## Radiosity

#### **Alexis Angelidis Graphics Lab - Otago University** 2003

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Greatly inspired by: - Radiosity & Global Illumination, F.X. Sillon & C. Puech - SIGGRAPH'93 Education Slide Set

#### Lecture outline

#### Introduction

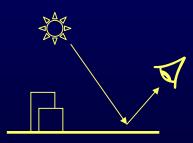
- Preliminaries
- Radiosity equation
- Solving the equation
- Optimization
- Extensions
- Conclusion



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## Introduction

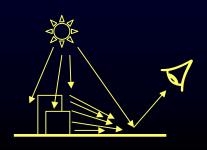
- Local illumination:
  - source of illumination = light



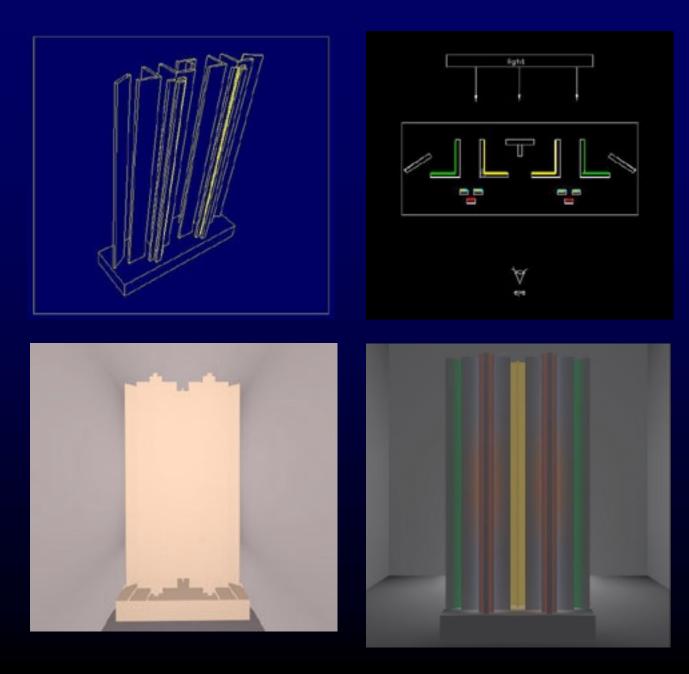


• Global illumination:

– source of illumination = any object







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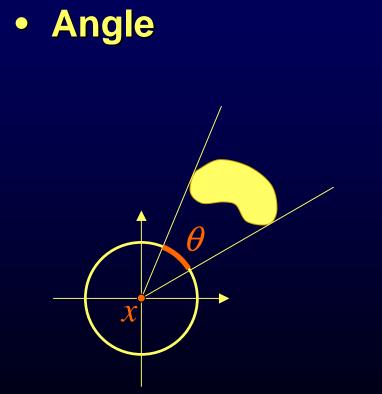


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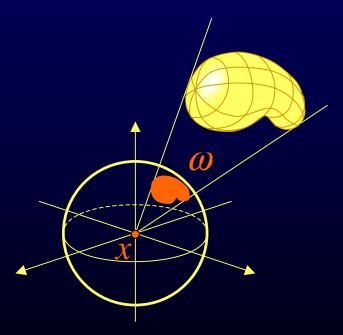
#### What quantities are we dealing with?

## Solid angle

What is the 'size' of an object from a point?



Solid angle



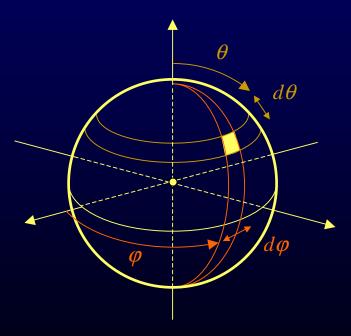
unit circle  $\equiv 2\pi$  radians

unit sphere  $\equiv 4\pi$  steradians (sr)

## Solid angle

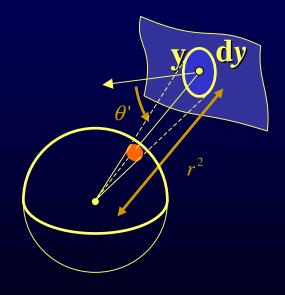
How is it related to other units?

