SIGGRAPH2004



Cords: Keyframe Control of Curves with Physical Properties

Patrick Coleman and Karan Singh Dynamic Graphics Project, University of Toronto August 11, 2004

Motivation



- Precise interactive control of curves with physical appearance properties
- String, wire, rubber bands, etc.



Motivation



Artistic control of primitives that interact with geometry



Motivation









Design Requirements



- Intuitive parameter space
- Interactive and precise control
- Continuous shape for keyframe animation
- No dependence on simulation data

Related Work



Physical simulation

Terzopoulos et al. 87, Pai 02

Empirical simulation

Brown 04

Faking dynamics

Barzel 97

Traditional Curve Modeling



 Animators and modelers understand the control point editing paradigm

 Interaction with scene geometry can require arbitrarily complex shapes

 Too many control points
 Shape and detail change with animation

Simulation



 Animators control initial state, environment, and simulation parameters

 Excellent for reactive motion
 Adheres to a given physical model

Control

 Hard to achieve desired response
 Can't specify shape at arbitrary time

Contributions



• Precise control for keyframe animation

Automatic bending and wrapping

Intuitive parameter space for predictable response

Easy to code algorithms

Cords Approach



- User controls general path with a guide curve
 - Arbitrary parametric curve in space f(t)



Cords Approach



- Procedural generation of cord
 - Analytic, continuous shape that follows guide curve
 - Material-like properties of length, stiffness, elasticity



Cords Approach





Cords Workflow



- Generation follows path of guide curve, wrapping around scene geometry
- User positions the guide curve and edits cord properties

Cords Workflow







Initialize Cord to f(0).
 Grow the Cord by stepping along f.

 if (ray from Cord to f intersects geometry)
 grow cord to intersection
 else
 grow cord by a stiffness factor s along the ray

Adjust Cord to given length, elasticity.























































































 Adjust Cord to given length, elasticity: stretched length: length to reach f(1) elastic length: linear interpolation between length and stretched length

> if (elastic length < stretched length) clip cord else extend cord along final tangent

Maintains continuous response to parameters

Cords Analysis



- Cords have a piecewise analytic form
 - Regions of "bending:" small linear steps
 - Longer straight regions when intersection found
- Notation for any region: p₀, p₁, p₂...
 First region: p₀ = f(0)

Cords Analysis



 We want the stiffness user parameter to be invariant to the guide curve step size Δt . • $s = stiffness * \Delta t$ will accomplish this. stiffness = 0 - No proportional steps - String-like appearance stiffness = 1 Linear approximation of guide curve - Bounds cord shape

Analytic Form



Proportional step:

$$p_i = p_{i-1} + s * (f(i\Delta t) - p_{i-1})$$

Recurrence relation:

$$p_m = (1 - s)^m p_0 + s \sum_{i=1}^m f(i\Delta t)(1 - s)^{m-i}$$

Analytic form as $\Delta t \rightarrow 0$: $g(t) = e^{-at}p_0 + ae^{-at}\int_0^t f(x)e^{ax}dx$

Invariance to Δt





Continuity



 G1 continuity at join points, when stiffness > 0

 Cord has continuity characteristics of guide curve along bending regions

Wide and Thick Cords



- Replace ray intersection with shape intersection
- Apply parameterized orientation



Ryan Larkin







Psychorealism and Ryan







- Fit a cubic polynomial curve with uniform parameterization
- Attach paint effects brush strokes that procedurally generate hair effect
- Animators "grew" the hair as it wrapped around characters

















Conclusions



- Interactive curve primitive with physical appearance properties
- Precise, analytic control for keyframe animation
- Bending and wrapping around 3D scene geometry

Future Work



Generation algorithms incorporating the analytic form

Higher order continuity along cord

Surfaces

Hybrid models incorporating simulation





Special Electronic Theater Presentation Chris Landreth, Director Electronic Theater Hall K Today, 4:00 pm Open to all attendees

Acknowledgments



• Chris Landreth and the Ryan crew

• DGP Lab at the University of Toronto

• NFB Canada, Seneca College

Alias, Pixar

More Information





Technical Development for Ryan

Patrick Coleman and Karan Singh

Nonlinear projection: how Ryan might see the world

One of the major themes in Ryan is that people see the world in unique ways, dependent on their attitudes and life experiences. The character Ryan, having been through drug addiction and alcoholism, offers the chance to explore how different states of mind affect our perception of the space around us. Computer animation software is built upon the rules of linear perspective, built it was necessary to break these rules in subtle ways to express how the characters of Ryan see their world. A nonlinear projection system was developed that allows animators to create multiple points of view and combine them in various ways to achieve a desired affect.



RYAN: Rendering Your Animation Nonlinearly projected. NPAR 2004.

Cords: tying up the animators

In Ryan, the two main characters suffer assaults upon themselves by metaphorical extensions of their own minds. Represented as colorful hairs growing from the character's heads, the shots called for animator control of string-like primitives. Typically, hair and other passive rope-like objects are animated with physical simulations, but this approach is difficult to control when the animated objects are a primary source of motion. Cords address this problem by allowing animators to keyframe animate curves that are restricted to behave like string or wire, with intuitive control properties such as stiffness and elasticity, in addition, cords are procedurally generated such that they appear to wrap around scene geometry. In *Ryan*, cords were used in conjunction with procedural brush strokes generated with maya's paint effects system to animate the hair as it ties up the main characters.



Cords: Keyframe Control of Curves with Physical Properties, SIGGRAPH 2004 Sketches

www.dgp.toronto.edu/~patrick/ryanTech