

CSC 418 Winter 2007 midterm solutions

(1) a) examine the slope of $f(x) = x^2/2a$

if $f' > 1$ on the interval, iterate on y } 2 or 0
 if $f' < 1$ on the interval, iterate on x } -1 for errors

($f' = 0$ is arbitrary, go with some convention)

b) $f(x, y) = 0$ defines the curve
 $f(x, y) > 0$ is one side
 $f(x, y) < 0$ is the other side

observing the sign of $f(x, y)$ determines which side to draw on

so $E = f(x, y)$

$$f(x, y) = y - \frac{x^2}{2a} = E_{x, y}$$

$$E_{x, y+1} = f(x, y+1) = y+1 - \frac{x^2}{2a}$$

$$E_{x+1, y+1} = f(x+1, y+1) = y+1 - \frac{x^2}{2a} - \frac{(2x+1)}{2a}$$

$$E_{x+1, y} = f(x+1, y) = y - \frac{x^2}{2a} - \frac{(2x+1)}{2a}$$

since we're iterating on y , we only need $E_{x, y+1}$ and $E_{x+1, y+1}$

To get $E_{x+1, y+1}$ from $E_{x, y}$ (and $E_{x+1, y}$ from $E_{x, y}$)
 examine their difference; add the difference to $E_{x, y}$ to get
 the updated error

$$x, y+1 \text{ update: } E_{x, y+1} - E_{x, y} = \left(y+1 - \frac{x^2}{2a} \right) - \left(y - \frac{x^2}{2a} \right) = 1$$

$$x+1, y+1 \text{ update: } E_{x+1, y+1} - E_{x, y} = \left(y+1 - \frac{x^2}{2a} - \frac{(2x+1)}{2a} \right) - \left(y - \frac{x^2}{2a} \right) = 1 - \frac{2x+1}{2a}$$

$$x+1, y \text{ update: } E_{x+1, y} - E_{x, y} = \left(y - \frac{x^2}{2a} - \frac{(2x+1)}{2a}\right) - \left(y - \frac{x^2}{2a}\right) = -\frac{2x+1}{2a}$$

the updates are in fp math because of the $\frac{1}{2a}$ factor, so multiply everything by $2a$ to gain integer versions

$$\Delta_{x, y+1} = 2a$$

$$\Delta_{x+1, y} = 2a - 2x - 1$$

- 1 for what E is
- 2 for the updates
- 1 for integer versions

having $f(x, y) = \frac{x^2}{2a} - y$ does not affect anything so may have updates

$$\Delta_{x, y+1} = -2a$$

$$\Delta_{x+1, y} = 1 + 2x - 2a$$

instead

c) no; for $x \in [2a, 4a]$ (original interval), $f'(x) > 1$ so iterating on y is used

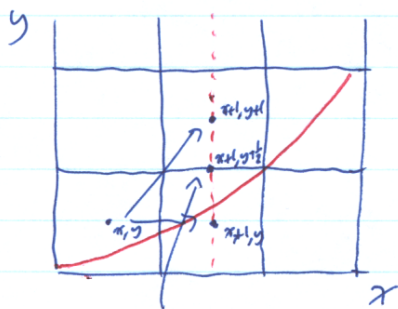
① for $x \in [0, a]$ (part of new interval), $f'(x) < 1$, so need to iterate on x

So, separate ~~into~~ the parabola into two segments, and iterate over x where $f' < 1$ and iterate over y where $f' > 1$.

~~Additionally, the error to maintain is different~~
If iterating over x , the error update $\Delta_{x, y+1}$ needs to be incorporated, and $\Delta_{x, y}$ won't be used in that case.

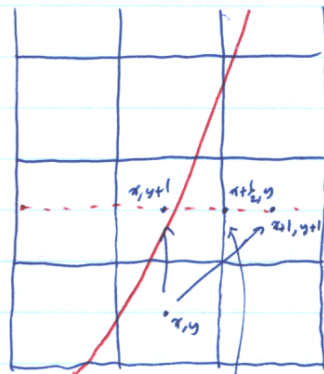
Additionally, the error to be maintained is different between iterating over x and over y :

While iterating over x , one is looking at the midpoint between y coords while when iterating over y , one is looking at the midpoint between x coords



testing midpoint to see which side of the parabola it lies on:

$$f(x + \frac{1}{2}, y) < 0 \text{ or } > 0$$



testing midpoint to see which side of the parabola it lies on:

$$f(x, y + \frac{1}{2}) < 0 \text{ or } > 0$$

This only matters to the initialization since difference between midpoints to check \neq remain 1 or 0 in the coords