• Solid angle in spherical coordinates



$$d\omega = \sin\theta d\phi d\theta$$

• Solid angle subtended by area dy

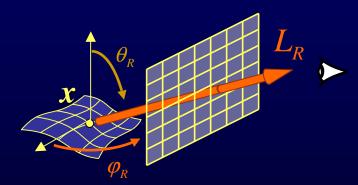


 $dy\cos\theta'$  $d\omega =$ 

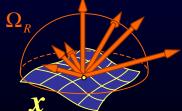
## Radiance & Radiosity

What is the relevant quantity for light?

• Radiance  $L_R(x, \theta_R, \varphi_R)$ 



• Radiosity B(x)



$$B(x) = \int_{\Omega_R} L_R(x, \theta_R, \varphi_R) \cos\theta_R d\omega_R$$

• Ideal diffuse reflector case:

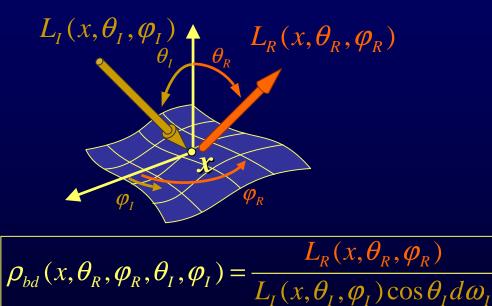
$$L_{R}(x,\theta_{R},\varphi_{R}) \equiv L_{R}(x) = \frac{1}{\pi}B(x)$$



## BRDF & DHRF

How are described surfaces?

BRDF (Bidirectional Reflectance Distribution Function)



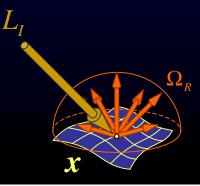
• Ideal diffuse reflector case:

$$\rho_{bd}(x,\theta_R,\varphi_R,\theta_I,\varphi_I) \equiv \rho_{bd}(x) = \frac{1}{\pi}\rho_{dh}(x)$$

 $\rho_{dh}^{R}(x) \in [0,1]$   $\rho_{dh}^{G}(x) \in [0,1]$   $\rho_{dh}^{B}(x) \in [0,1]$   $\equiv \text{`color of surface'}$  $\rho_{dh}^{B}(x) \in [0,1]$ 

• **DHRF** (Directional Hemispherical Reflectance Function)

$$\rho_{dh}(x,\theta_R,\varphi_R) = \frac{\int_{\Omega_R} L_R(x,\theta_R,\varphi_R) \cos\theta_R d\omega_R}{L_I(x,\theta_I,\varphi_I) \cos\theta_I d\omega_I}$$



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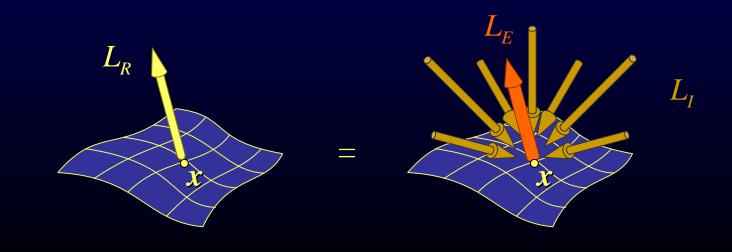


