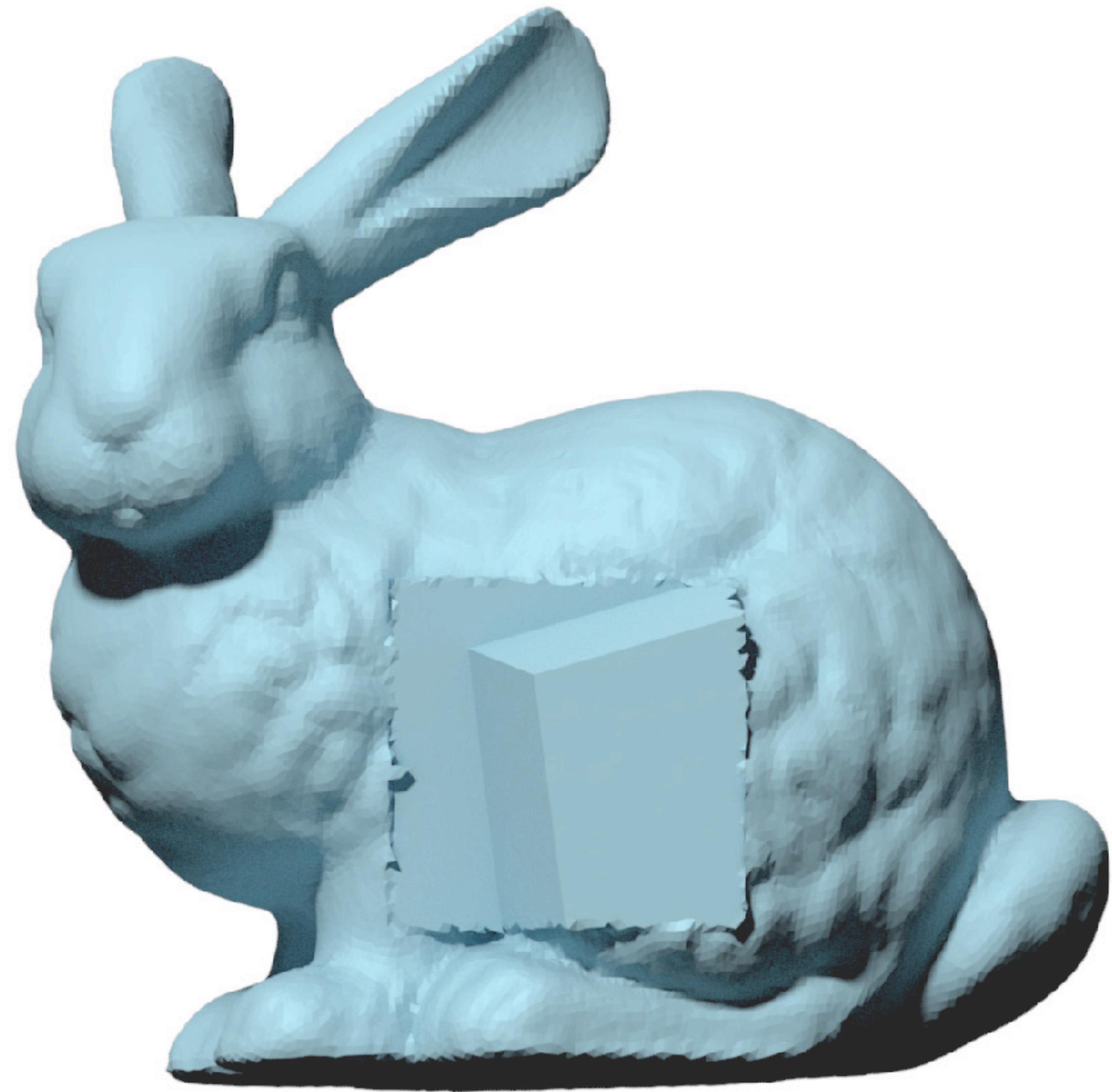


orthographic projection



Differentiable

# Single-View



# Multi-view Generalization

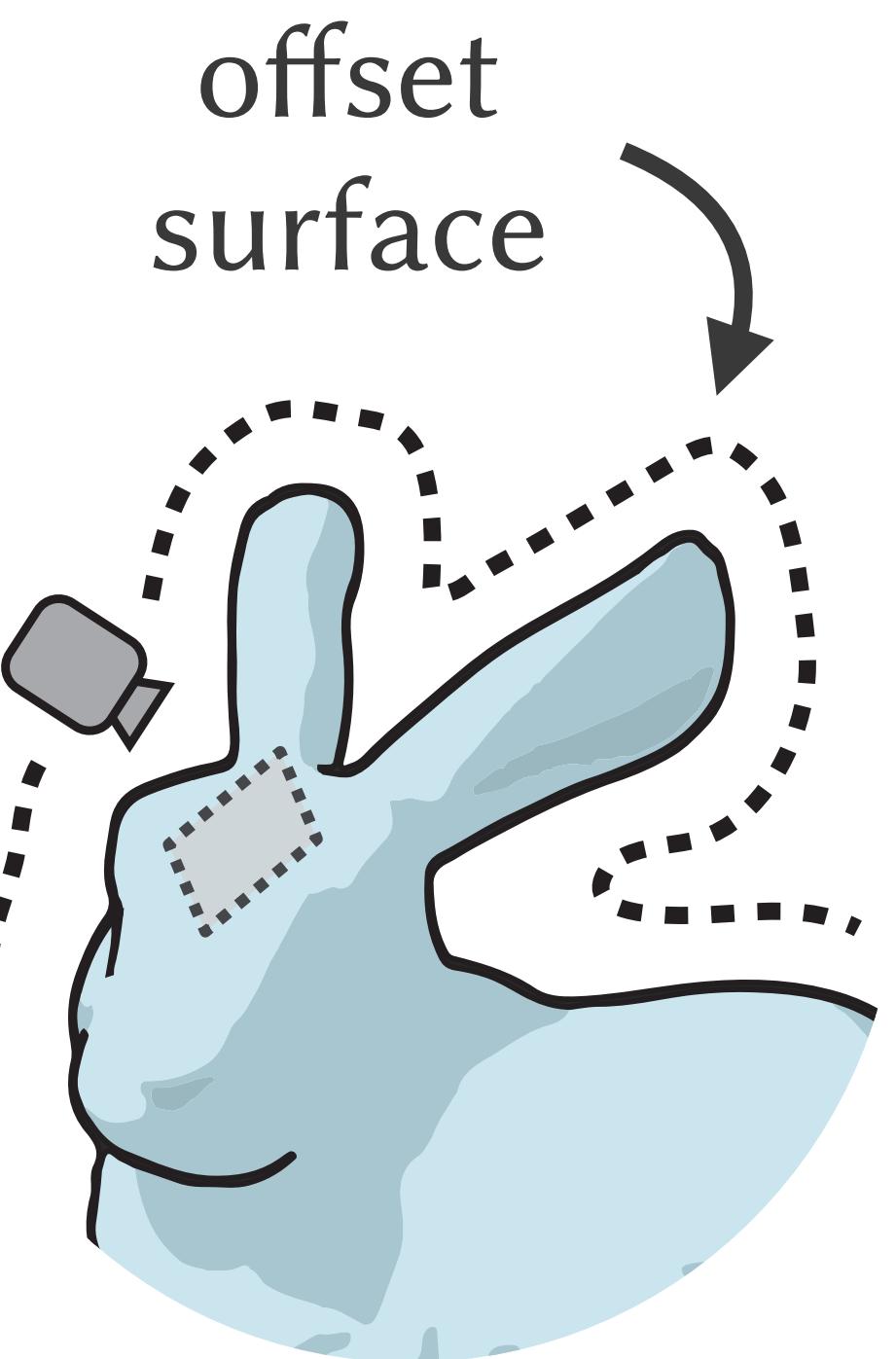
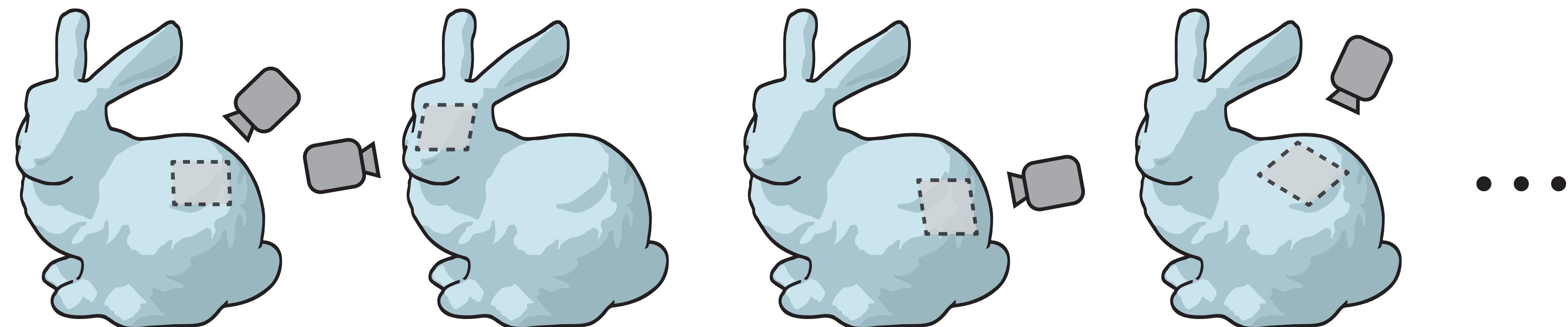
Multi-view energy:

