Stroke processing & gestures

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Issues in Digital Sketching

2D

- Stroke filtering. (clothoids, multi-stroke... what are we filtering?)
- Stroke Processing. (sketch widgets, gestures...)
- Strokes and multi-touch. (gestures, symmetric drawing...)
- Stroke appearance (NPR, neatening...)
- Stroke dynamics (pressure, tilt, direction, temporal order...)
- Seamless UI Control (sketch widgets, crossing menus, gestures...)
- Navigation (paper manip., onion skinning...)
- 2D curve creation: (What are desirable curves, how do we perceive them in relation to our design knowledge?).
- Stroke Perception (what spatio-temporal information do they convey?)

3D (Additional dimension for 3D design, animation or 2D design explorations)

- 3D Navigation. (camera tools, single/multi-view, view bookmarks...).
- 3D curve creation: (2D stroke to 3D curves perception & inference).
- Animation (motion trails, evolving shape fronts...)
- Alternate Designs (co-locating them in space...)
Stroke processing: widgets & UI

- WIMP GUI not well-suited to sketching.
- Typical 3D manipulation widgets not suited to sketching.
CrossY: Crossing-Based Drawing
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[Apitz, G. and Guimbretière, F. CrossY: A Crossing-Based Drawing Application ACM UIST, 2004]
Sketch widgets

suggested axes

crossing interaction and composition

[Schmidt, Singh & Balakrishnan Sketching and Composing Widgets for 3D Manipulation, Eurographics 2008]
http://www.dgp.toronto.edu/~rms/pubs/SketchWidgetsEG08.html
Stroke processing: Sketch widgets

Sketching 2D projections of desired 3D strokes is hard!!

[Schmidt, Singh & Balakrishnan Sketching and Composing Widgets for 3D Manipulation, Eurographics 2008]
http://www.dgp.toronto.edu/~rms/pubs/SketchWidgetsEG08.html
Further stroke processing

- Abstraction.
- Segmentation, classification, recognition.
- Beautification.
- Oversketching.
Stroke recognition
Stroke abstraction: finding corners

[T. Sezgin et al., Sketch Based Interfaces: Early Processing for Sketch Understanding, Workshop on Perceptive User Interfaces, 2001.]
Beautification

- Fit primitive shapes.
- Infer geometric relations and constraints.
  - Parallelism
  - Perpendicularity
  - Symmetry
  - Isometry
  - Snapping
Oversketching

- Interactive sketch correction
  1. Find affected region
  2. Splice in new stroke
  3. Smooth connection
Gestural input

• “Gesture-based interfaces offer an alternative to traditional keyboard, menu, and direct manipulation interfaces.” [Rubine]

• “Pen, finger, and wand gestures are increasingly relevant to many new user interfaces.” [Wobbrock]

Recognizable spatio-temporal strokes.
What can gesture?

mouse, pen, wands, fingers, hands, face, body...
Why support gestures?

- Natural form of communication

- Efficient
  - A single stroke can indicate:
    - The operation
    - The operand
    - Additional parameters
  - A proofreader’s mark indicates [Rubine] :
    - that a move should occur (operation)
    - the text that should be moved (the operand)
    - and the new location of the text (an additional param)
Gesture support

• Ad-hoc or pre-defined: “Recognizers that use heuristics specifically tuned to a pre-defined set of gestures.” [Wobbrock 2007]
  • Application specific: shorthand, chinese Brush Painting, musical scores, chemical formulas.
  • Platform specific: gesture libraries.

• Template-based or systematic.
  • Toolkit or framework
  • Simple algorithm
Ad-hoc vs. template-based

- Ad-hoc can recognize more complex gestures.
- Harder to train template-based gestures.
- Better consistency of gestural use in ad-hoc systems.
- Better gesture collision handling in ad-hoc systems.

- Ad-hoc doesn’t allow new gestures and limited customization.
GRANDMA approach

1. Create a new gesture handler and associate it with a class.
2. Draw gesture ~15 times.
3. Define semantics (in Objective C)
Problem Statement

• Gesture is represented as an array $g$ of $P$ sample points:
  \[ G_p = (x_p, y_p, t_p) \]
  \[ 0 \leq p \leq P \]

• Problem: Given an input gesture $g$ and set \{${C_1, C_2, \ldots}$\} of gesture classes determine which class $g$ belongs to.
GRANDMA Algorithm

- 13 Features
- A gesture class is a set of weights assigned to each feature
  - Gestures are given a grade by the linear evaluation function resulting from the weights
  - A gesture is assigned to the class with the maximum grade.
- Training assigns weights to the 13 features
- Gestures are rejected if the grade assigned to two classes is similar
$1$ recognizer

- Most recognizers are hard to write and involve a certain amount of machine learning.
- Toolkits are not available in every setting.
- i.e. easily implement your own.
$1 goals

- Resilience to sampling.
- Require no advance math.
- Small code.
- Fast.
- 1-gesture training.
- Return an N-best list with scores.
$1$ algorithm

- Resample the input
  - $N$ evenly spaced points
- Rotate
  - "Indicative" angle between centroid and start point
- Scale
  - Reference square
- Re-rotate and Score
  - Score built from average distance between candidate and template points
Limitations

- Cannot distinguish between gestures whose identities depend on aspect ratios, orientations.
  - Square from rectangle
  - Up arrow from down arrow
- Cannot be distinguished based on speed.
- Only single strokes.
- Stroke order is important.
- Closed strokes?
- Gestalt gestures!