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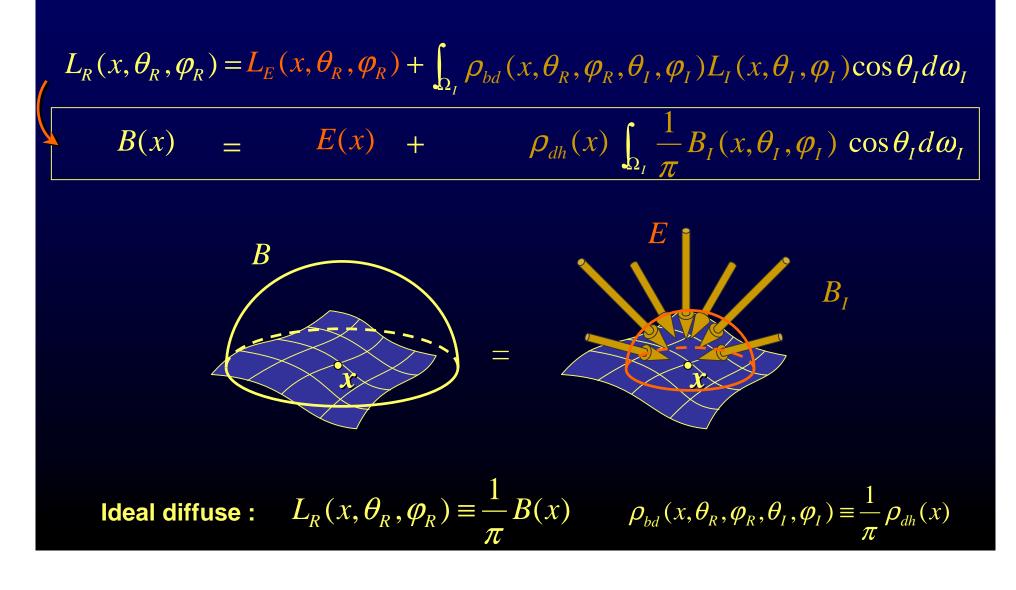
## **Global Illumination Equation**

How can it lead to the Radiosity Equation?



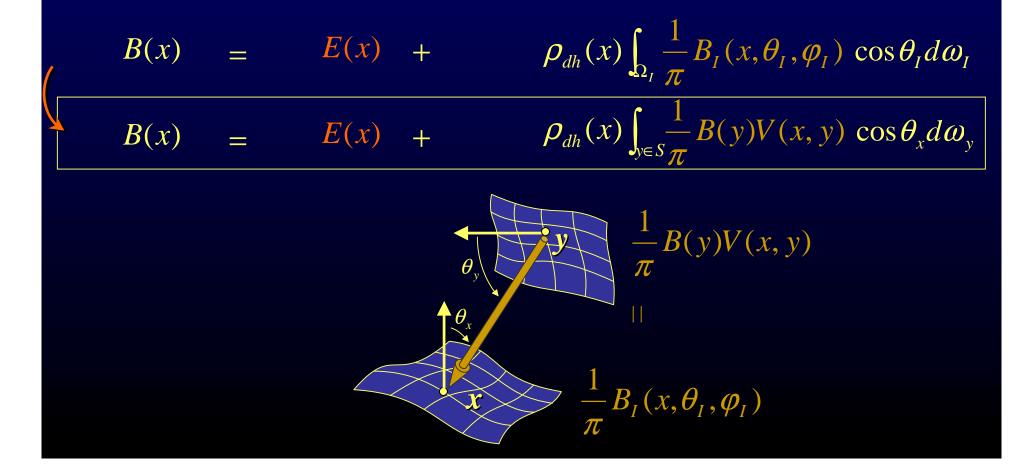


## Ideal diffuse reflectors Equation



## Introducing Visibility

Can we replace the 'incoming radiosity' terms?



### **Discrete Radiosity Equation**





 $B(x) = E(x) + \rho_{dh}(x) \int_{y \in S} \frac{1}{\pi} B(y) V(x, y) \cos \theta_x d\omega_y$ 

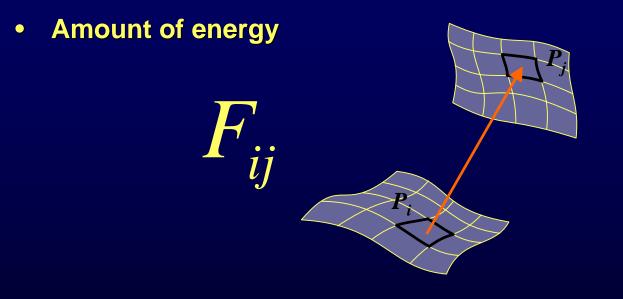
 $B(x) = E(x) + \rho_i \sum_{j=1}^N B_j \int_{y \in P_j} \frac{1}{\pi} V(x, y) \cos \theta_x d\omega_y$   $B_i = \frac{1}{A_i} \int_{x \in P_i} B(x) \qquad E_i = \frac{1}{A_i} \int_{x \in P_i} E(x)$ 