$$V^* \leftarrow \arg \min_V \int_{\text{bag}} E(R_{\text{bag}}(V))$$

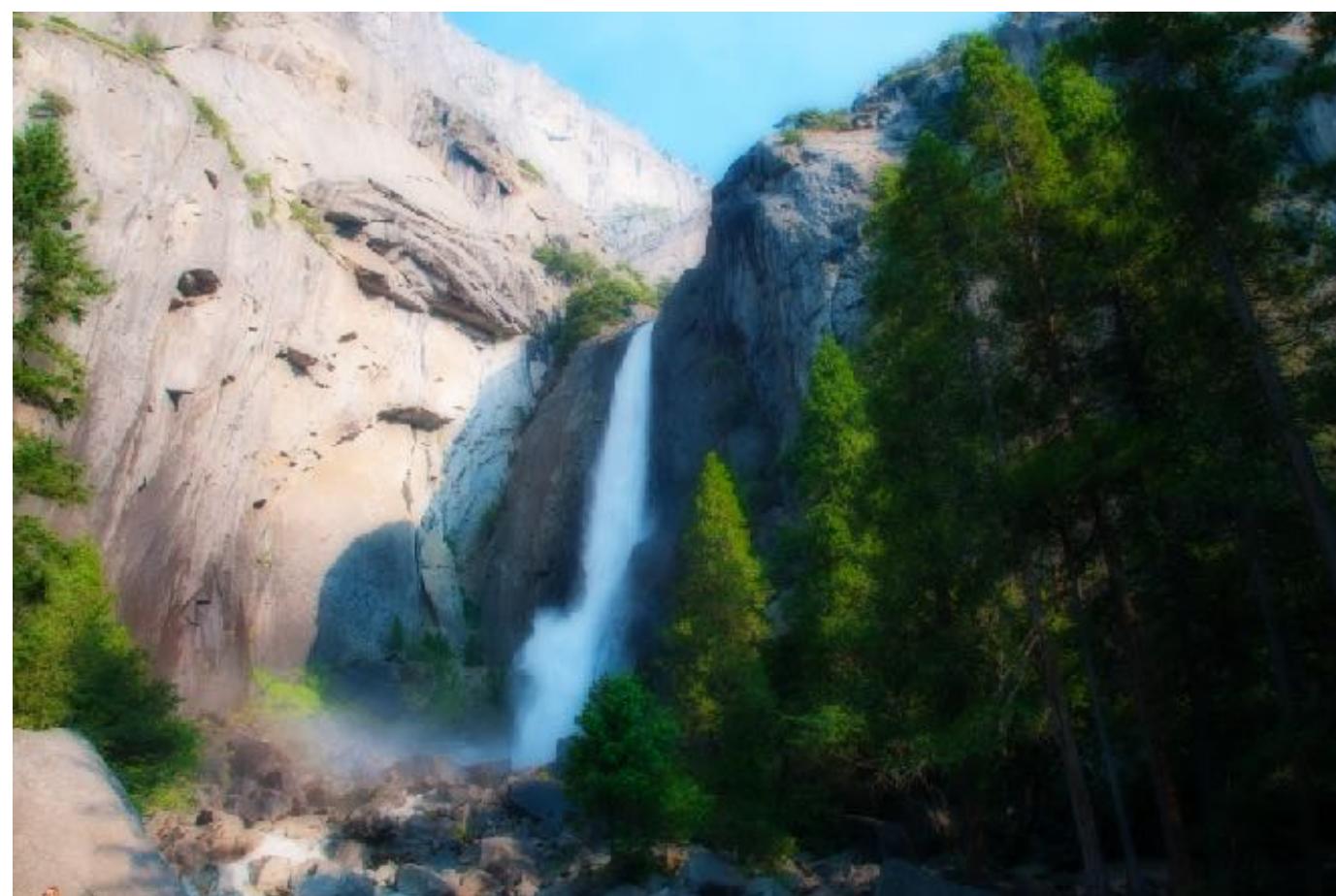
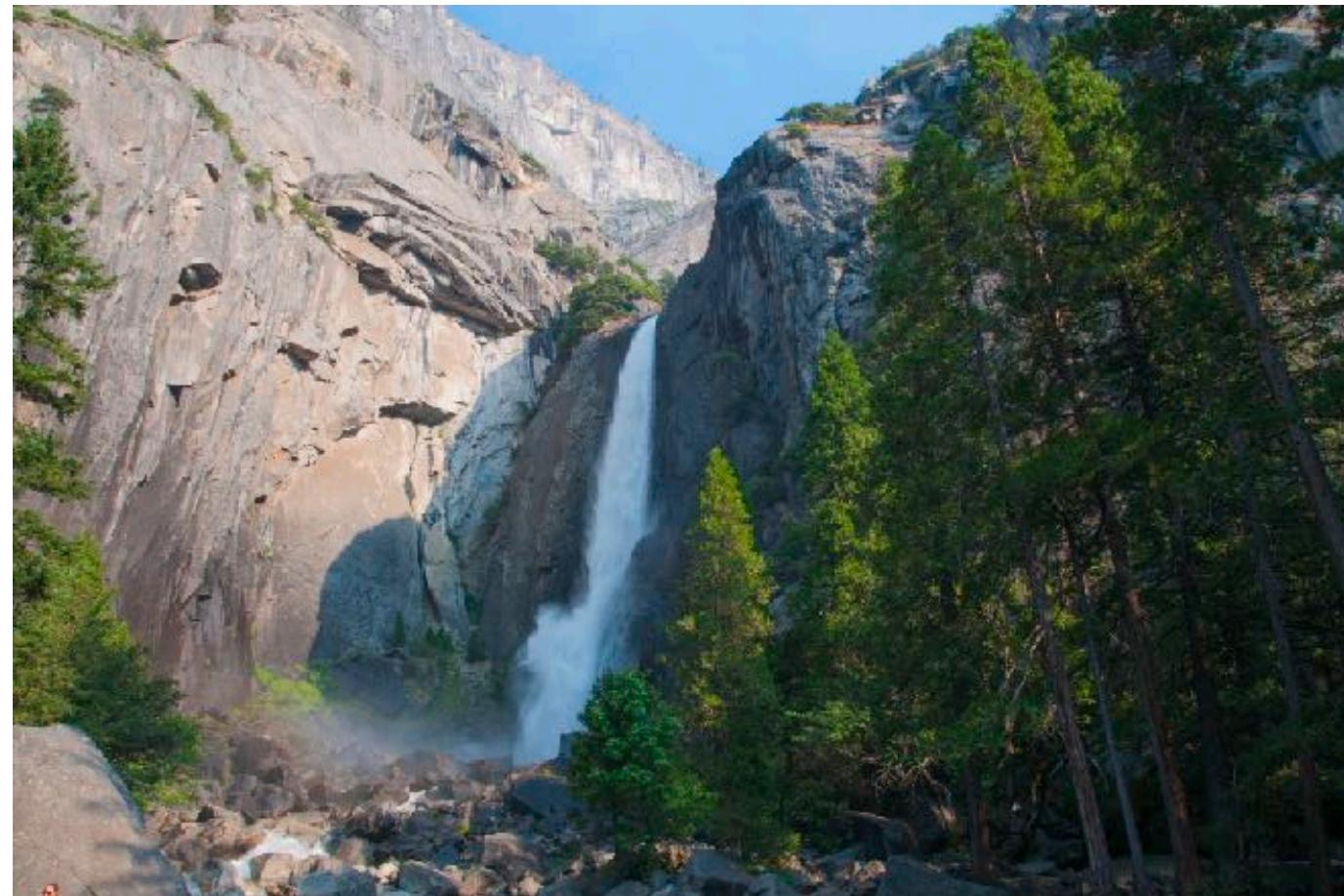
Gradient descent optimization:

$$V \leftarrow V - \gamma \int_{\text{bag}} \frac{\partial E}{\partial R_{\text{bag}}} \frac{\partial R_{\text{bag}}}{\partial V}$$

Stochastic gradient descent



# From Energy to Filter



$$V \leftarrow V - \gamma \int_{\text{bag}} \frac{\partial E}{\partial R_{\text{bag}}} \frac{\partial R_{\text{bag}}}{\partial V}$$

$$\Rightarrow V \leftarrow V - \gamma \int_{\text{bag}} \Delta R_{\text{bag}} \frac{\partial R_{\text{bag}}}{\partial V}$$