~~4~~ 4, 2, 0 for material in block ①

2 for nothing about slope being the reason

Note about Q1:

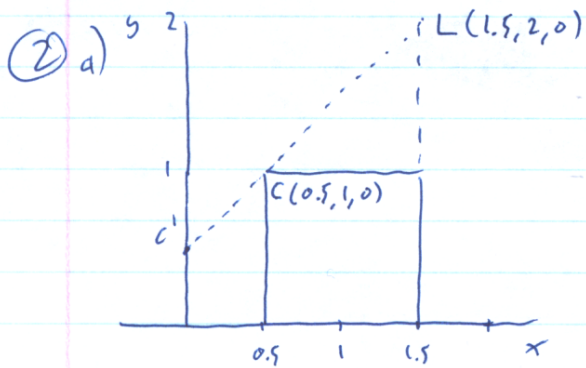
the point $(2a, 2a)$ does not lie on the parabola;

if the function was

$$y - \left(\frac{x}{2a}\right)^2 = 0$$

then that would have been the case.

~~Any~~ point There was no penalty when discussing $(2a, 2a)$ as if it were the slope's turning point

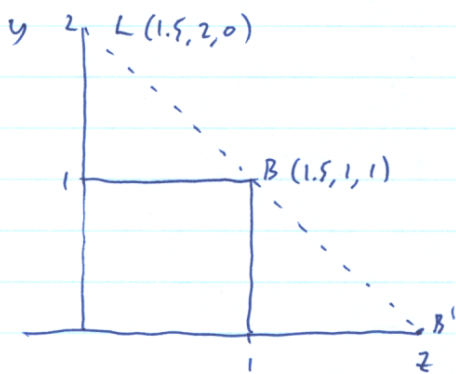


$$C' = (0, 0.5, 0)$$

1 mark per correct point

0 if wrong and without work

$\frac{1}{2}$ if wrong with correct work



$$B' = (1.5, 0, 2)$$

The ray through A hits the yz plane ($x=0$), or at least appears to

$\rightarrow x=0$, see if the point makes sense

$$\vec{L} = (1.5, 2, 0) \quad \vec{A} = (0.5, 1, 1)$$

$$\text{ray: } \vec{r}(\lambda) = (\vec{A} - \vec{L})\lambda + \vec{L}$$

$$= \begin{bmatrix} 0.5 - 1.5 \\ 1 - 2 \\ 1 - 0 \end{bmatrix} \lambda + \begin{bmatrix} 1.5 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} \lambda + \begin{bmatrix} 1.5 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ ? \\ ? \end{bmatrix}$$

$$-1 \cdot \lambda + 1.5 = 0$$

$$\lambda = 1.5 \quad \Rightarrow$$

$$A' = \begin{bmatrix} 1.5 \\ 2 \\ 0 \end{bmatrix} + 1.5 \begin{bmatrix} -1 \\ -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 - 1.5 \\ 0 + 1.5 \end{bmatrix} = \begin{bmatrix} 0 \\ 0.5 \\ 1.5 \end{bmatrix}$$

$$A' = (0, 0.5, 1.5)$$

the point lies in the right octant ($x \geq 0, y \geq 0, z \geq 0$) so it's good

(2) b) take \vec{P} , construct the ray through \vec{L} and P , originating from \vec{P}

$$\vec{x}(\lambda) = (\vec{P} - \vec{L})\lambda + \vec{P}$$

intersect the ray with the three planes, $x=0, y=0, z=0$

$$(\hat{i} = \hat{i}, \hat{n} = \hat{j}, \hat{n} = \hat{k})$$

solve for λ and check λ and $\vec{x}(\lambda)$ against restrictions:

$$\lambda \geq 0, \quad \underbrace{x \geq 0, y \geq 0, z \geq 0}_{\text{correct octant}}$$

↑
forward ray direction

using the implicit plane equation, $(\vec{x} - \vec{x}_0) \cdot \vec{n} = 0$, we can find λ appropriately.