## **Radiosity Equation**

#### • Discrete formulation

$$B_{i} = E_{i} + \rho_{i} \sum_{j=1}^{N} B_{j} \frac{1}{A_{i}} \int_{x \in P_{i}} \int_{y \in P_{j}} \frac{V(x, y) \cos \theta_{x} d\omega_{y}}{\pi}$$
Radiosity Equation
$$B_{i} = E_{i} + \rho_{i} \sum_{j=1}^{N} B_{j} F_{ij}$$
• Solving radiosity :
$$- \text{ compute form factors} - \text{ solve } N \text{ equations}$$

### Form Factors

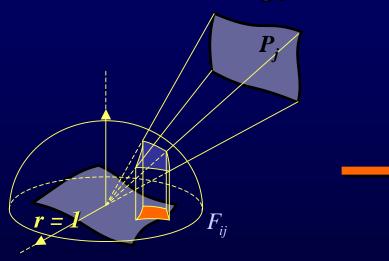


• Property

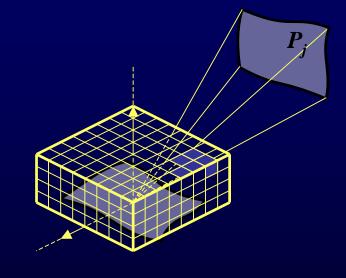
$$A_i F_{ij} = A_j F_{ji}$$

### Form Factors

• Nusselt's analogy



• Hemi-cube



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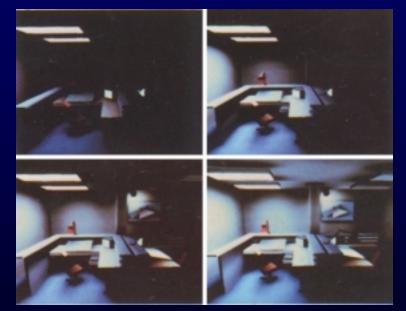
 $F_{ij} =$ 

 $\Delta F$ 

 $\frac{1}{A_i} \int_{x \in P_i} \int_{y \in P_j} \frac{V(x, y) \cos \theta_x d\omega_y}{\pi}$  $\frac{V(x, y)\cos\theta_{x}d\omega_{y}}{\pi}$  $F_{ij} pprox$  $y \in P_i$ 

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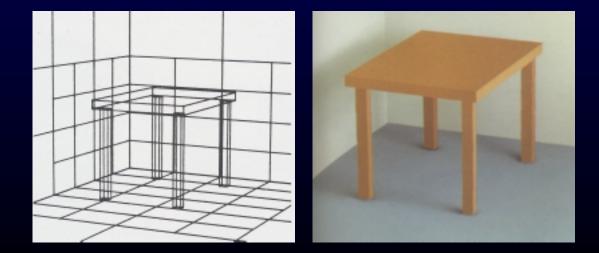
Radiosity Equation  

$$B_i = E_i + \rho_i \sum_{j=1}^N B_j F_{ij}$$

## Solving the equation

#### 4 famous methods for solving the 'classic' radiosity

- Matrix inversion
- Jacobi relaxation
- Gauss-Seidel relaxation (gathering)
- Southwell relaxation (shooting)



### Matrix inversion

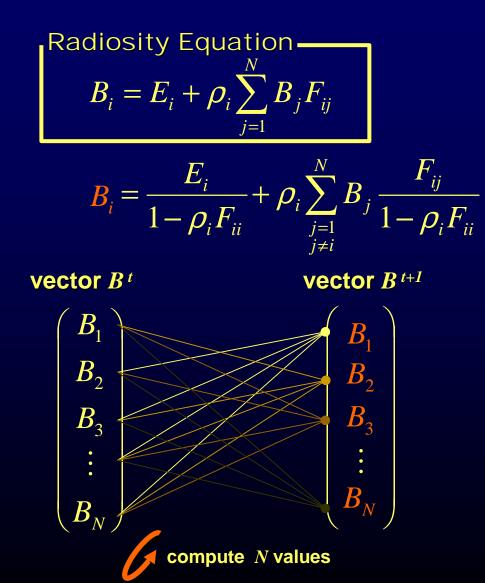
 $B_{i} = E_{i} + \rho_{i} \sum_{j=1}^{N} B_{j} F_{ij}$  $B_{i} - \rho_{i} \sum_{j=1}^{N} B_{j} F_{ij} = E_{i} \qquad i \in [1, N]$  $\begin{pmatrix} 1 - \rho_{1} F_{11} & -\rho_{1} F_{12} & \cdots & -\rho_{1} F_{1N} \\ -\rho_{2} F_{21} & 1 - \rho_{2} F_{22} & \vdots \\ \vdots & \ddots & \vdots \\ -\rho_{N} F_{NN} & \cdots & \cdots & 1 - \rho_{N} F_{NN} \end{pmatrix} \begin{pmatrix} B_{1} \\ B_{2} \\ \vdots \\ B_{N} \end{pmatrix} = \begin{pmatrix} E_{1} \\ E_{2} \\ \vdots \\ E_{N} \end{pmatrix}$ 