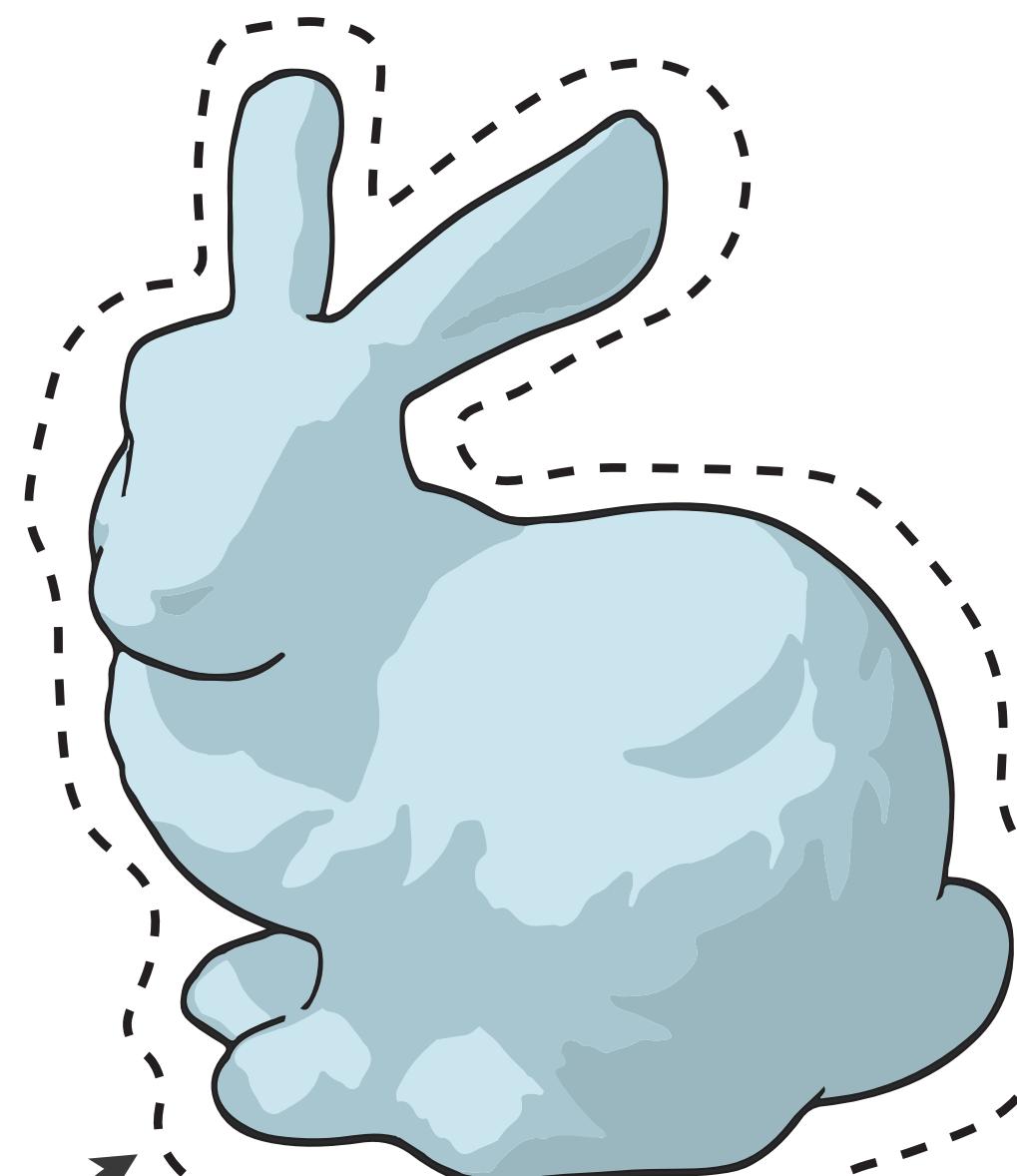
$$\Delta R =$$



filtered image      original image

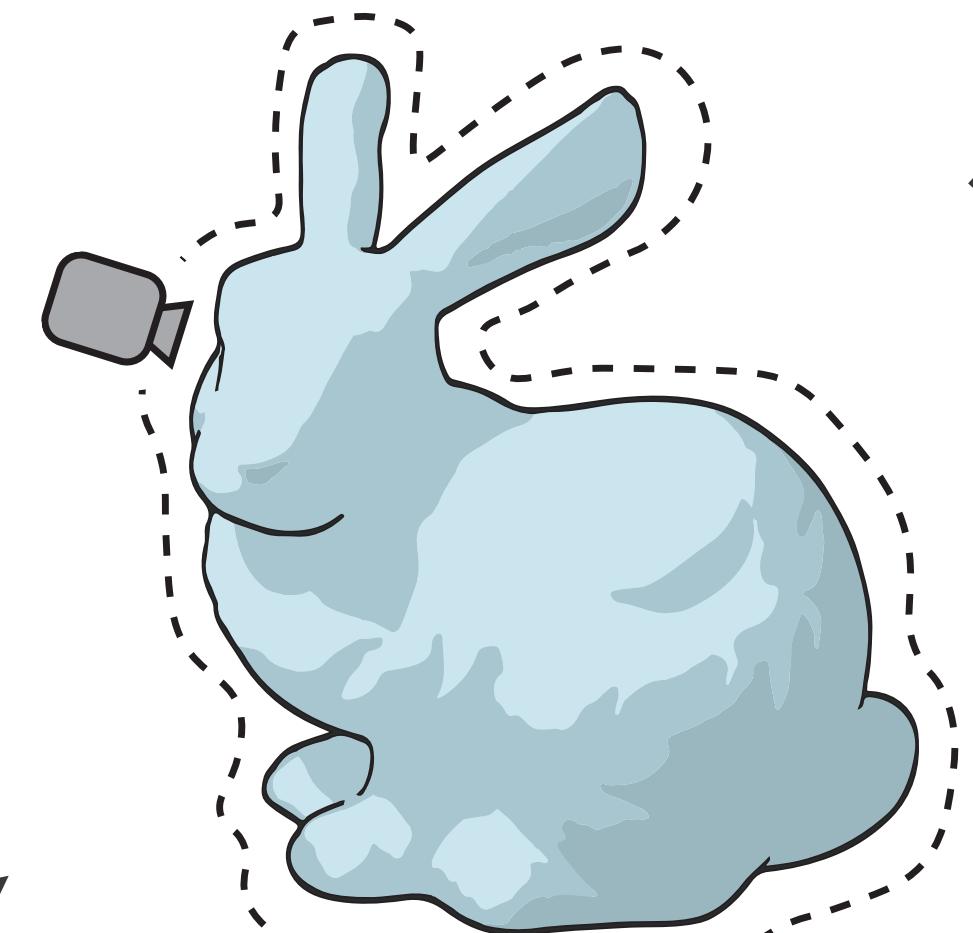
# Recap

input 3D shape  $V$

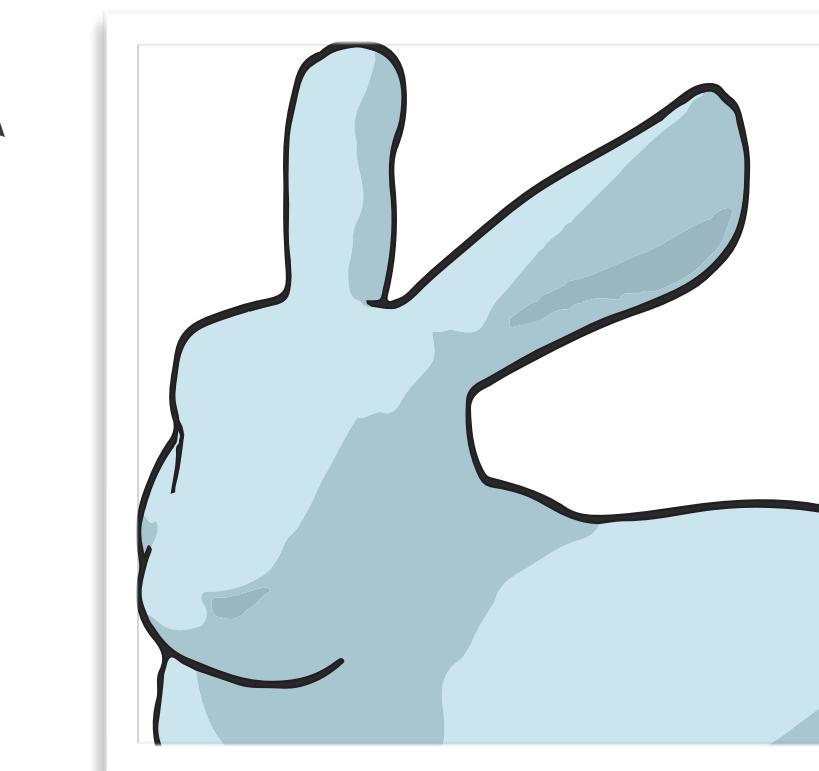


compute offset

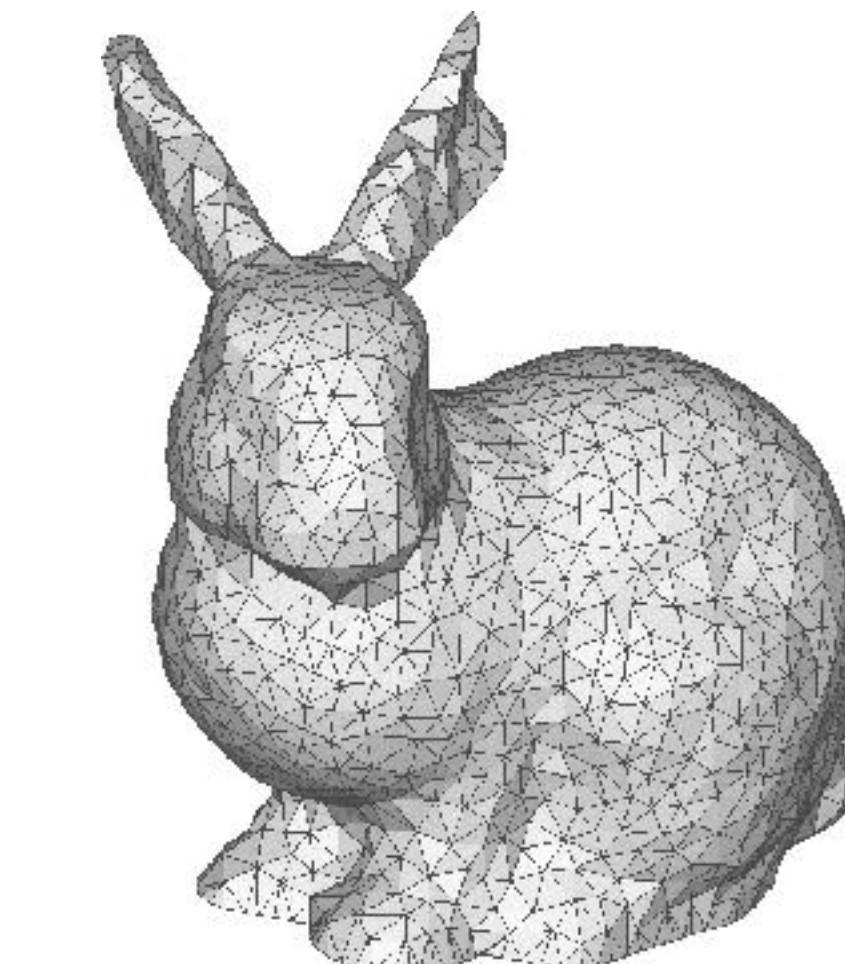
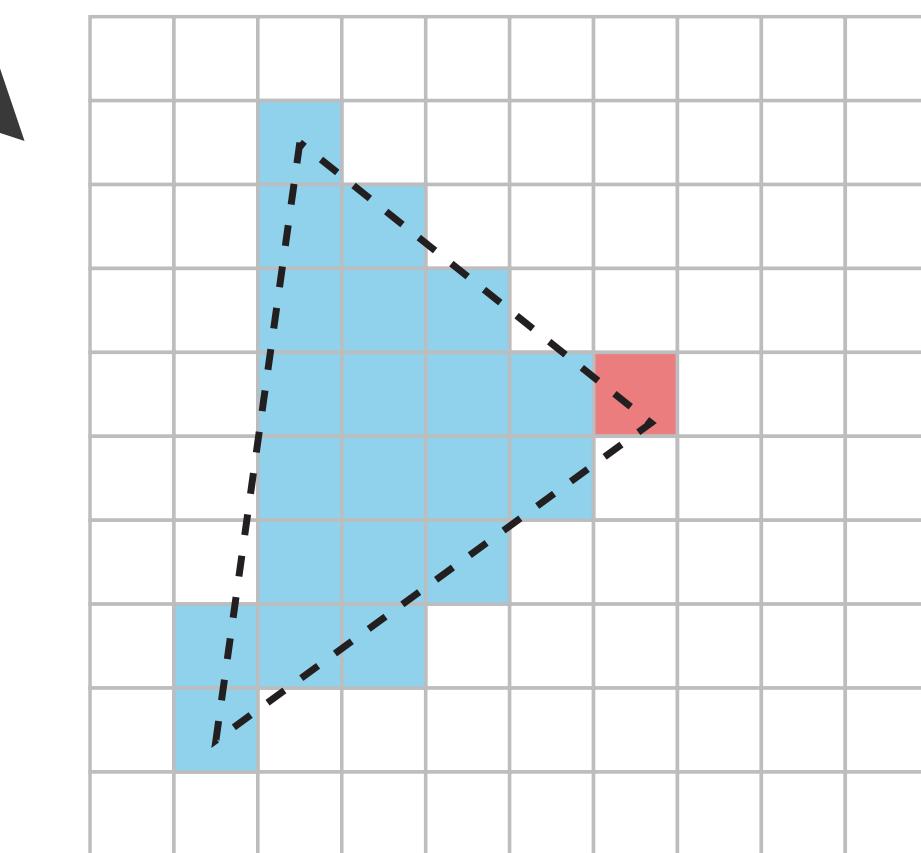
sample a camera  $i$