(\vec{n} is ~~one of~~ chosen to correspond to the plane to intersect with, $\vec{x}_0 = \vec{0}$ since all planes we meet go through the origin)

$$\vec{x}(\lambda) \cdot \vec{n} = 0$$

$$((\vec{P} - \vec{L})\lambda + \vec{P}) \cdot \vec{n} = 0$$

$$\lambda = \frac{-\vec{P} \cdot \vec{n}}{(\vec{P} - \vec{L}) \cdot \vec{n}}$$

$$\text{so } \vec{x}(\lambda) = (\vec{P} - \vec{L}) \frac{-\vec{P} \cdot \vec{n}}{(\vec{P} - \vec{L}) \cdot \vec{n}} + \vec{P}$$

if λ done (ie $(\vec{P} - \vec{L}) \cdot \vec{n} = 0$) the ray is perpendicular to the normal, so either the line runs parallel to the plane, never touching, or it is embedded in the plane. Test \vec{P} to find out

1 plane-ray intersection idea

1 math discussion on how to get to finding P'

0.5 for the point P'

1 for $\lambda \geq 0, x \geq 0, y \geq 0, z \geq 0$

0.5 for λ done case

*alternate ~~point~~ ^{point} solution

$$P(x, y, z) \quad L = (1.5, 2, 0)$$

the ray through \vec{P} and \vec{L} , originating at \vec{P} is \vec{L}

$$\begin{bmatrix} x' \\ y' \\ z' \end{bmatrix} = \begin{bmatrix} x-1.5 \\ y-2 \\ z-0 \end{bmatrix} \lambda + \begin{bmatrix} 1.5 \\ 2 \\ 0 \end{bmatrix} = \begin{bmatrix} x-1.5 \\ y-2 \\ z \end{bmatrix} \lambda + \begin{bmatrix} 1.5 \\ 2 \\ 0 \end{bmatrix}$$

we can write this in symmetric form

$$\left. \begin{array}{l} x' = (x-1.5)\lambda + 1.5 \\ y' = (y-2)\lambda + 2 \\ z' = z\lambda \end{array} \right\} \rightarrow \lambda = \frac{x'-1.5}{x-1.5} = \frac{y'-2}{y-2} = \frac{z'}{z}$$

test plane $x=0$, $y=0$, but not $z=0$ as it's impossible to hit that plane directly

$$x'=0 : \frac{y'-2}{y-2} = \frac{0-1.5}{x-1.5} \qquad \frac{z'}{z} = \frac{0-1.5}{x-1.5}$$

$$y' = -1.5 \frac{y-2}{x-1.5} + 2 \qquad z' = z \frac{-1.5}{x-1.5}$$

$$y'=0 : \frac{x'-1.5}{x-1.5} = \frac{0-2}{y-2} \qquad \frac{z'}{z} = \frac{0-2}{y-2}$$

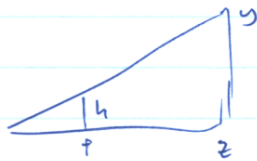
$$x' = -2 \frac{x-1.5}{y-2} + 1.5 \qquad z' = -2 \frac{z}{y-2}$$

to sort out which ~~point~~ intersection is the right one, one can check to see if $P'(x', y', z')$ lies in the correct quadrant. However, that does not eliminate backwards running rays. To check this, simply compute λ for one of the ratios

What happens if one of the denominators is zero?
 The denominator is a component of the line's direction vector,
 so if it's zero, the corresponding coordinate is invariant,
 and that term may be excluded from computation.

- 1 - plane-ray intersection
- 1 - math-discussion
- 0.5 included if using $x \geq 0, y \geq 0$ bounds
- 0.5 if does not discuss \rightarrow case
- 0.5 point P'
- 0.5 \rightarrow done case (denominator = 0 case)

② c) Consider perspective projection of an object onto an image plane



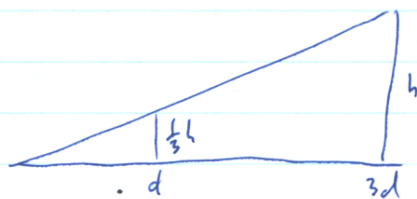
unknown h is related to everything else by

$$\frac{h}{f} = \frac{y}{z}$$

$$h = f \frac{y}{z}$$

\Rightarrow it only depends on the distance/height ratio.

So of course, an object 3 times as far and one $\frac{1}{3}$ as big
 appear to have the same size on the image plane as
 they have the same distance/height ratio



1 idea

1 illustrative picture

(2) d) Consider a line in world space

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} a_x \\ a_y \\ a_z \end{bmatrix} + \lambda \begin{bmatrix} b_x \\ b_y \\ b_z \end{bmatrix}$$

under perspective projection;