MB = E

Invert M

Drawbacks: all form factors required / no intermediate solution

#### Jacobi relaxation



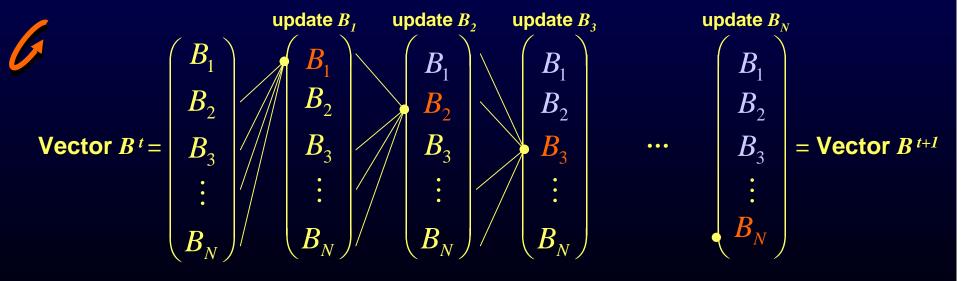
Drawbacks: all form factors required / two vectors *B*<sup>t</sup> and *B*<sup>t+1</sup> required

### Gauss-Seidel relaxation

Radiosity Equation  

$$B_i = E_i + \rho_i \sum_{j=1}^N B_j F_{ij}$$

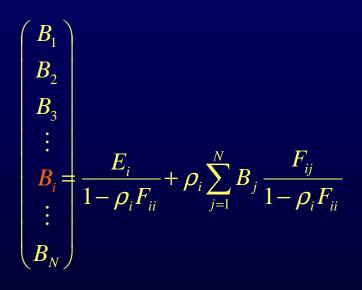
$$\mathbf{g}_{i} = \frac{E_{i}}{1 - \rho_{i}F_{ii}} + \rho_{i}\sum_{\substack{j=1\\j\neq i}}^{N} B_{j}\frac{F_{ij}}{1 - \rho_{i}F_{ii}}$$

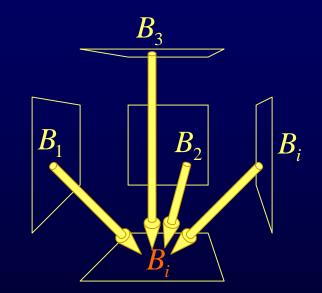


Drawbacks: all form factors are required for one <u>complete</u> iteration Advantages: only one storage vector required / faster convergence than Jacobi

## Gauss-Seidel relaxation

• Why is it called <u>Gathering</u>?







## Southwell relaxation

• Idea: distribute the residual energy of the patch of most residual energy,  $P_i$ 

Radiosity Equation  
$$B_i = E_i + \rho_i \sum_{j=1}^N B_j F_{ij}$$

$$A_i B_i = A_i E_i + \rho_i \sum_{j=1}^N A_j B_j F_{ji}$$

Energy Equation — 
$$\boldsymbol{\beta}_i = \boldsymbol{\varepsilon}_i + \boldsymbol{\rho}_i \sum_{j=1}^N \boldsymbol{\beta}_j F_{ji}$$