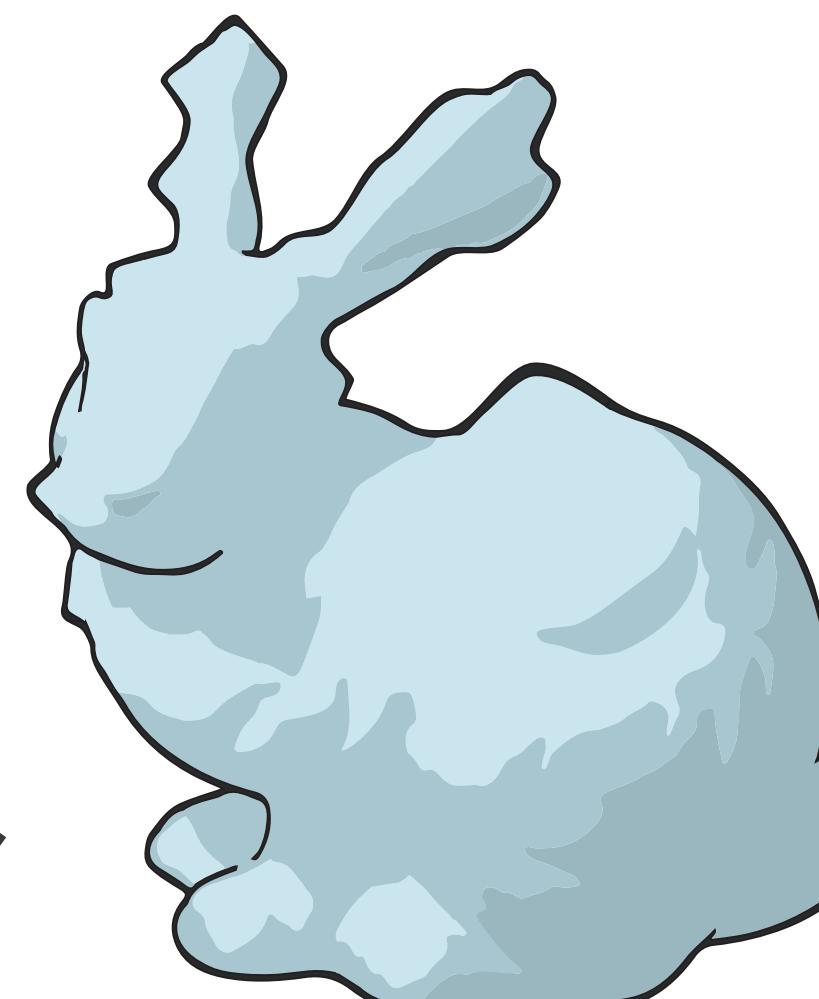
render image  $R_i(V)$



compute visibility



(remeshing)



transfer to 3D

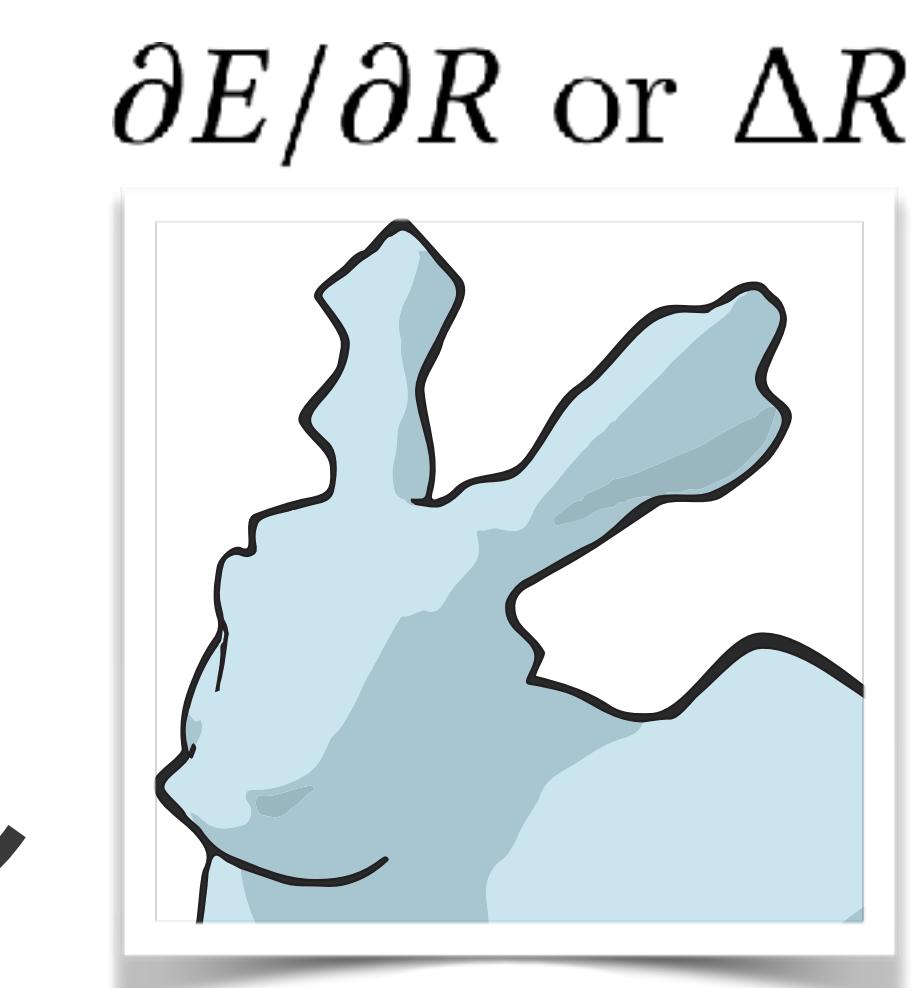
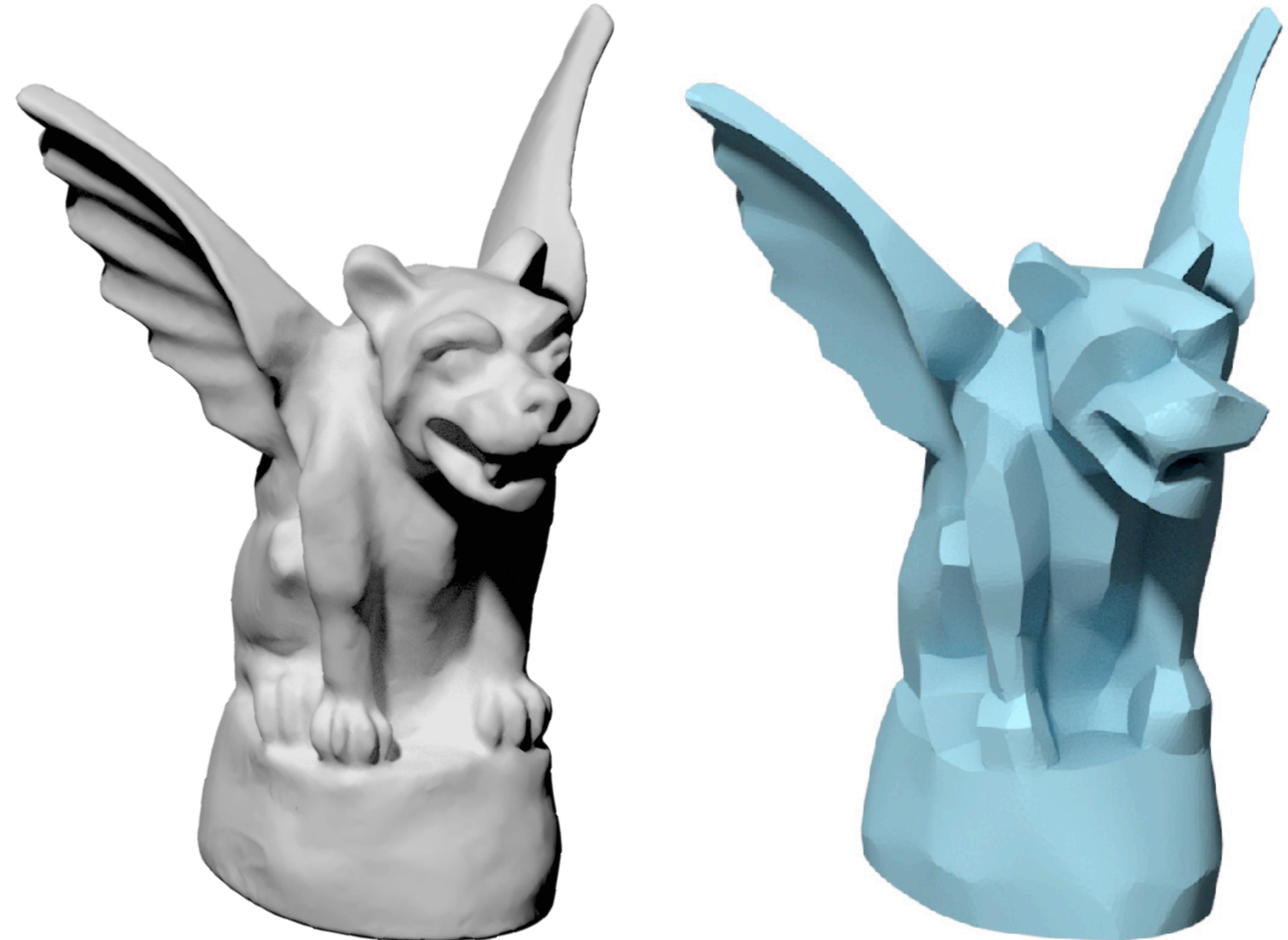
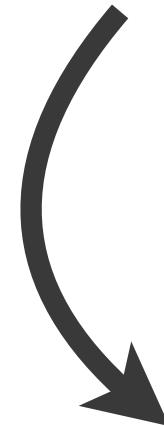