$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} \rightarrow \begin{bmatrix} \frac{x}{z} f \\ \frac{y}{z} f \\ f \end{bmatrix} \quad f \text{ some constant}$$

$$\text{so } \begin{bmatrix} a_x + \lambda b_x \\ a_y + \lambda b_y \\ a_z + \lambda b_z \end{bmatrix} \rightarrow f \begin{bmatrix} \frac{a_x + \lambda b_x}{a_z + \lambda b_z} \\ \frac{a_y + \lambda b_y}{a_z + \lambda b_z} \\ 1 \end{bmatrix}$$

as $\lambda \rightarrow \infty$ (or $-\infty$ depending on orientation of the line);

$$\lim_{\lambda \rightarrow \infty} f \begin{bmatrix} \frac{a_x + \lambda b_x}{a_z + \lambda b_z} \\ \frac{a_y + \lambda b_y}{a_z + \lambda b_z} \\ 1 \end{bmatrix} = \begin{bmatrix} f \frac{b_x}{b_z} \\ f \frac{b_y}{b_z} \\ 1 \end{bmatrix}$$

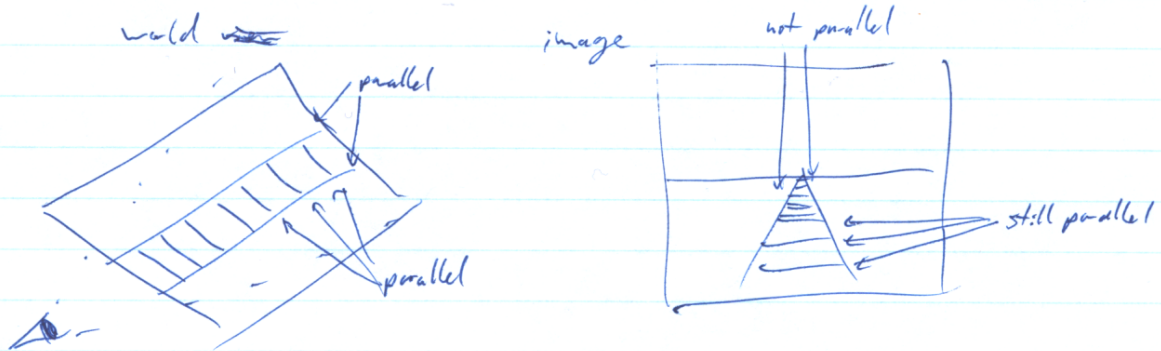
so it doesn't matter which point the lines go through; as long as they have the same direction vector, they converge to the same spot point, as long as the lines are defined.

If $b_z = 0$, this is undefined. That corresponds to lines with constant z coord. Examining that case;

$$\begin{bmatrix} \frac{a_x + \lambda b_x}{a_z + \lambda b_z} \\ \frac{a_y + \lambda b_y}{a_z + \lambda b_z} \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{a_x + \lambda b_x}{a_z} \\ \frac{a_y + \lambda b_y}{a_z} \\ 1 \end{bmatrix} = \frac{1}{a_z} \begin{bmatrix} a_x \\ a_y \end{bmatrix} + \lambda \frac{1}{a_z} \begin{bmatrix} b_x \\ b_y \end{bmatrix}$$

~~so such lines will remain parallel as their direction vectors~~

So such lines will remain parallel as their direction vectors are still proportional



- | explanation
- | diagram
- | between diagram and explanation, depending on how well the section was done.

words, explanation:

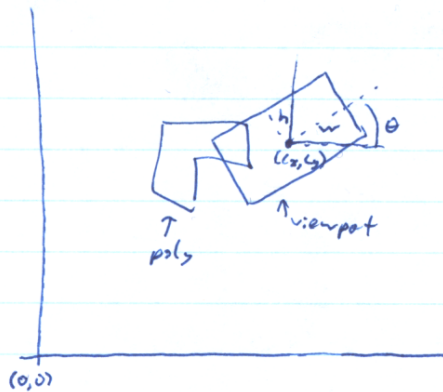
objects further away appear smaller, so the distance between parallel lines will appear to shrink as the points get further into the distance, thus no longer being parallel.

Conversely

→ if they do not go into the distance, they remain parallel

(followed by appropriate picture)

③



goal: transfer from world to viewport space, clip, transfer back.

assuming the operations operate on polygons;

$$P = \text{translate}(-c_x, -c_y, P)$$

$$P = \text{rotate}(-\theta, P)$$

$$P = \text{clip}(-w, w, h, -h, P)$$

$$P = \text{rotate}(\theta, P)$$

$$P = \text{translate}(c_x, c_y, P)$$

2 idea of untransform, clip, transform

1 retransform part

3 function details

$-\frac{1}{2}$ for $\theta, -\theta$ flip and ; rotater usually go ccw with the angle given

-1 for translate not pre-rot

-1 for rotate / translate order inversion

-0 for $\frac{h}{2}, \frac{w}{2}$ instead of h, w as if $h \rightarrow$ height, $w \rightarrow$ width, it should be halved (no original labeling ambiguous)