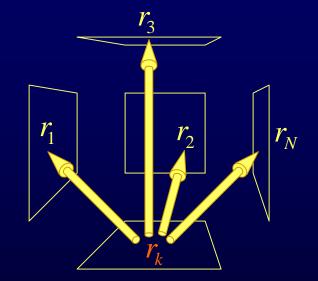
Posiduals energy

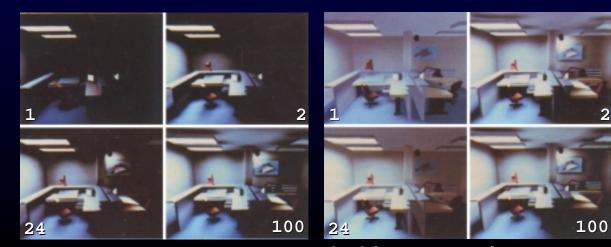
1. 
$$k = \arg \max_{k} (r_{k})$$
  
 $r_{i} = \mathcal{E}_{i} - \beta_{i} + \rho$   
2.  $r_{i\neq k} + = \frac{\rho_{i}F_{ik}}{1 - \rho_{k}F_{kk}}r_{k}, \quad r_{k} = 0$   
3.  $\beta_{k} = \frac{\mathcal{E}_{k}}{1 - \rho_{k}F_{kk}} + \rho_{i}\sum_{\substack{j=1\\j\neq k}}^{N} \beta_{j}\frac{F_{jk}}{1 - \rho_{k}F_{kk}}, \quad B_{i} = \frac{\beta_{i} + r_{i}}{A_{i}}$ 

### Southwell relaxation

• Why is it called <u>Shooting</u>?

$$r_{i\neq k} + = \frac{\rho_i F_{ik}}{1 - \rho_k F_{kk}} r_k$$
$$r_k = 0$$

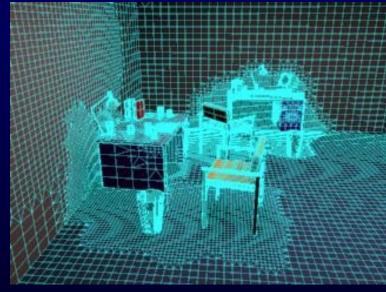




Ambient correction

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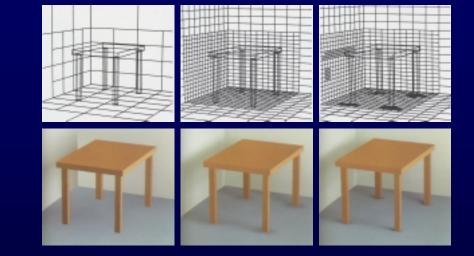


F. Sillion

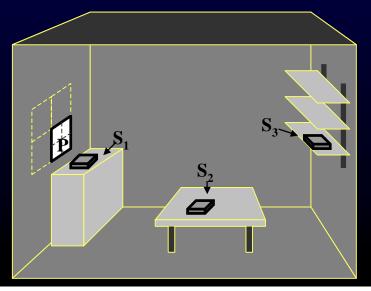
## Optimizing

#### Sampling tradeoff

- too coarse: ugly solution
- too fine: time consuming

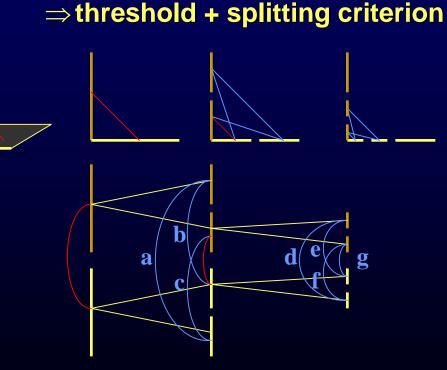


#### • The necessity to emit energy at different levels:



## Hierarchical Radiosity

- Allow exchanges at different levels
- Links between two hierarchical patches:





Gathering radiosity for a patch P<sub>i</sub>:

- 1. Compute gathered radiosities  $B_G$  for patch  $P_i$  and its subpatches
- 2. Update the radiosities B of the tree (bidirectionnal sweep)



Decreasing tolerance

(Blocks are breaking)