image processing

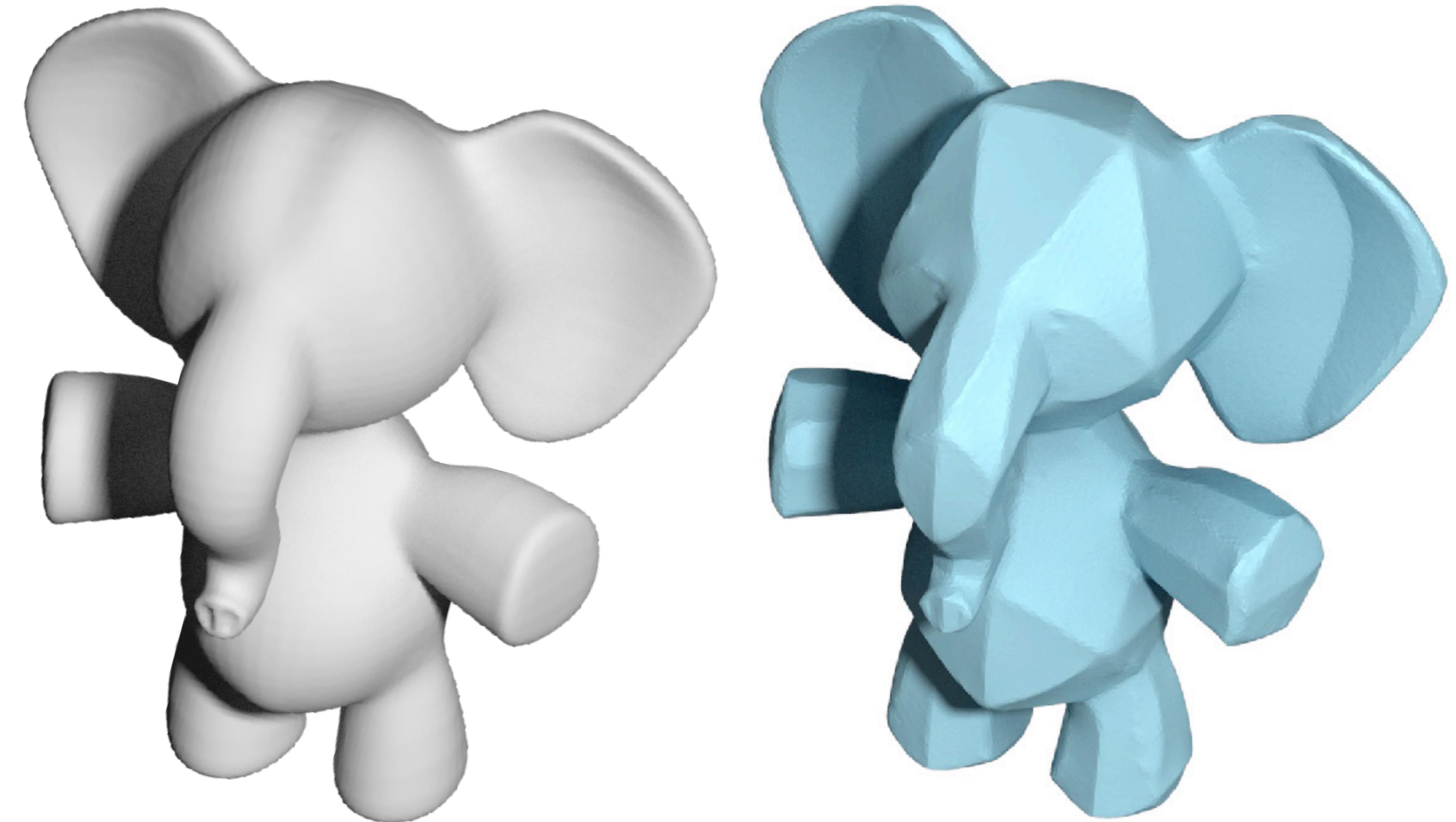
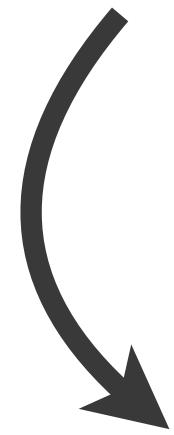
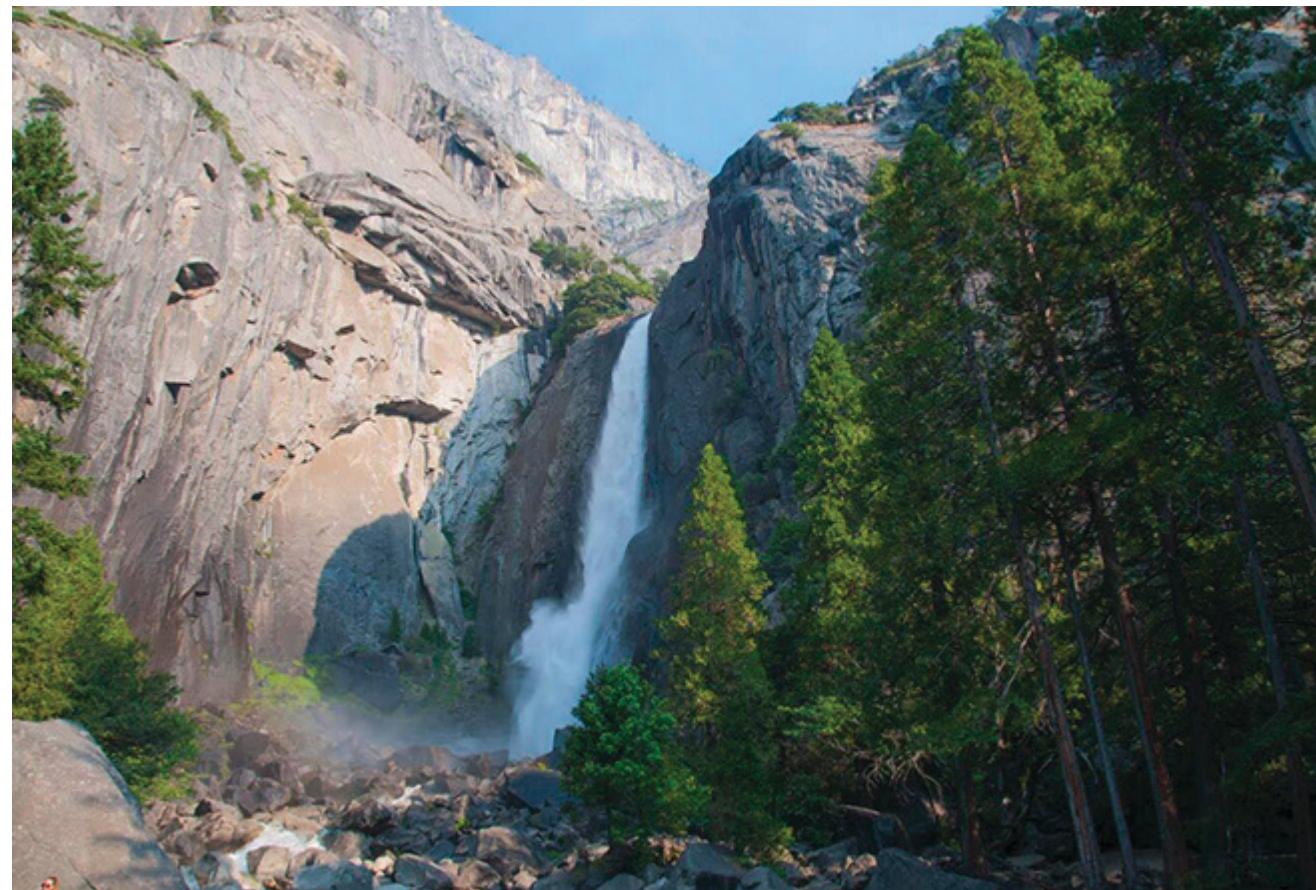
# RESULTS



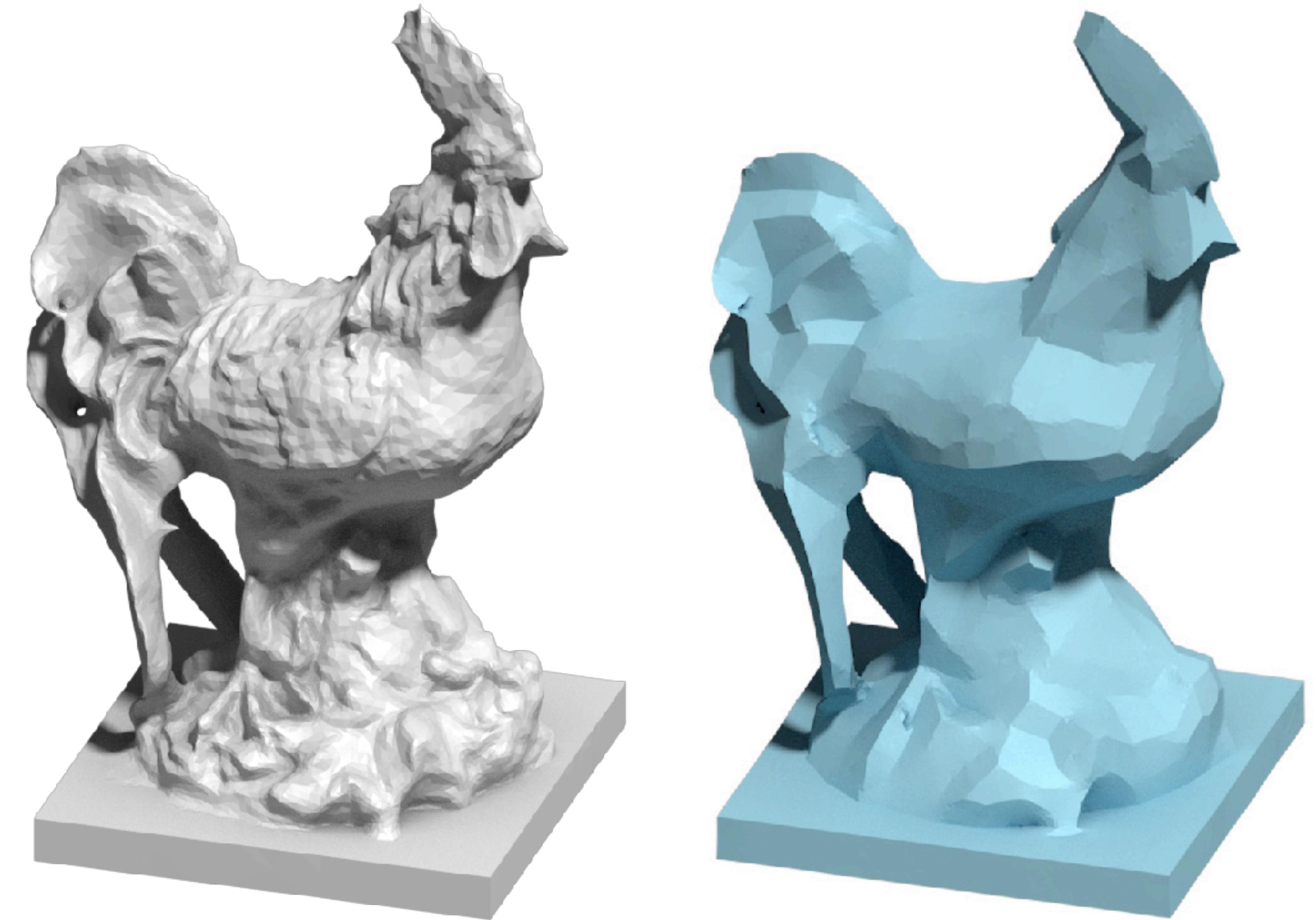
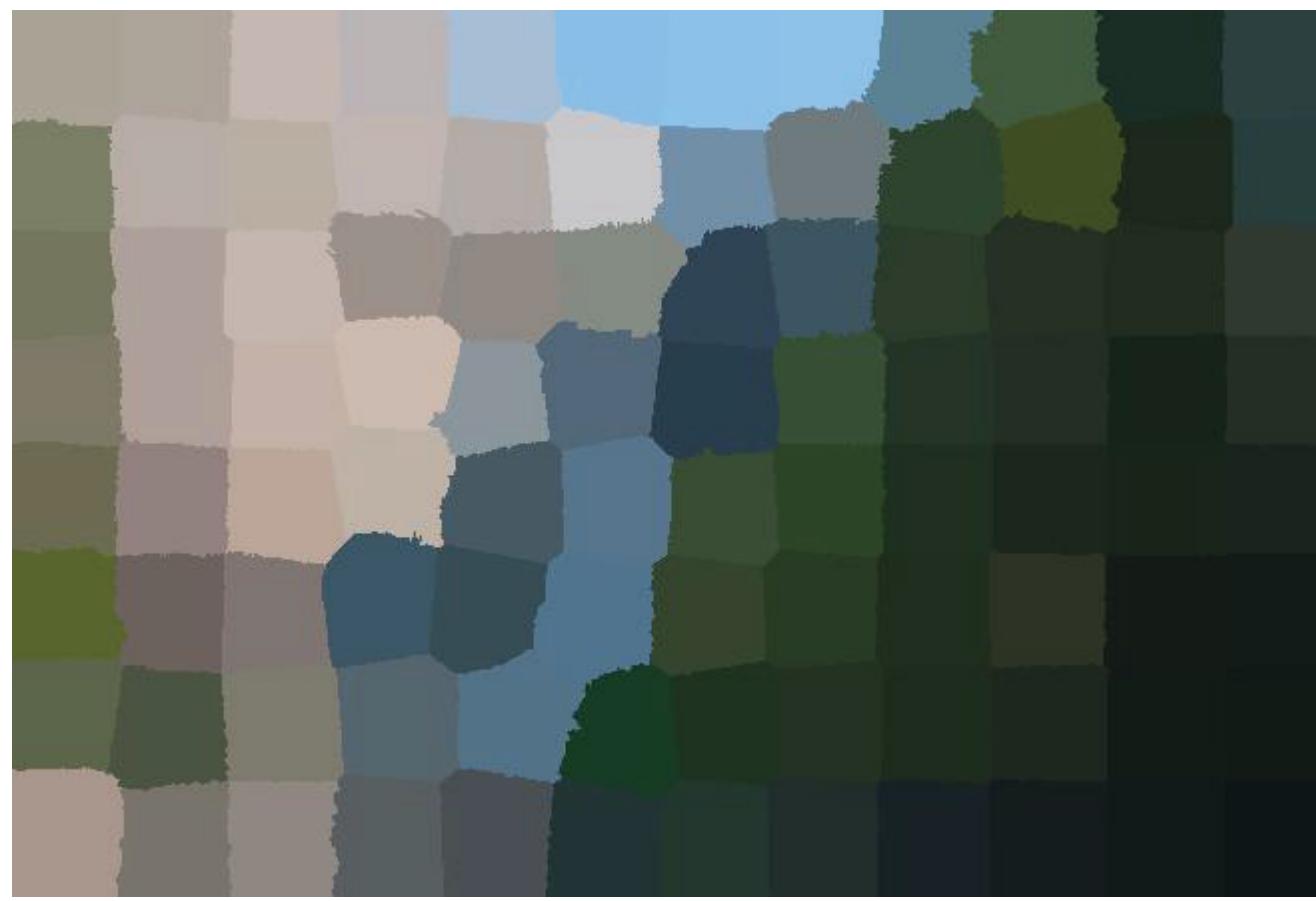
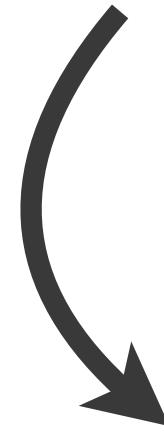
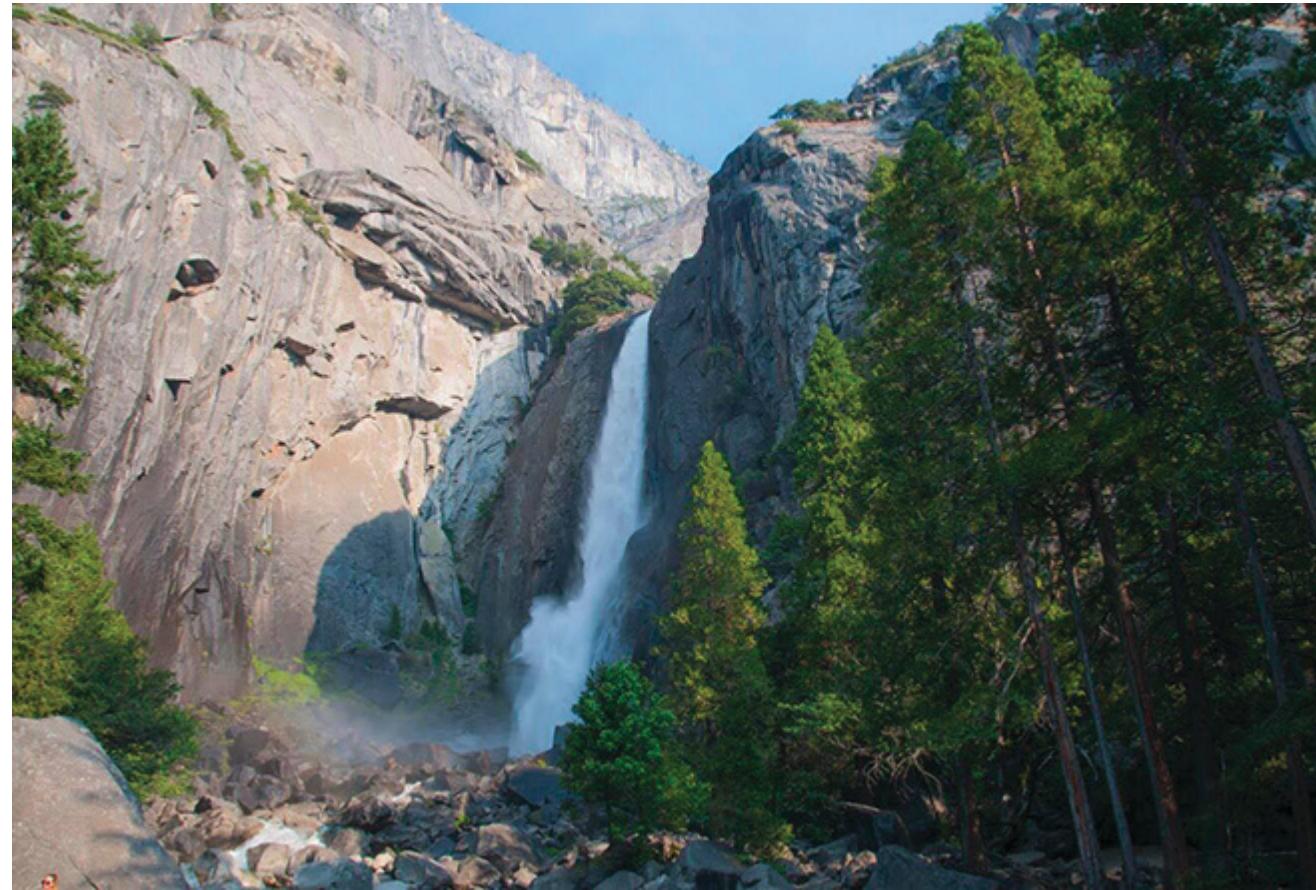
# Fast Guided Filter [He and Sun 2015]



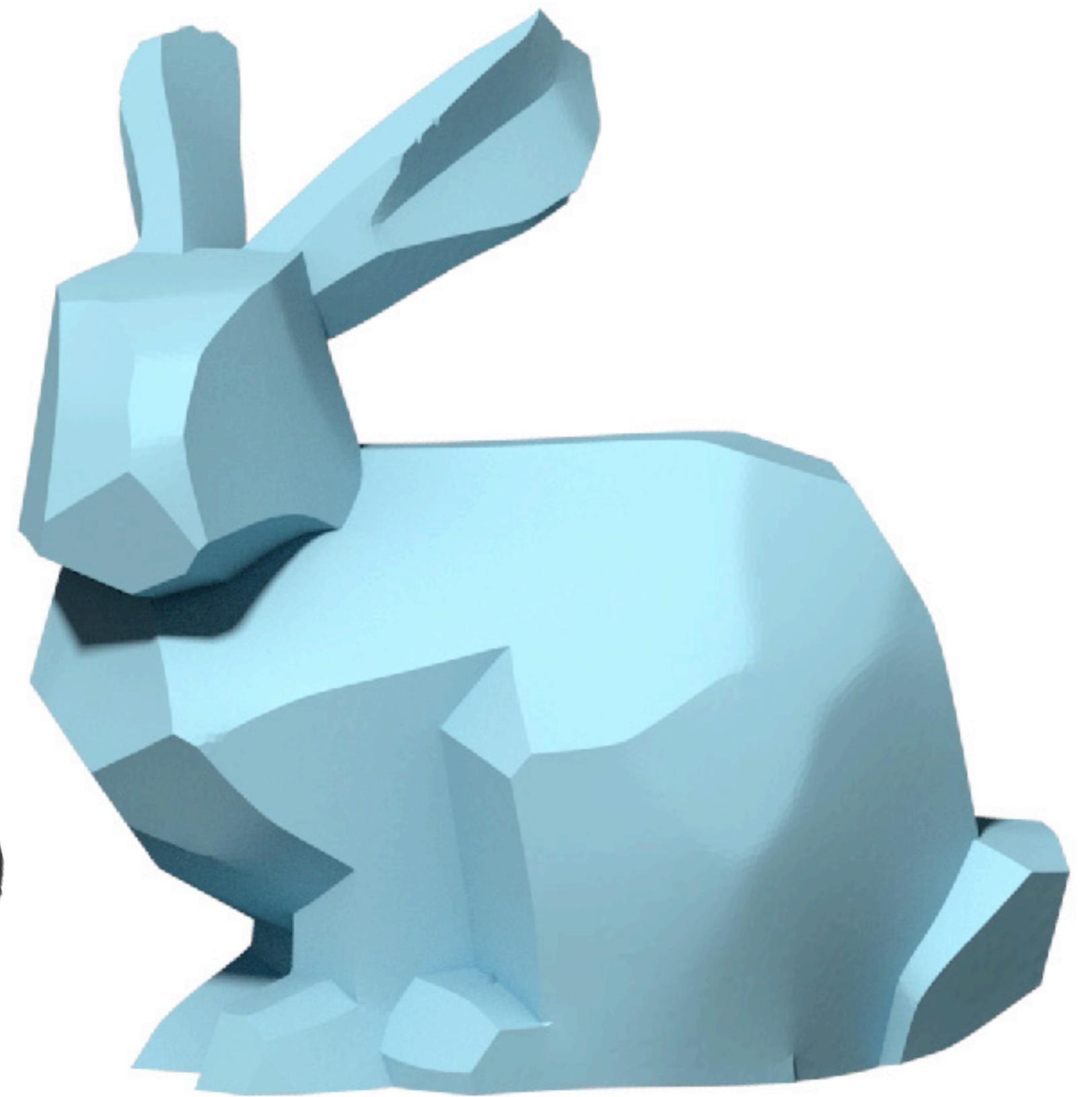
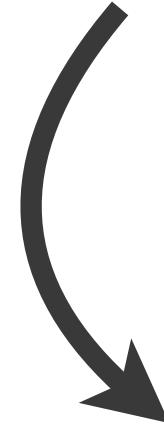
# Quantization [Ozturk et al. 2014]