F. Sillion

### Importance

#### • View dependent refinement



**Radiosity solution** 

**Importance solution** 

Superposition, in yellow

Importance Equation  

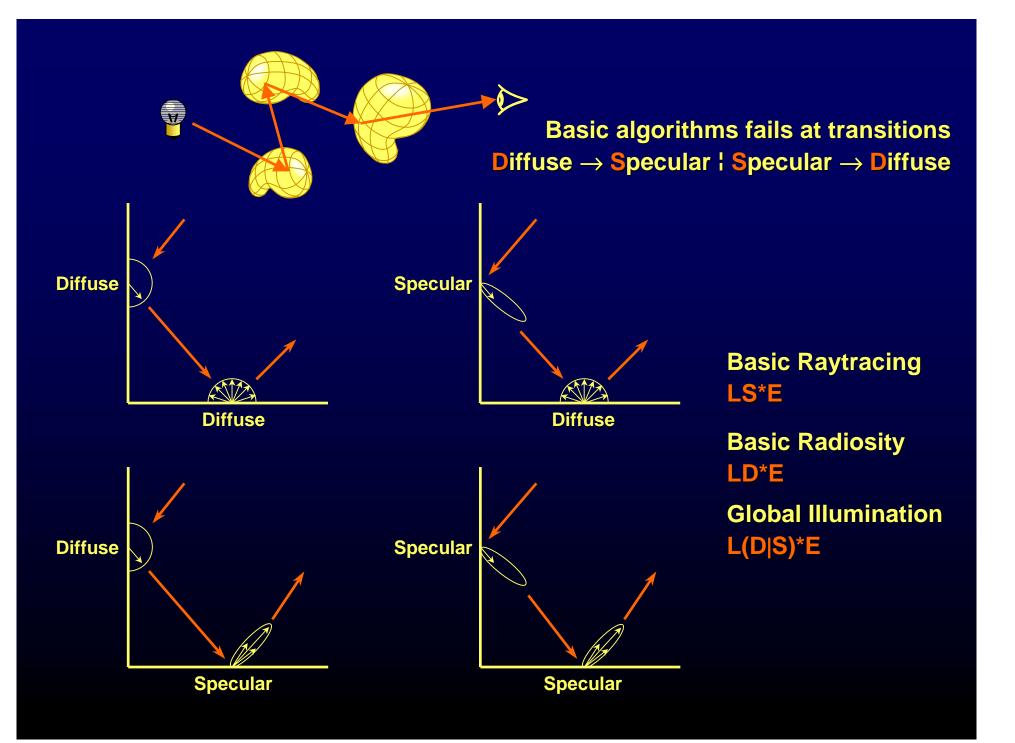
$$I_i = R_i + \sum_{j=1}^N \rho_j F_{ji} I_j$$

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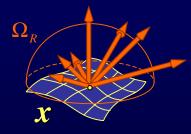


F. Sillion



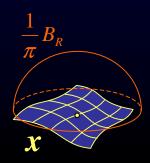
## **Directional radiosity**

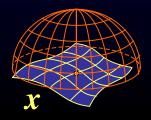
• Global Illumination:





• Radiosity: radiance is constant Directional radiosity : radiance is piecewise constant



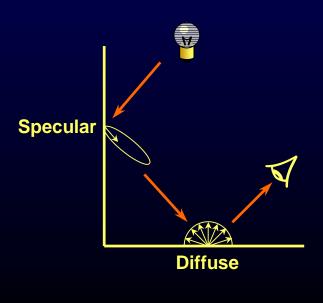


### Two-pass approach

- Two-pass approach
  - 1. Radiosity: LD\*E
  - 2. Raytracing LDS\*E

#### • Limitation: misses LS\*DE

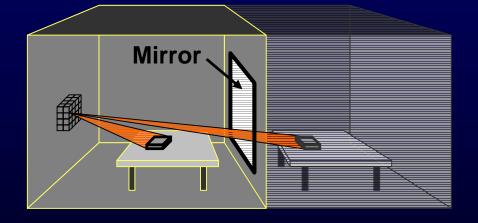


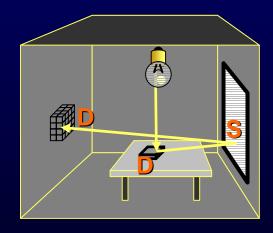


# Complete\* two-pass approach

(\* Ideal diffuse & ideal specular surfaces)

 Two-pass approach with extended form factors Idea: Include D→ S\* → D in the first pass







# For the eyes