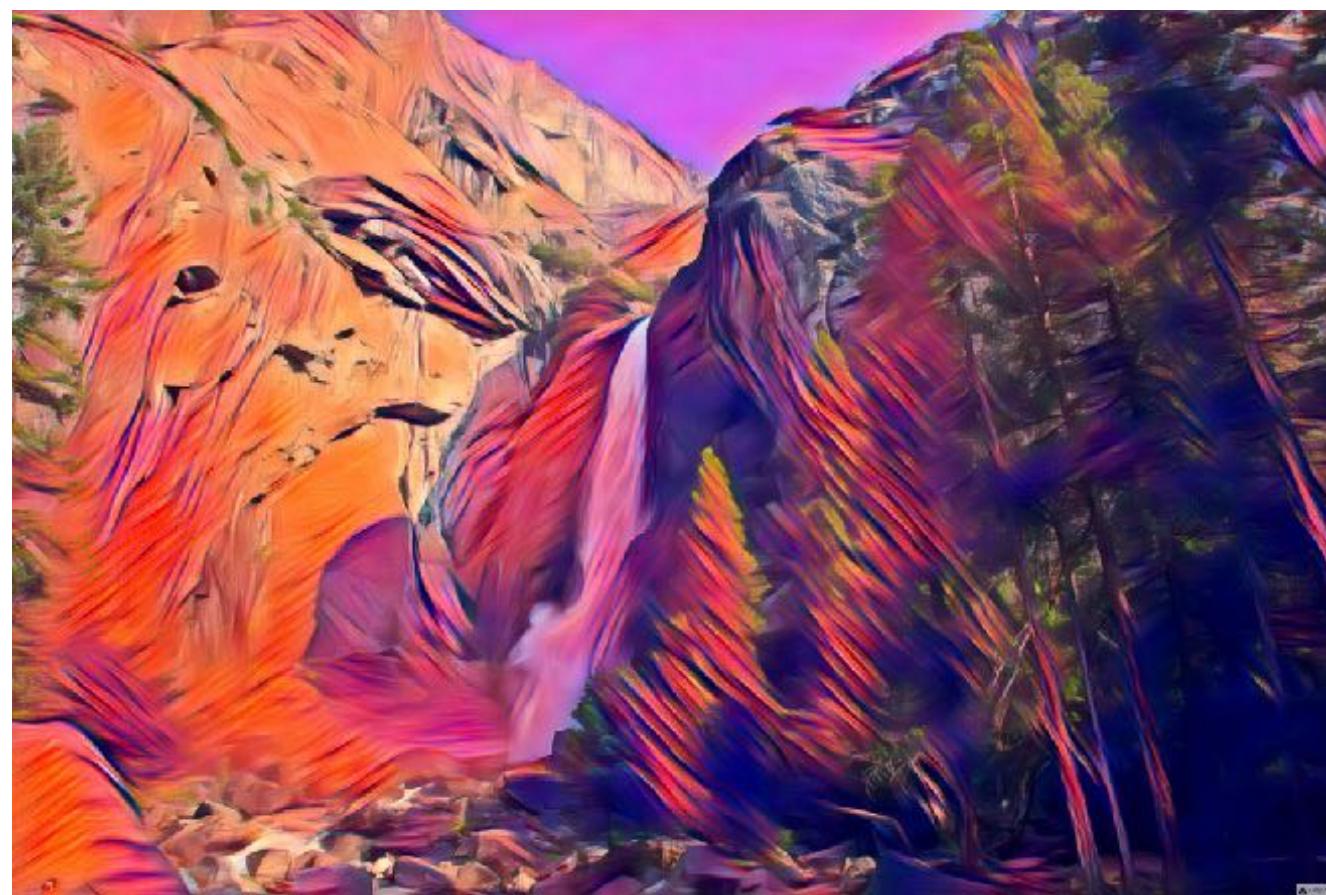
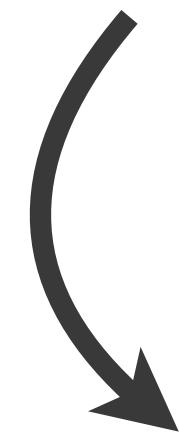
# SLIC Superpixel [Achanta et al. 2012]



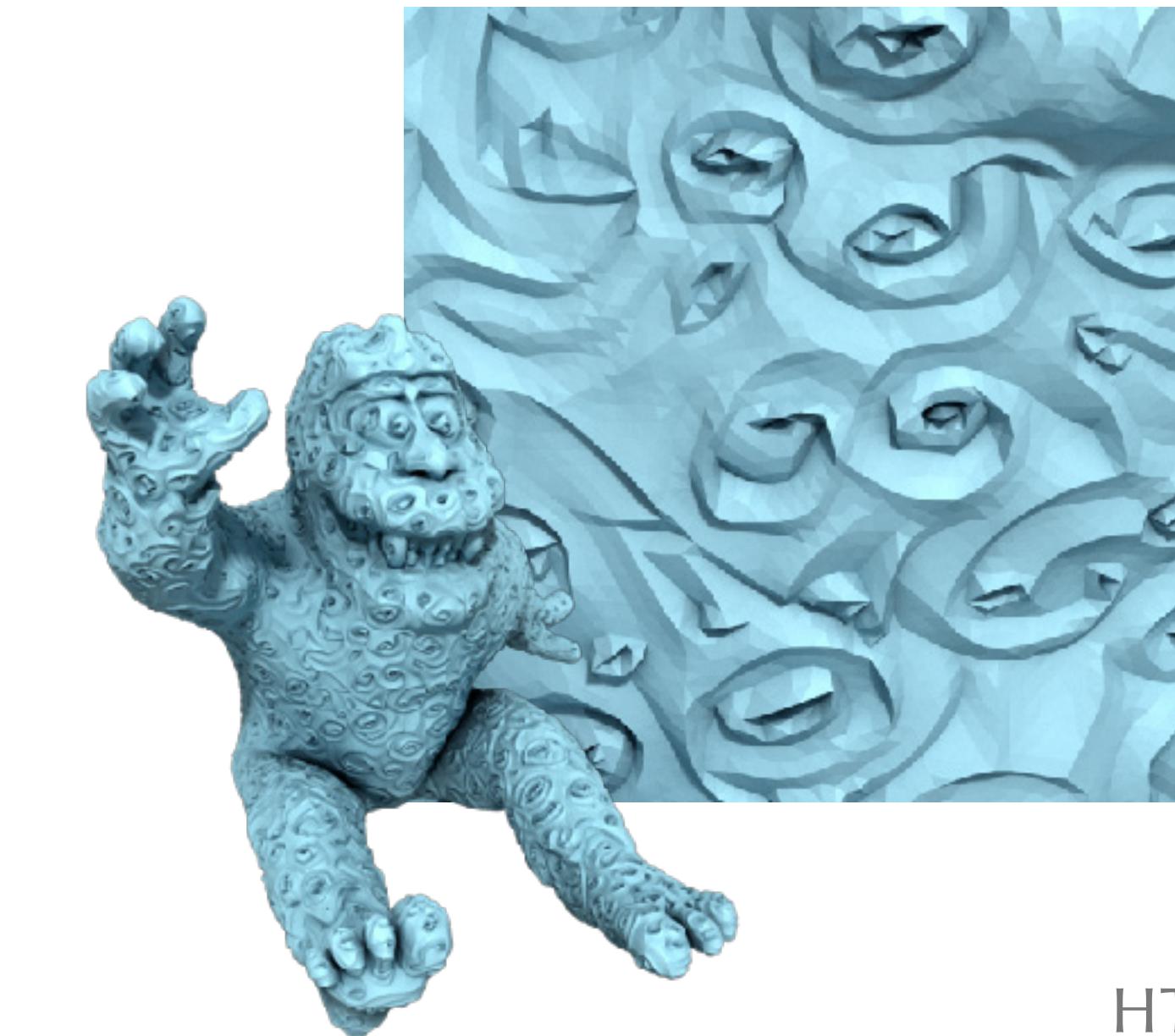
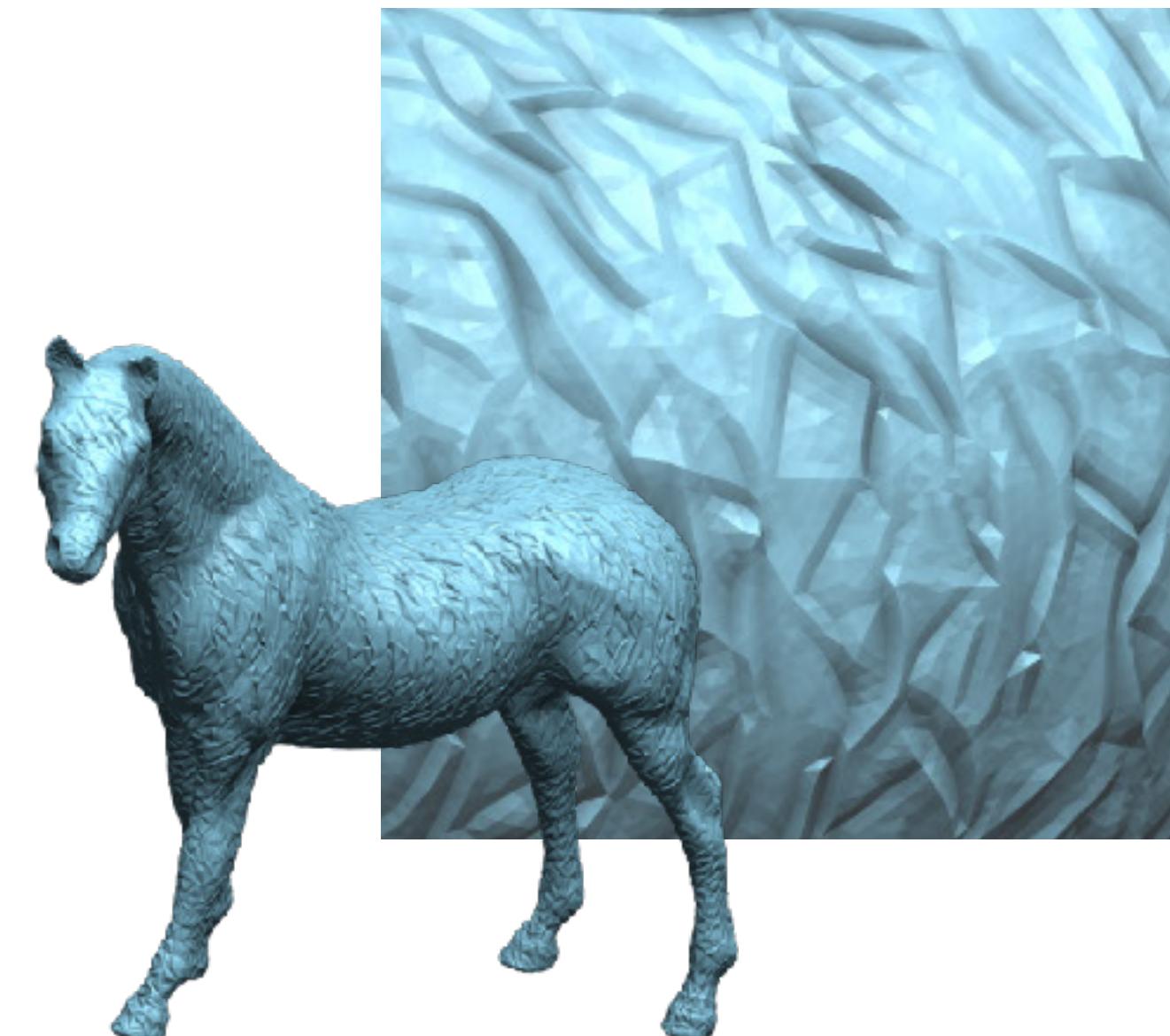
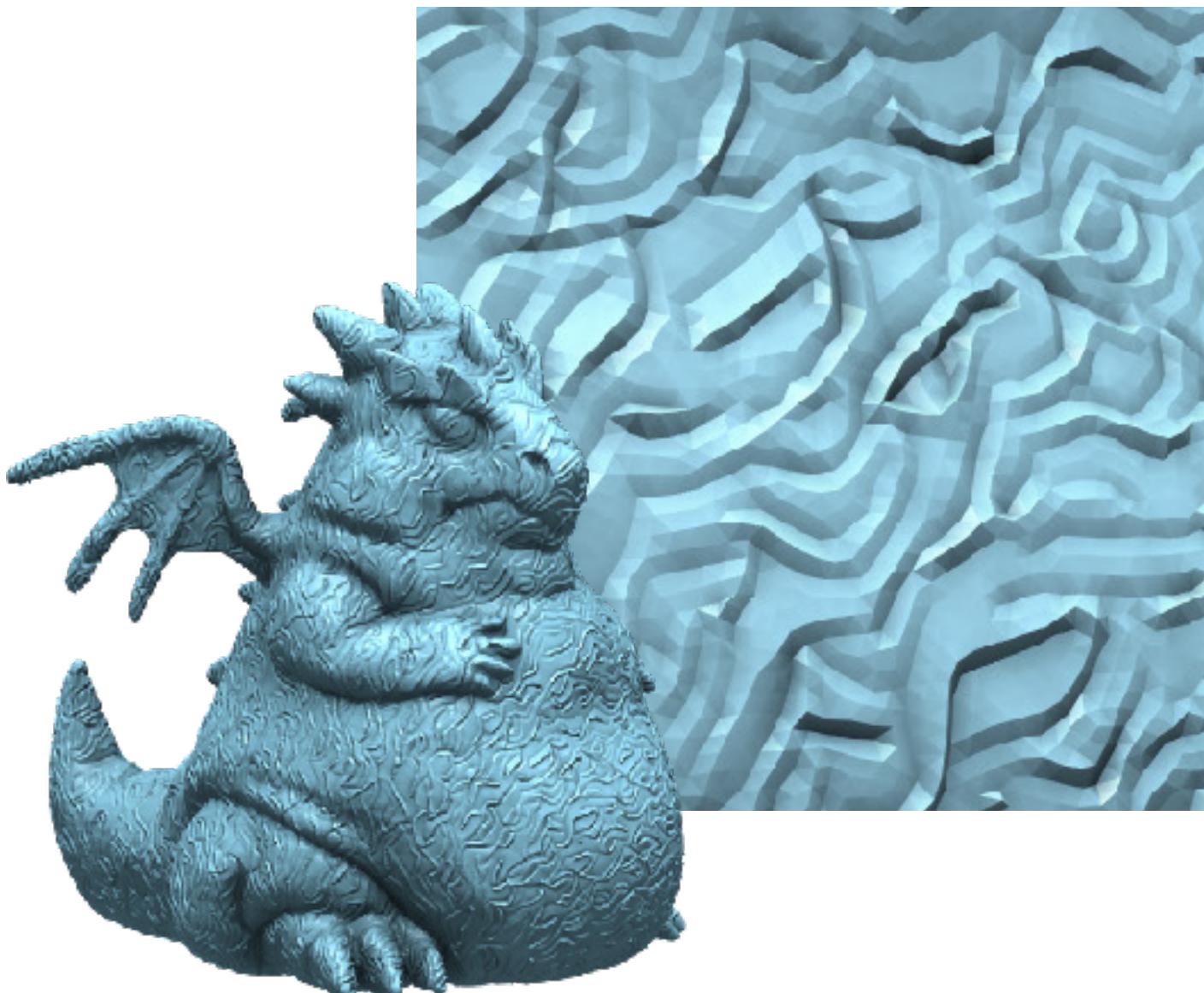
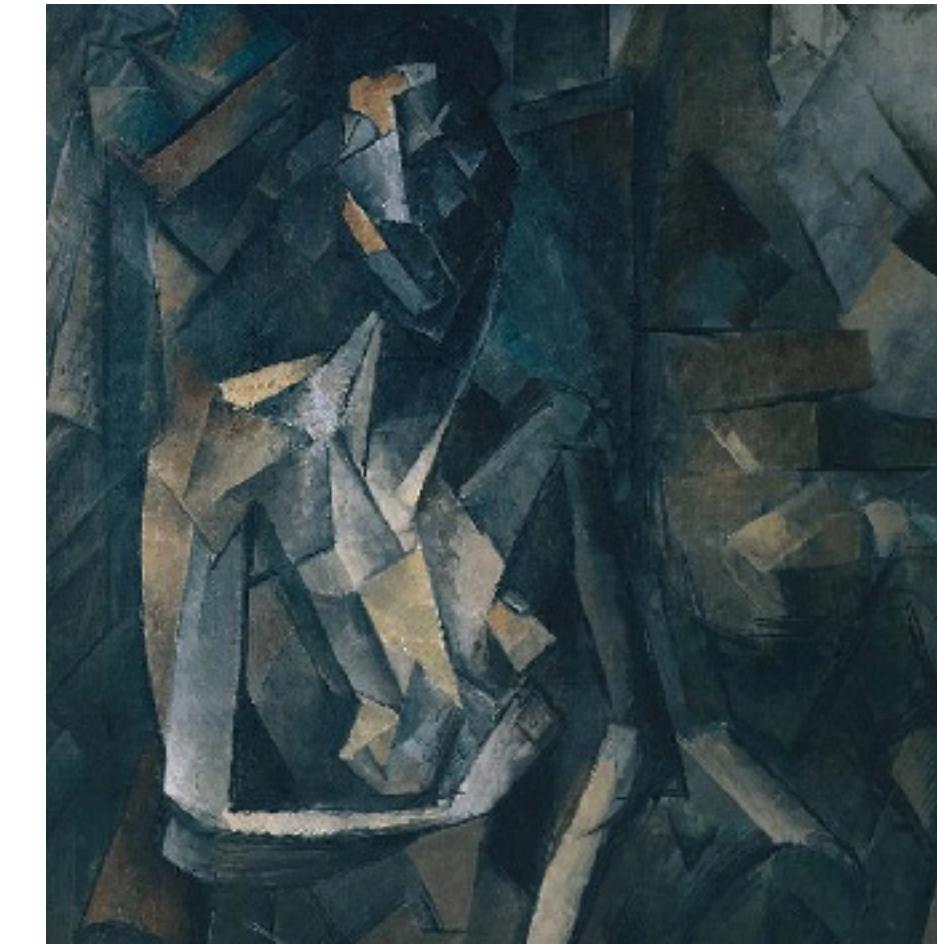
# L0 Gradient Regularization [Xu et al. 2011]



# Neural Style Transfer [Gatys et al. 2016]



# Neural Style Transfer [Gatys et al. 2016]



# Limitations & Future Work

Surface editing using image processing

- accelerate (batch gradient descent)
- large deformations
- combine 3D and 2D editing

Analytically differentiable renderer

- applications in computer vision & machine learning
- incorporate real-time rendering techniques

3D adversarial examples



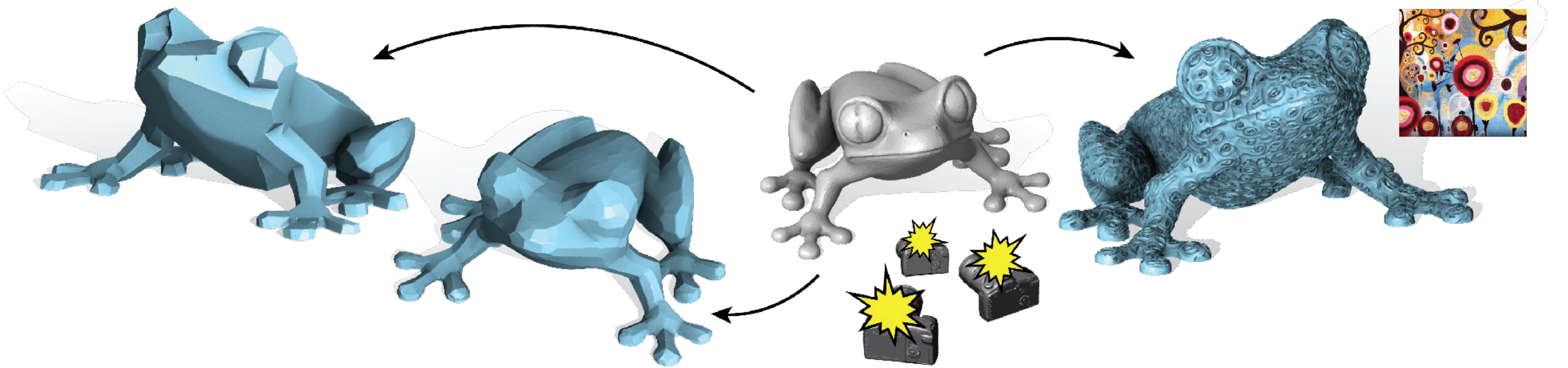
street sign

98%



mailbox

83%



# Paparazzi: Surface Editing by way of Multi-View Image Processing

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